

DOCKETED	
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Floating Offshore Wind Research and Development Portfolio Showcase Webinar

November 5, 2024



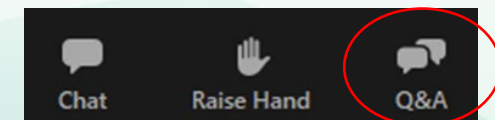
Agenda

Time	Item
9:30 am	<ul style="list-style-type: none">• Welcome and Introduction, Katherine Greenwald-CEC• EPIC Offshore Wind R&D Overview, Daphne Molin-CEC
9:45 am	<p>Project Presentations</p> <ol style="list-style-type: none">1. Grace Chang, Integral Consulting Inc.2. Yuxin Wu, Lawrence Berkeley National Laboratory3. Jason Cotrell, Sperra4. Spencer Hallowell, University of Maine5. Greyson Adams, Schatz Energy Center and Erica Escajeda, H.T. Harvey & Associates6. Zachary Miller, Triton Anchor7. Matthew Hall, National Renewable Energy Laboratory
11:05 am	Break
11:15 am	Panelist Discussion Q&A
12:00 pm	Adjourn



Housekeeping

- This webinar is being recorded will be posted along with the presentation slide decks to the CEC event page website : <https://www.energy.ca.gov/event/webinar/2024-11/floating-offshore-wind-research-and-development-portfolio-showcase-webinar>
- Attendees will be muted during the presentation. Please chat your question using the Q&A window. We will leave time between speakers for any technical/clarifying questions that come in, discussion-oriented questions will be held until the end.





EPIC R&D Objectives

- Electric Program Investment Charge (EPIC) funds technology development to advance market adoption of clean energy solutions:
 - Improve technology performance, reliability, and safety
 - Reduce technology costs
 - Address environmental and equity issues
- EPIC floating offshore wind objectives:
 - Lower levelized cost
 - Reduce technical and financial risk
 - Inform environmental mitigation, deployment planning, permitting



Research Prioritization

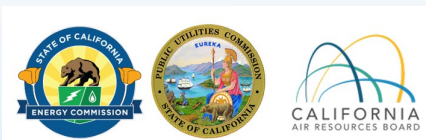


- Publications
- Reports
- Conferences
- Webinars



- Industry
- State agency partners
- Federal Partners
- Communities, fishers, Tribal members

- Clean energy goals
- CA Strategic Plan
- Development timeline





EPIC Offshore Wind R&D Investments

~\$30M AWARDED

- REMOTE ENVIRONMENTAL MONITORING
- ANCHOR AND MOORING LINE DESIGNS
- INNOVATIVE MANUFACTURABILITY OF COMPONENTS
- ENVIRONMENTAL EVALUATIONS

[Search | CEC \(energizeinnovation.fund\)](https://energizeinnovation.fund)

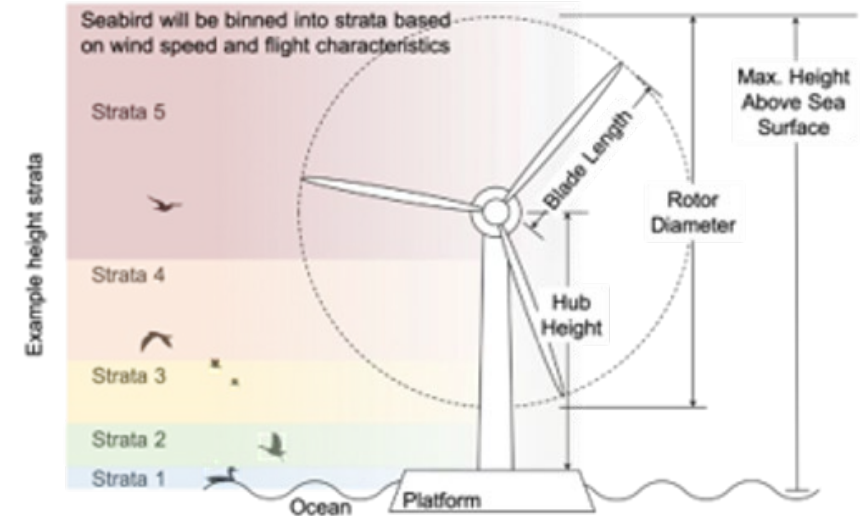


Photo credit: Sperra



Investments in Progress

[GFO-22-401](#) - Environmental Monitoring Technologies Solicitation

Award Amount: \$8,900,868

Purpose: Advance technologies to support detecting marine life or ecosystem processes to assess risks and impacts to California's Wind Energy Areas.





Investments in Progress

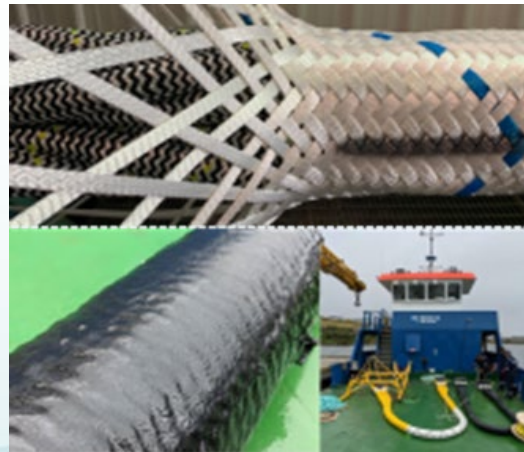
GFO-22-402 – Advancing Designs for Floating Offshore Wind Mooring Lines and Anchors (Award Amount: \$11,869,231)

- **Purpose:** Design and test mooring line materials, anchor designs, and/or shared mooring lines and anchors for California conditions

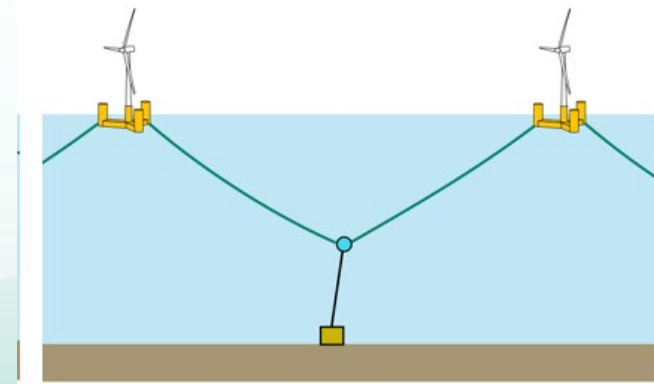
Torpedo Anchor



Mooring Line



Shared Mooring Configurations





FOSW R&D under Consideration

1. Optimizing Designs for Cost and Operational Efficiency
2. Cost-Effective Installation and Operations & Maintenance Developments
3. Grid Integration Innovations and Port Infrastructure Readiness Strategies
 - a. Request for Information: Deep water HVDC substations
4. Environmental Impact Assessment and Minimization
 - a. Request for Information: Entangled Debris Monitoring

~\$17M

EPIC FUNDING FOR OFFSHORE WIND
AND SOLAR THROUGH 2025



Thank You!

Please let us know if you have additional questions:

Daphne.Molin@energy.ca.gov (Supervisor, R&D Division)

Integrated, Real-Time, Multi-Scale System for Monitoring Seabird Interactions with Floating Offshore Wind Technologies

Grace Chang

**CEC Floating Offshore Wind Research
and Development Portfolio Showcase**

November 5, 2024



Problem Statement

California's wind energy areas are rich with seabirds under protection by the Migratory Bird Treaty Act and the Endangered Species Act.



Black-footed albatross



Marbled murrelet

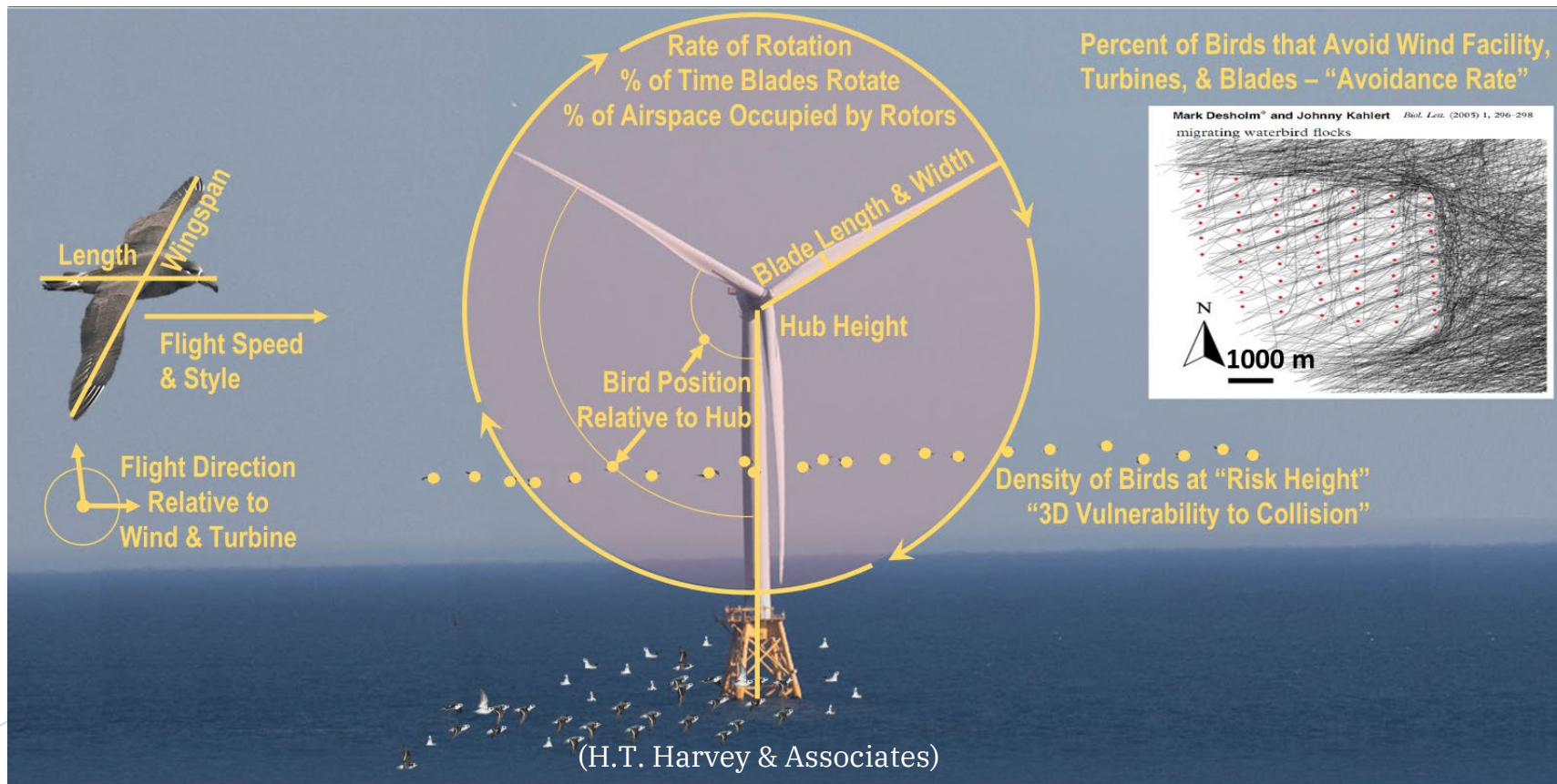


Ashy storm petrel

(Photos from eBird)

Problem Statement

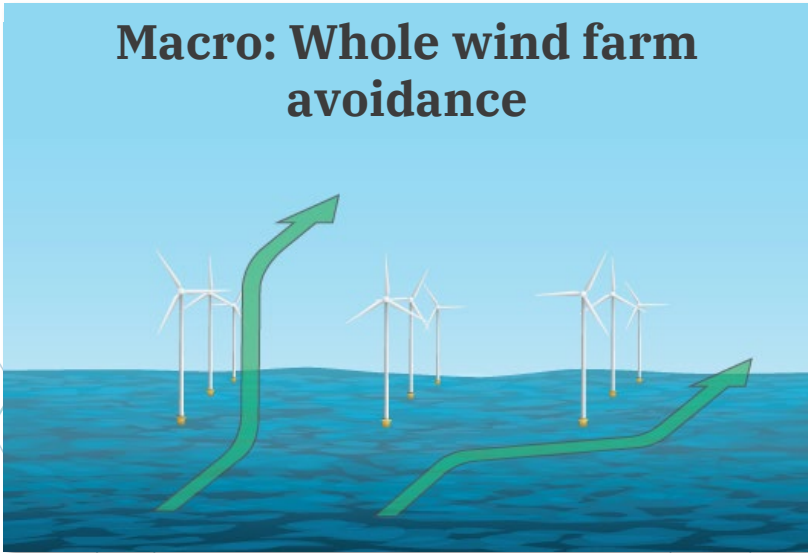
Offshore wind energy projects will likely be required to generate seabird and bat collision risk models to estimate species-specific impacts.



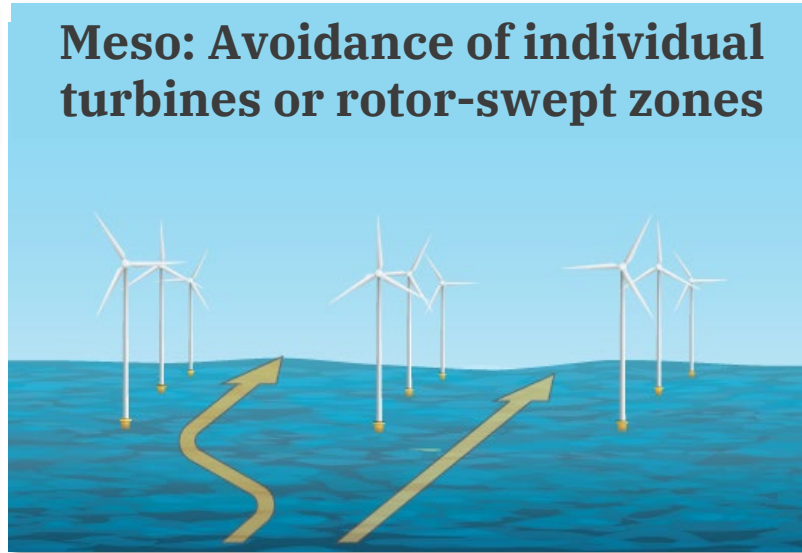
Problem Statement

Collision risk models are most sensitive to avoidance rate, which requires knowledge of seabird and bat interactions over multiple scales.

Macro: Whole wind farm avoidance



Meso: Avoidance of individual turbines or rotor-swept zones

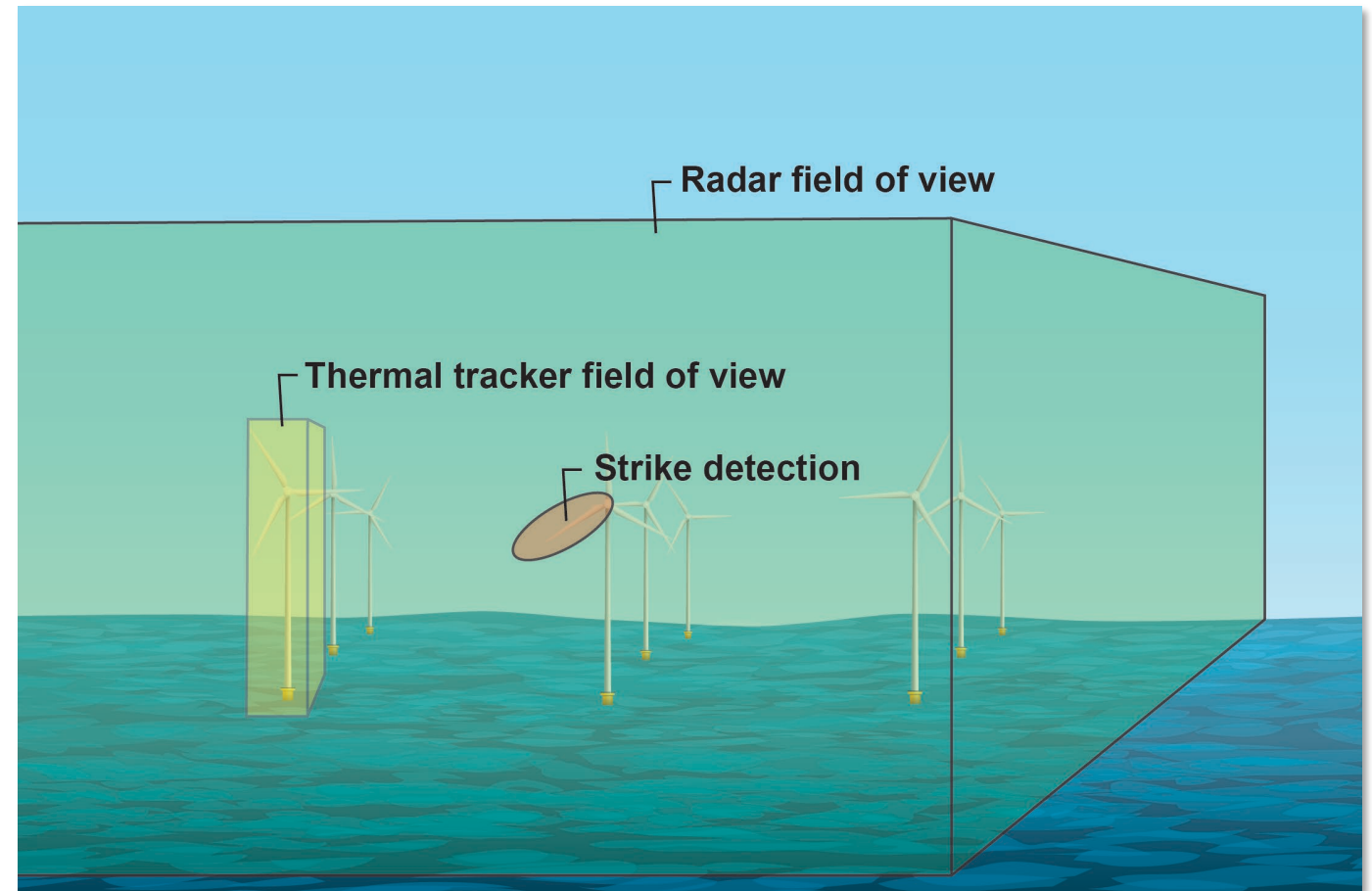


Micro: Last-second avoidance to avoid collision



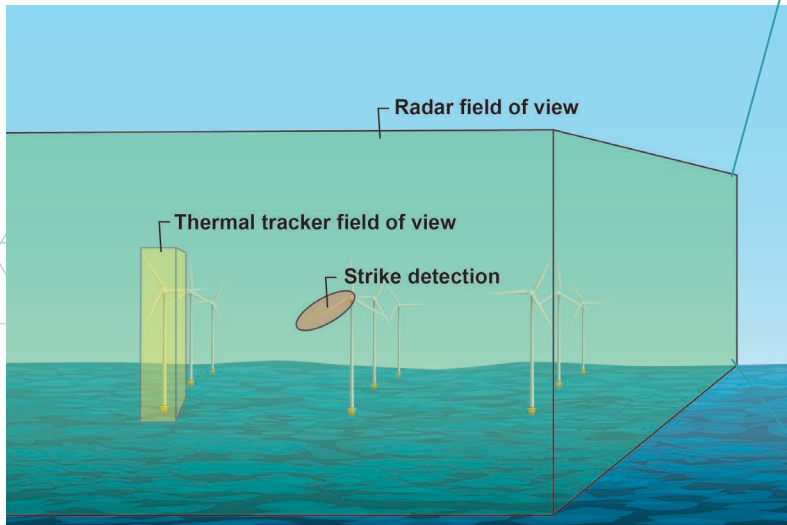
Project Goal

Integrate, test, and validate multiple real-time sensing technologies to quantify seabird and bat avoidance and collision risk across macro-, meso-, and micro-scales to improve wildlife monitoring and seabird and bat collision risk model-based forecasting.



Macro-scale

Abundance, relative size, and movement patterns in the far-field vicinity of a wind farm area



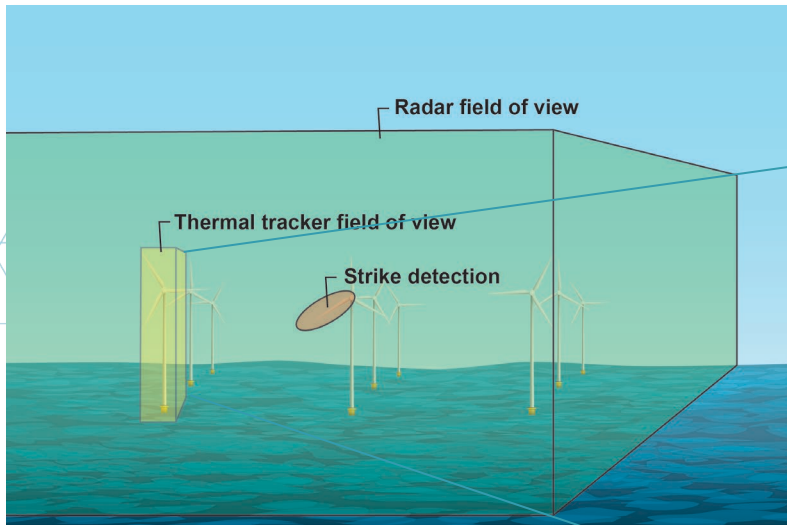
(DeTect Inc.)

3D Radars (x2)

- Marine S-band, pulsed Doppler
- 360° at 45° elevation over 2-3 km range
- 90° at 12.5° elevation over 6-8 km range

Meso-scale

3D flight trajectory with feature extraction for identification based on shape, size, and flight behavior

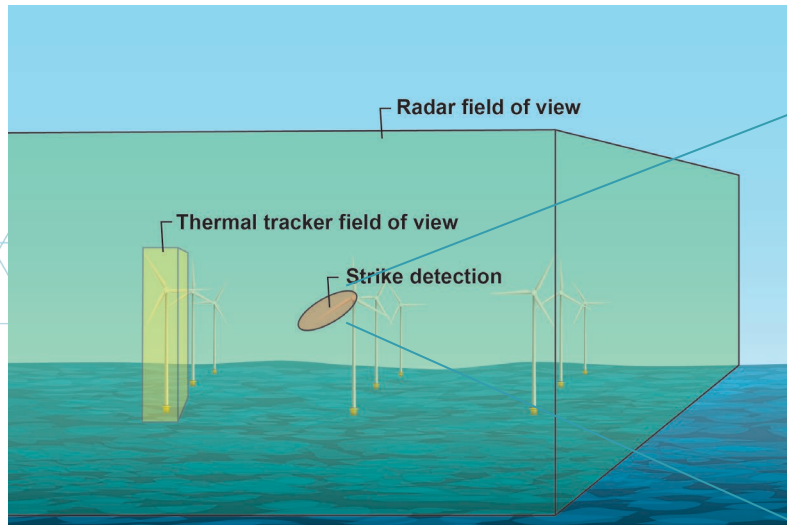
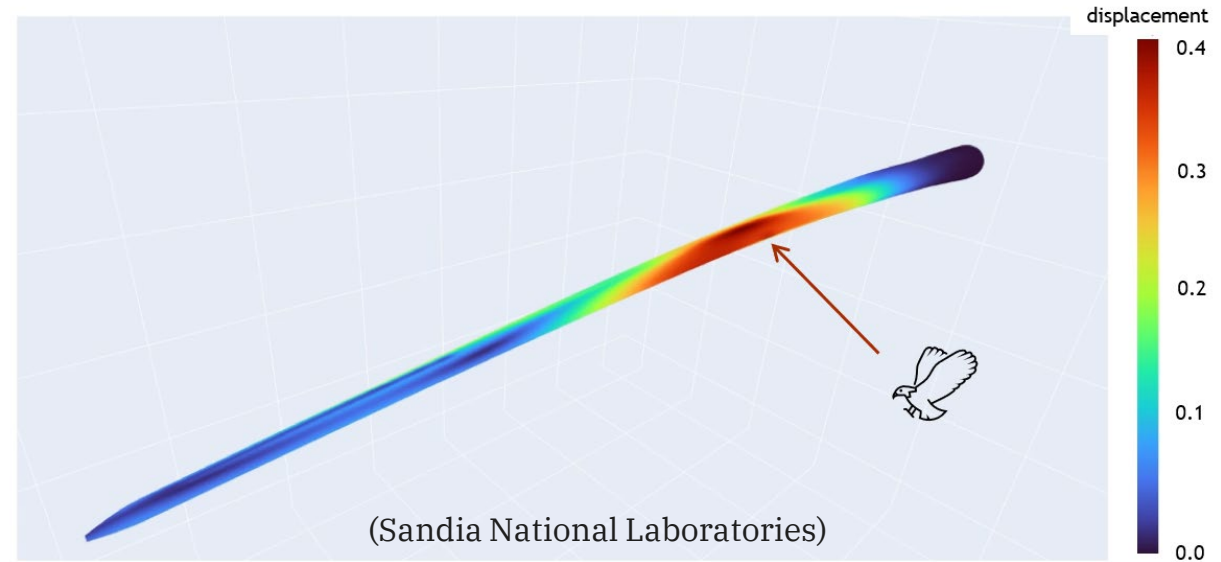


(Sightir, Inc.)



Micro-scale

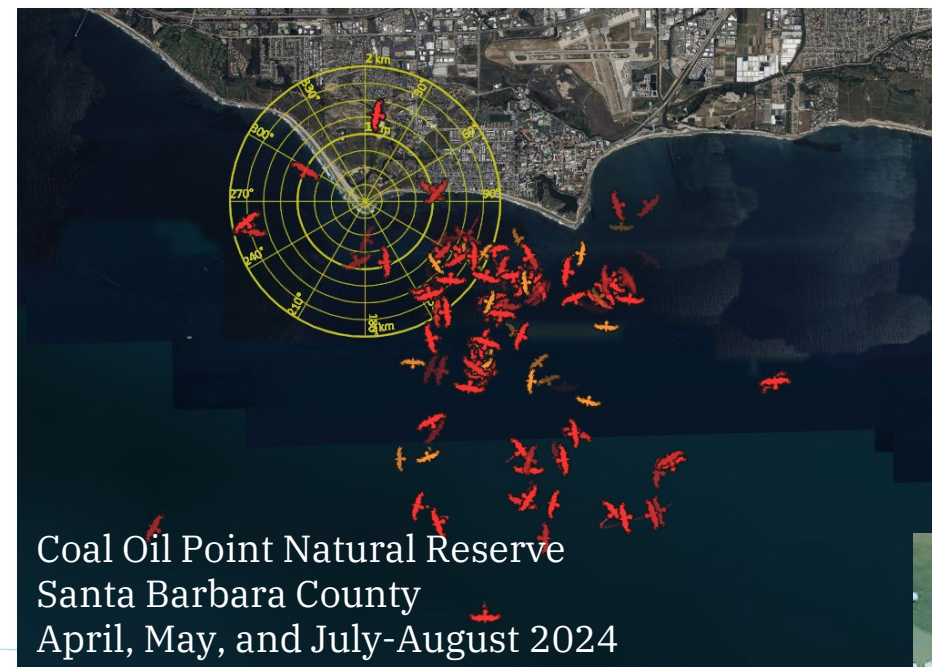
Detect and characterize blade strike events



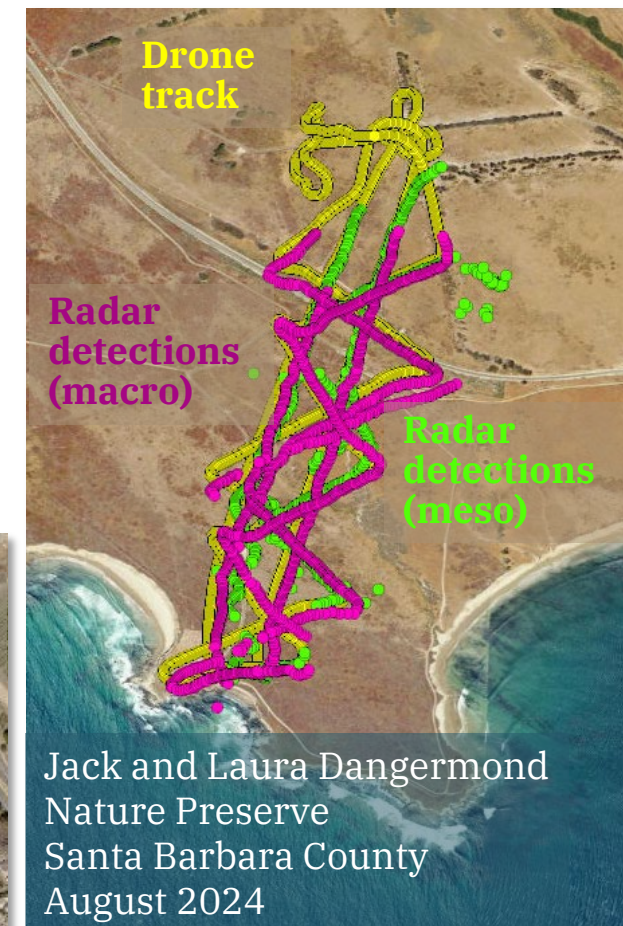
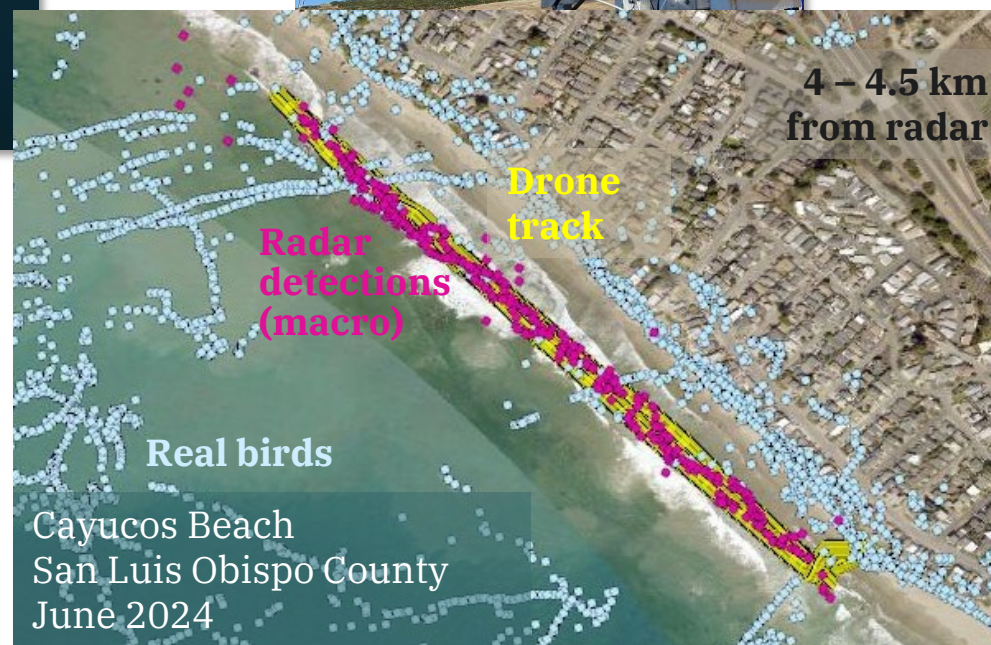
Real-time vibration monitoring informed by model simulations

- IEA-15 MW and V27-220 kW
- Implicit, linear dynamic response to impact

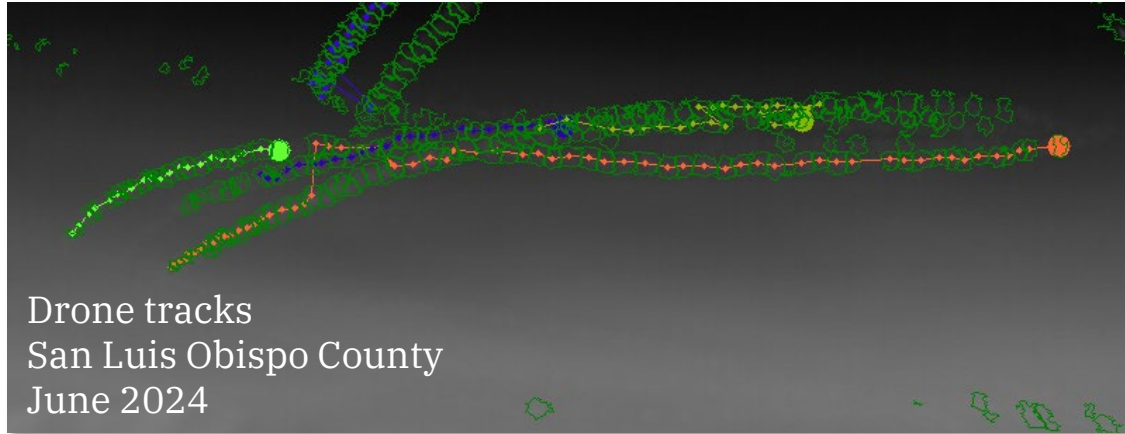
Field Testing – Macro- and Meso-Scale



Strauss Wind
Energy
Project
Santa
Barbara
County
August 2024



Field Testing – Macro- and Meso-Scale



Pigeon
San Luis Obispo County
June 2024



Micro-scale Simulations

LS-DYNA keyword deck by LS-PrePost

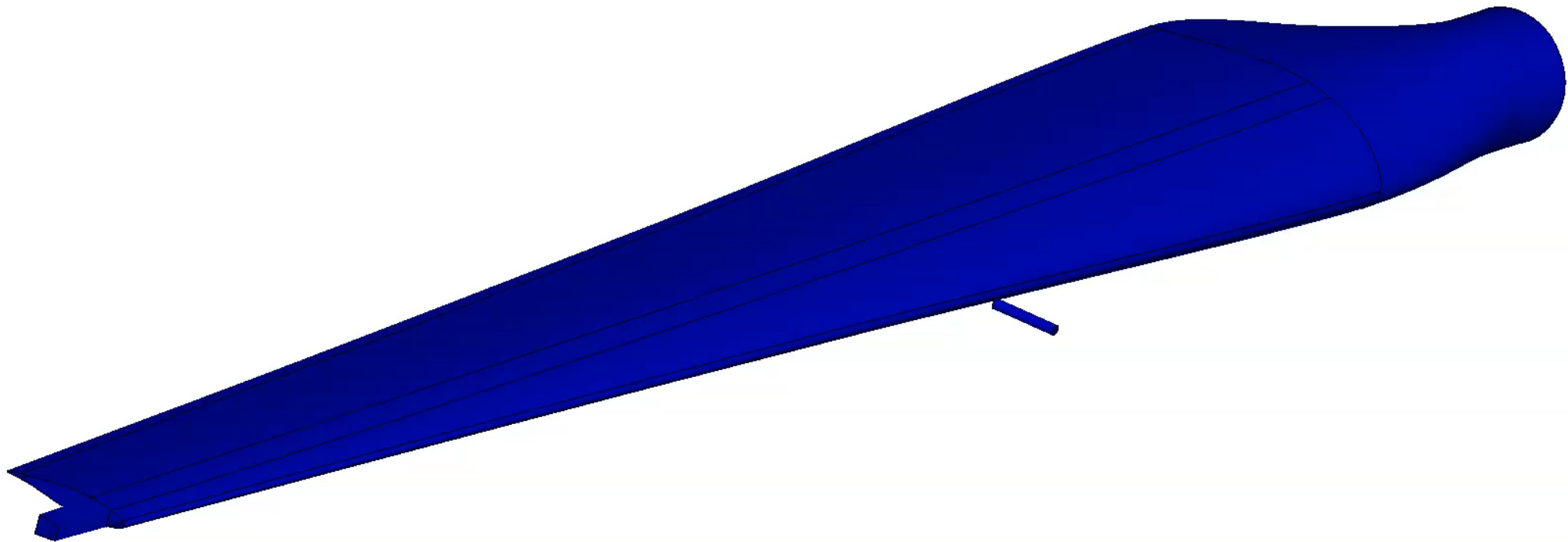
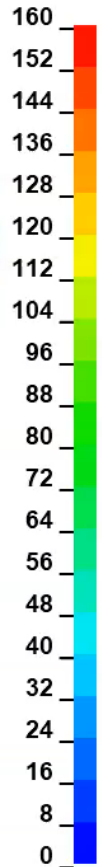
Time = 0

Contours of Resultant Acceleration

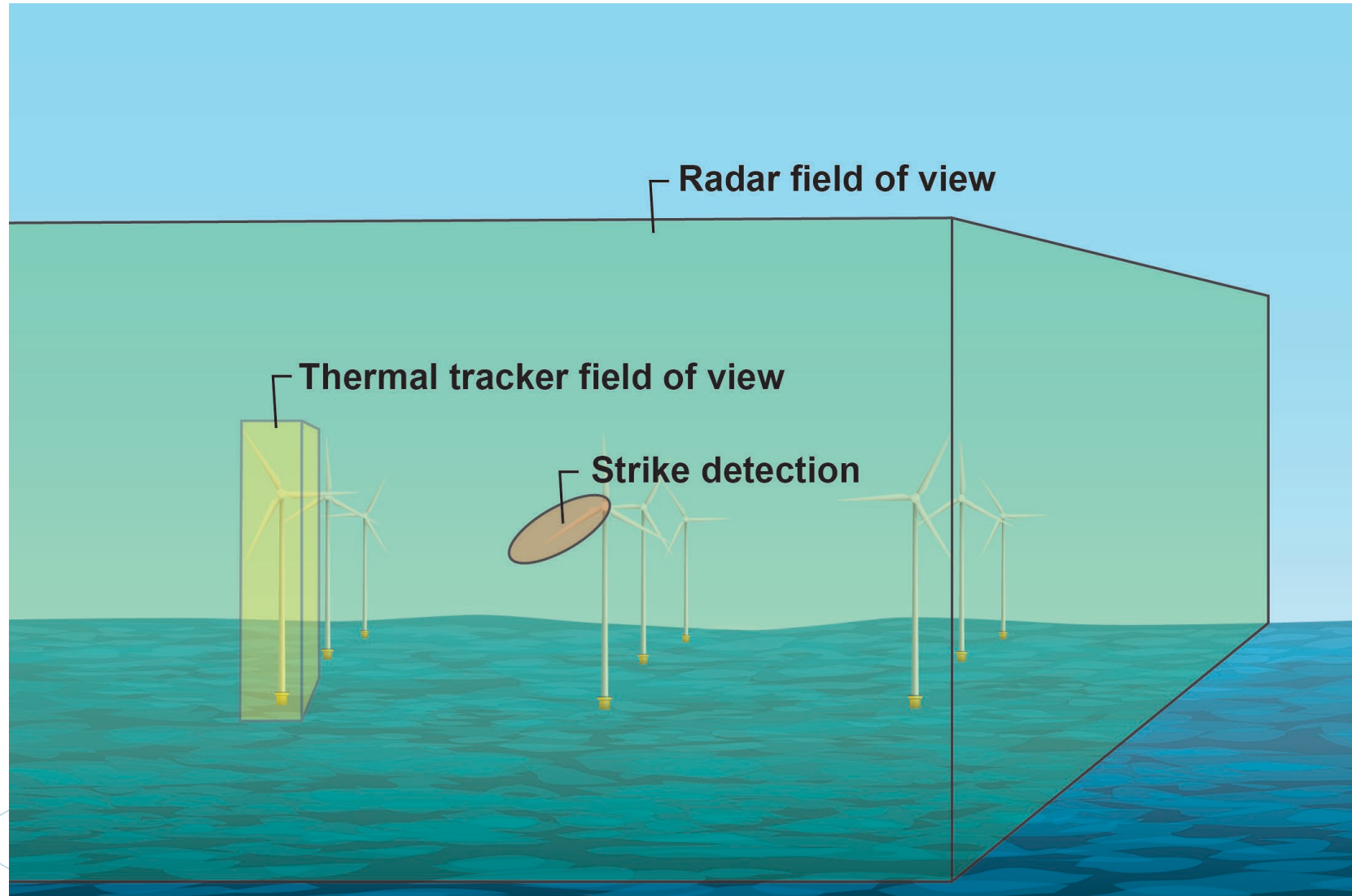
min=0, at node# 27413

max=0, at node# 27413

Resultant Acceleration



Summary



Team

Integral Consulting Inc.

Grace Chang, Ph.D.
Michael Macrander, Ph.D.
Daniel Doolittle

PRIME

Sightir Inc.

Marcus Chevitarese

Systems Engineering

H. T. Harvey & Associates

Sharon Kramer, Ph.D.
Stephanie Schneider

Bird and Bat Expertise

Sandia National Laboratories

Lawrence Cheung, Ph.D.

Turbine Blade

DeTect Inc.

Jesse Lewis

Radar

Pacific Northwest National Laboratory

*Shari Matzner, Ph.D.**

Thermal Tracker

GE Vernova

Charles Seeley, Ph.D.

Turbine Blade

Velvetwire

Eric Bodnar

Blade-Mounted Sensors

*Shari has just retired. The PNNL team is now led by Jenny Wehof.



integral

THANK YOU!

Grace Chang

gchang@integral-corp.com



**EARTH &
ENVIRONMENTAL
SCIENCES**



CEC Offshore Wind Seminar

INTEGRATED MONITORING OF FLOATING OFFSHORE WIND TECHNOLOGY & ENVIRONMENTAL IMPACTS ON THE PACIFIC COAST

Yuxin Wu (YWU3@lbl.gov)

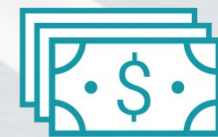
Staff Scientist, Geophysics Department Head

Earth & Environmental Sciences Area

Lawrence Berkeley National Laboratory

Berkeley, CA

11/05/2024



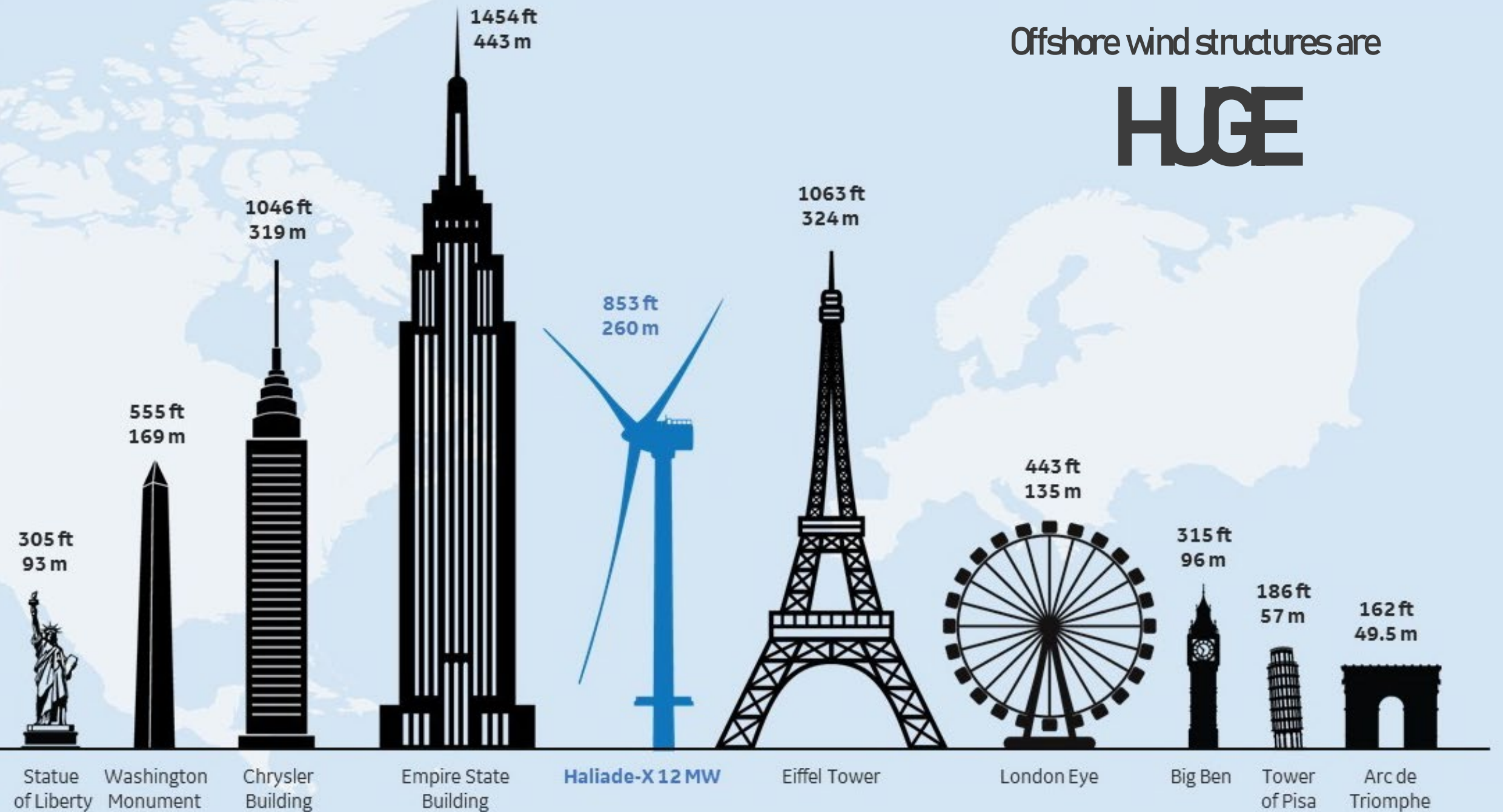
>70% Reduction



2035

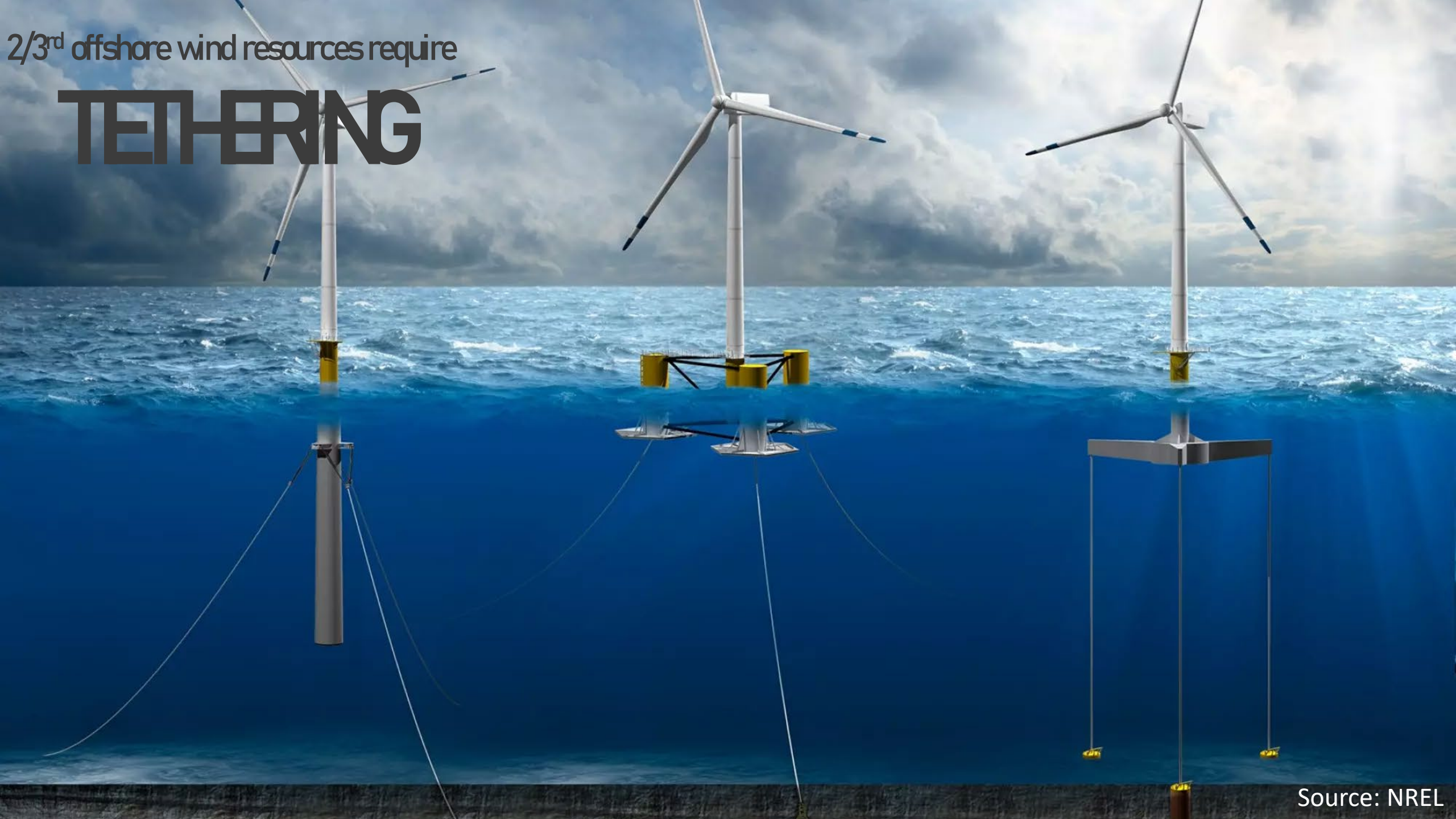
Offshore wind structures are

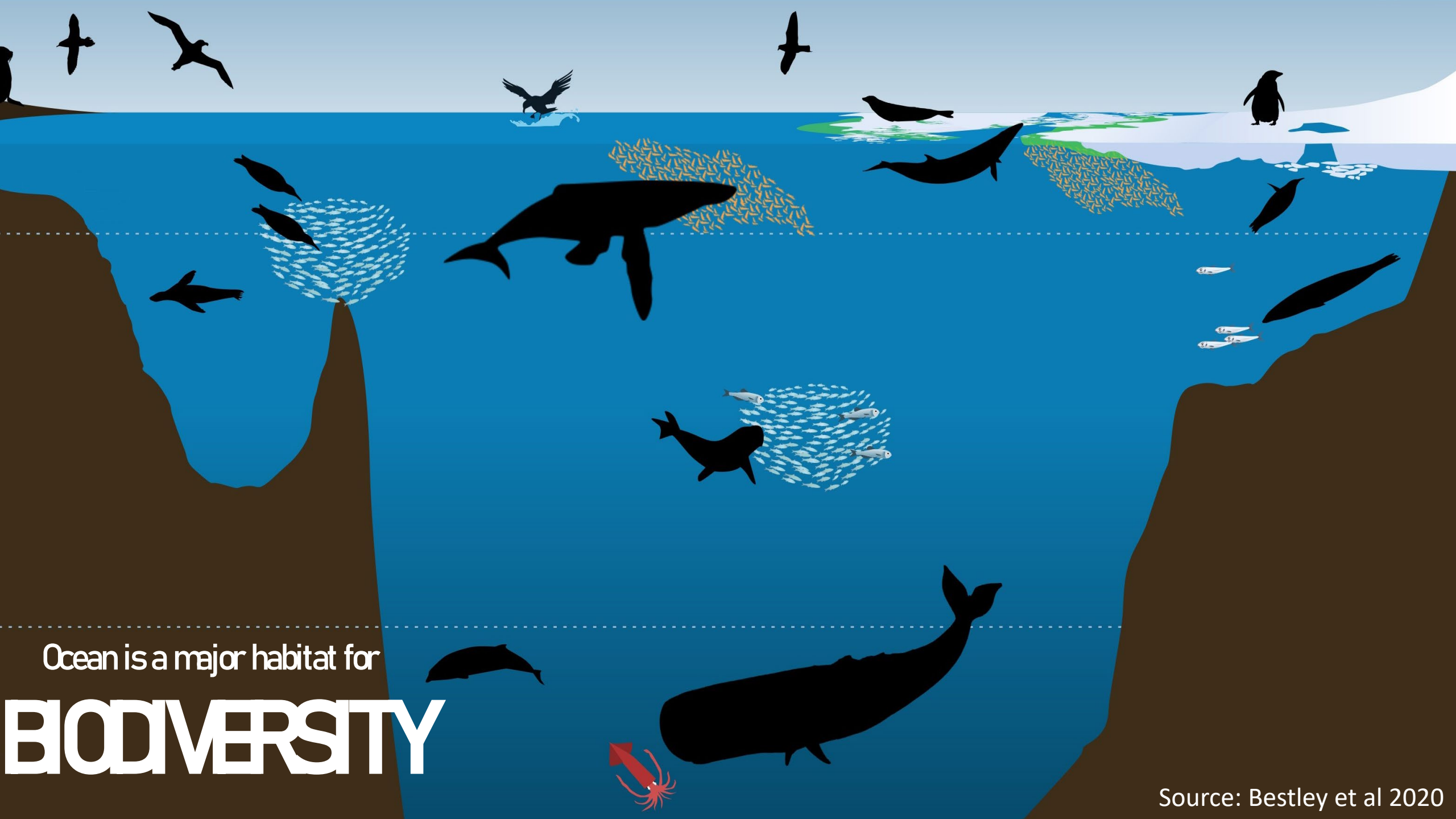
HUGE



2/3rd offshore wind resources require

TETHERING



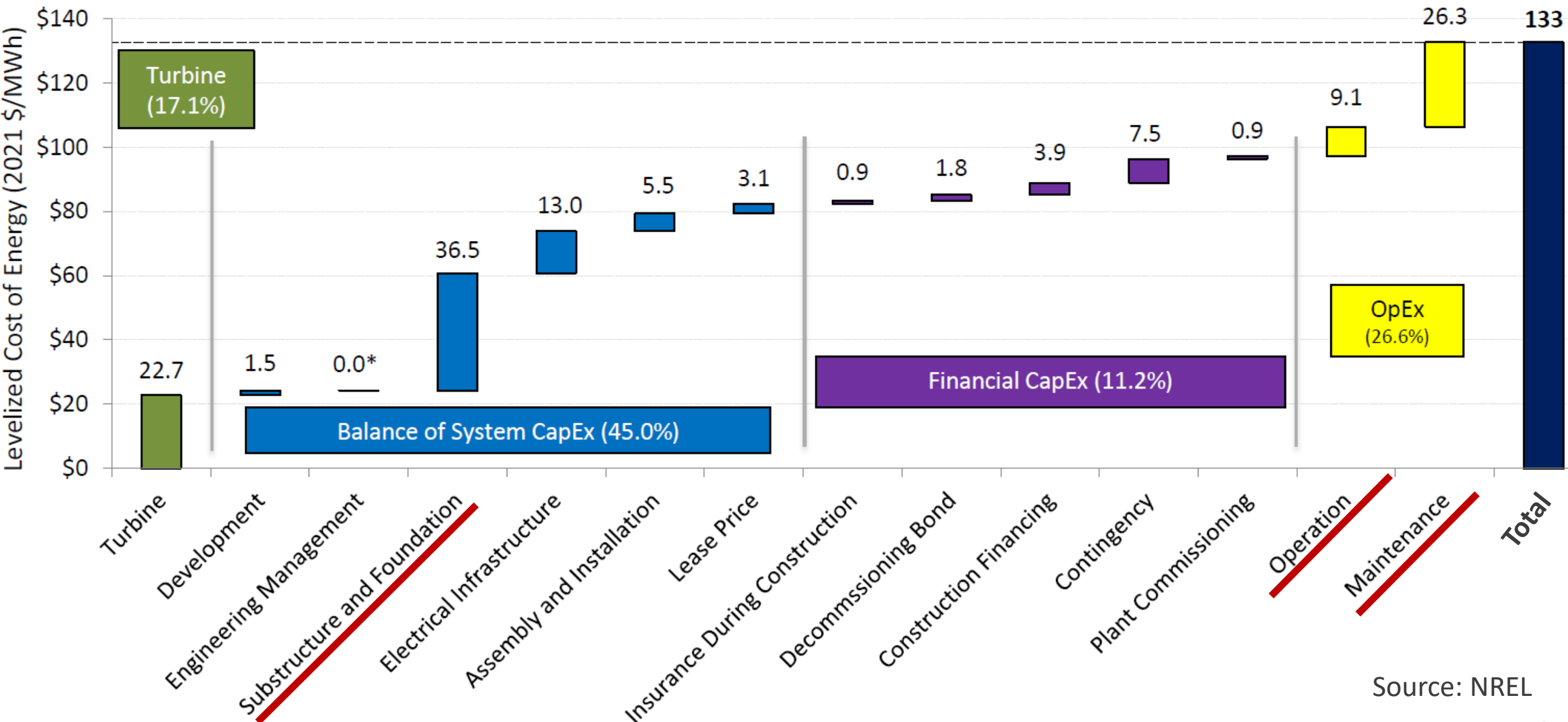


Ocean is a major habitat for

BIODIVERSITY

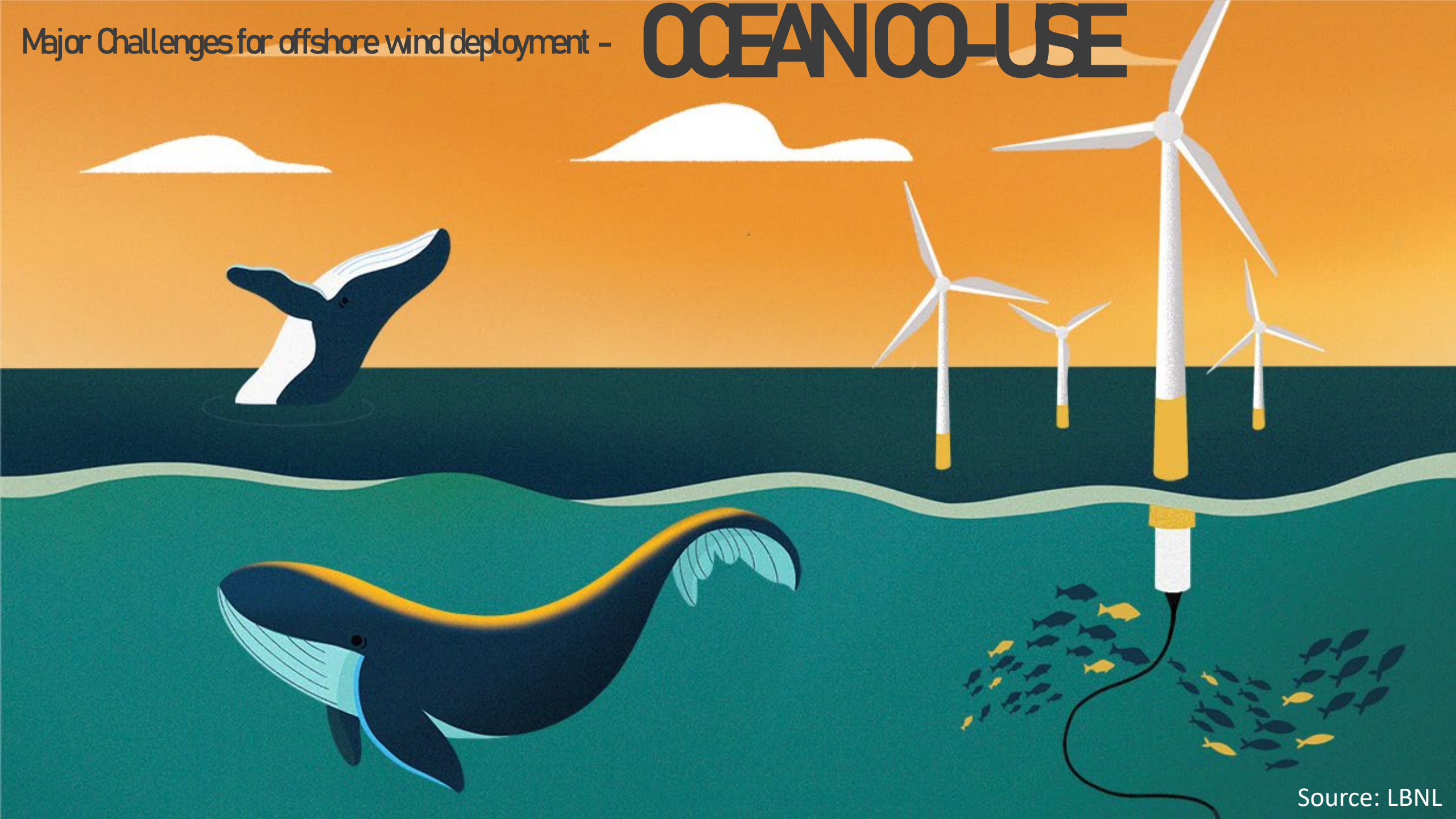
Source: Bestley et al 2020

Major Challenges for offshore wind deployment -

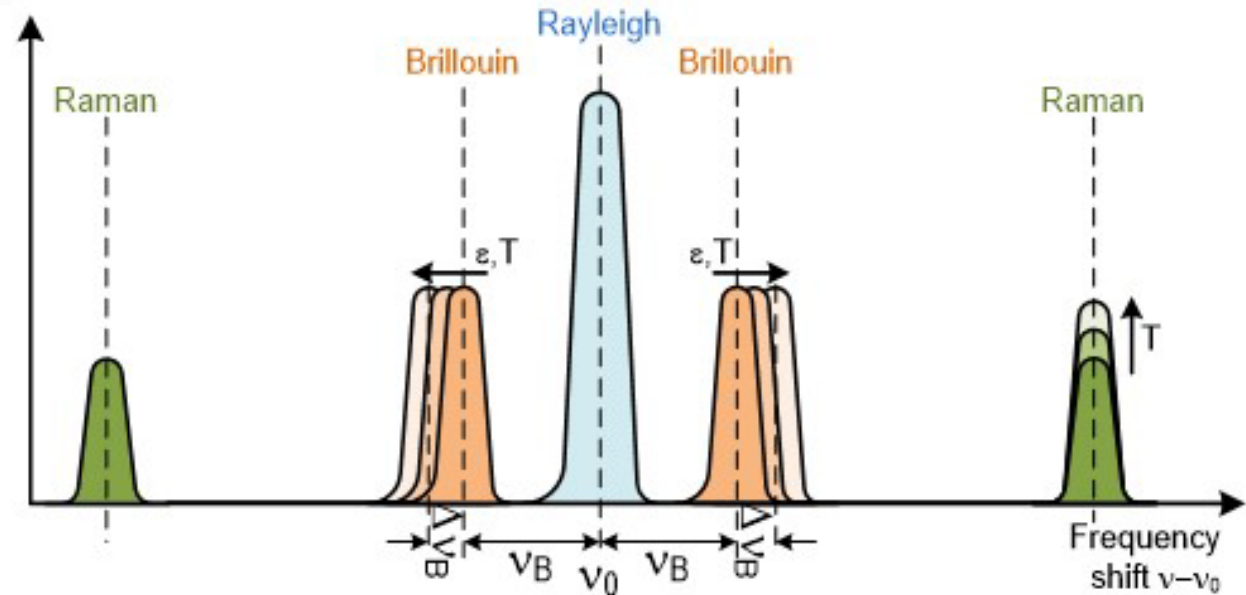
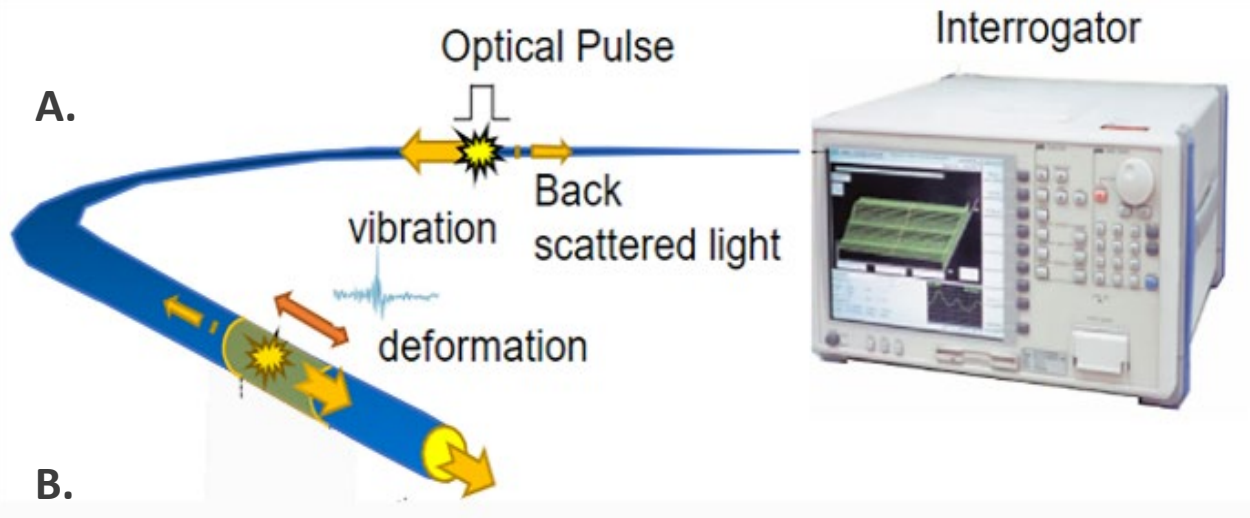
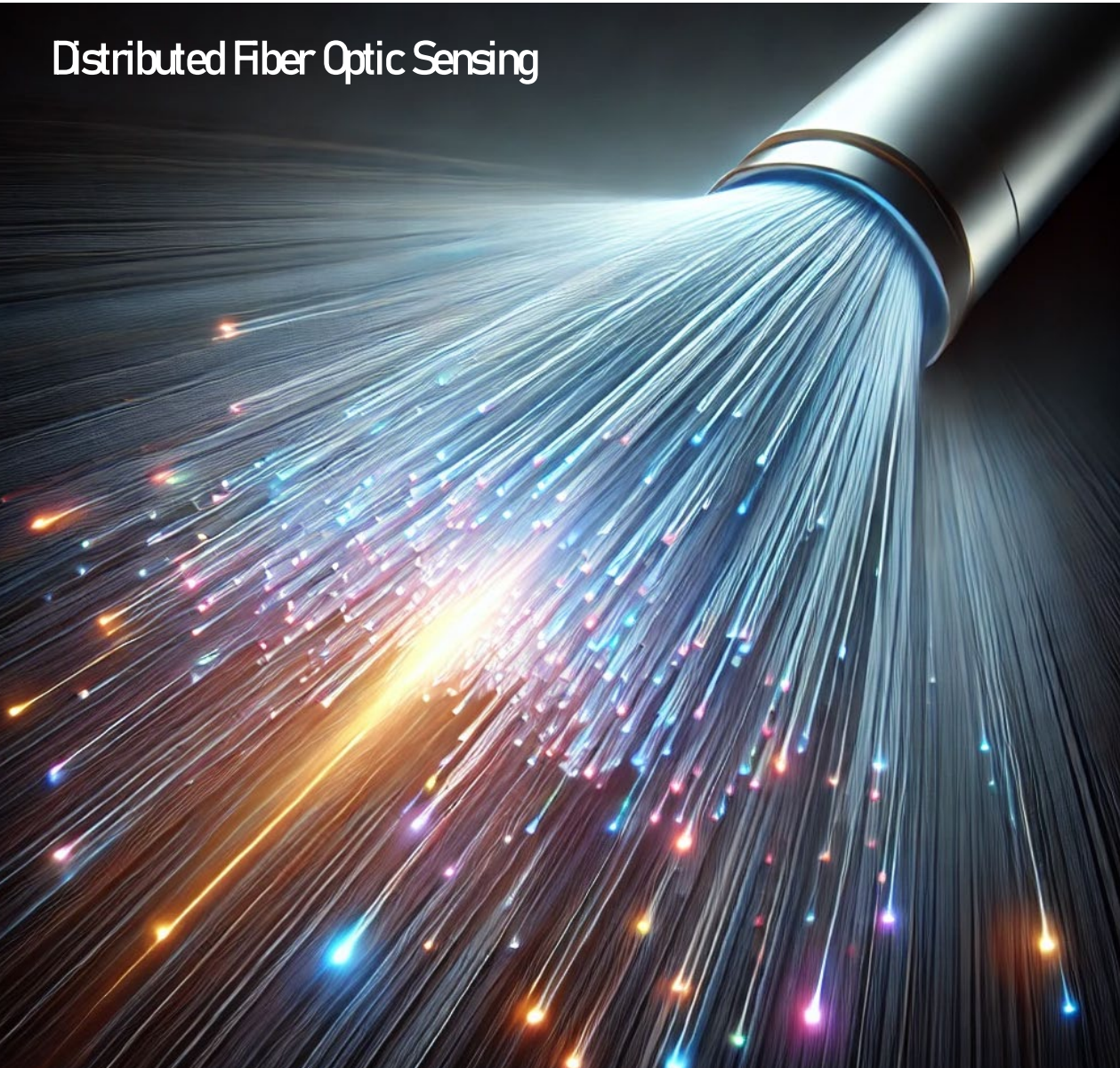


Major Challenges for offshore wind deployment -

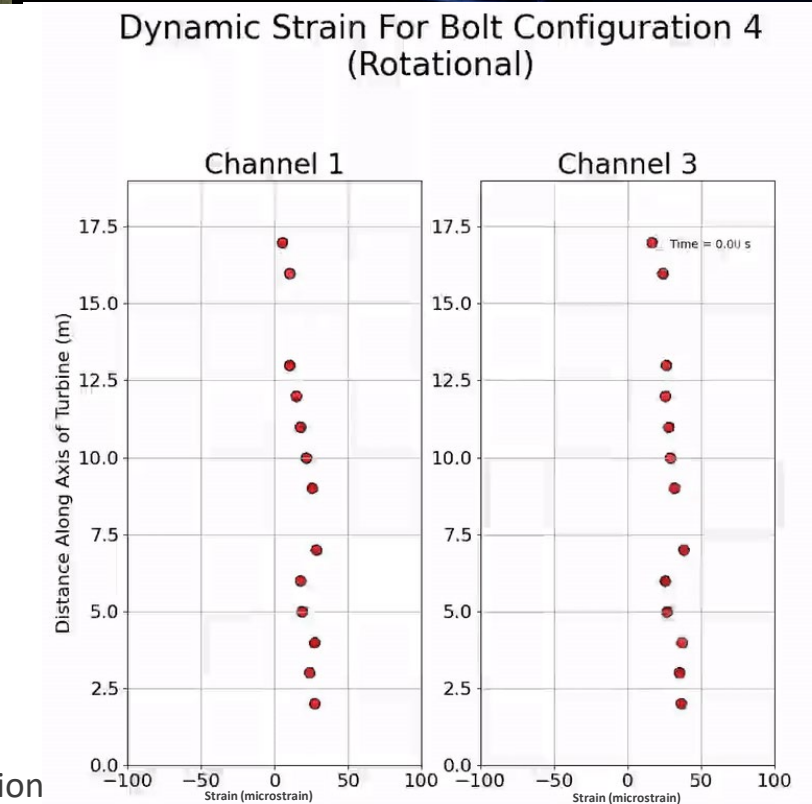
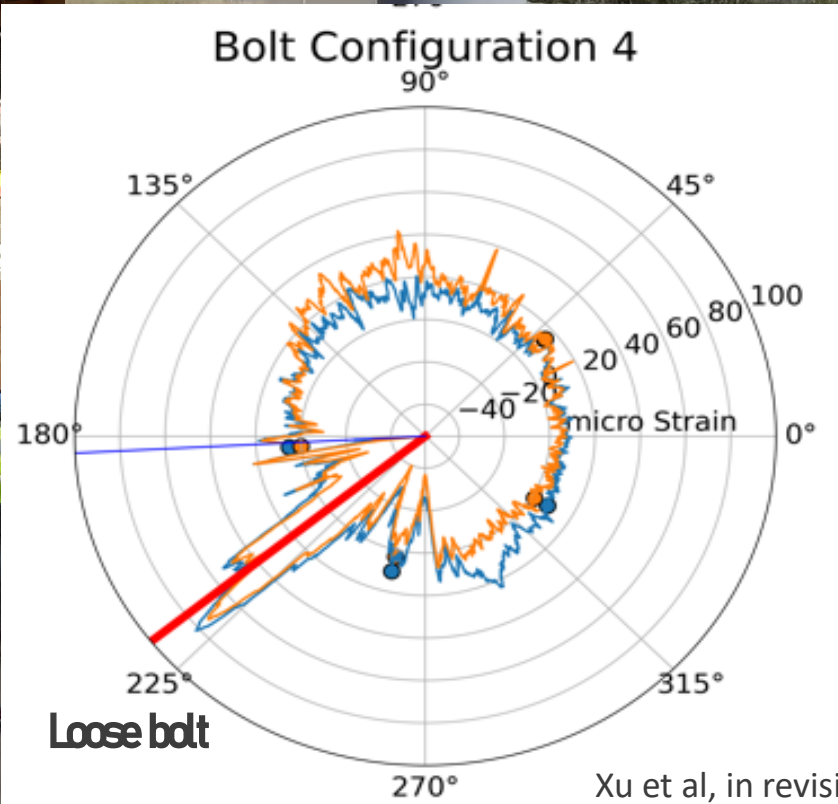
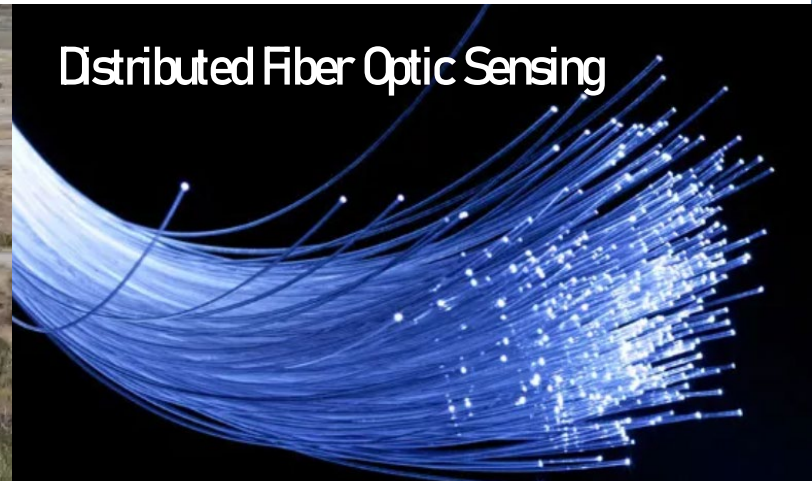
OCEAN USE



Distributed Fiber Optic Sensing

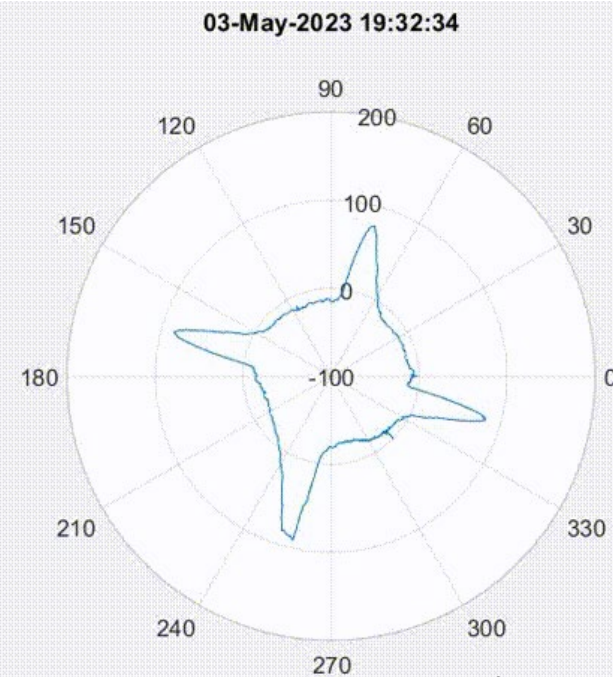
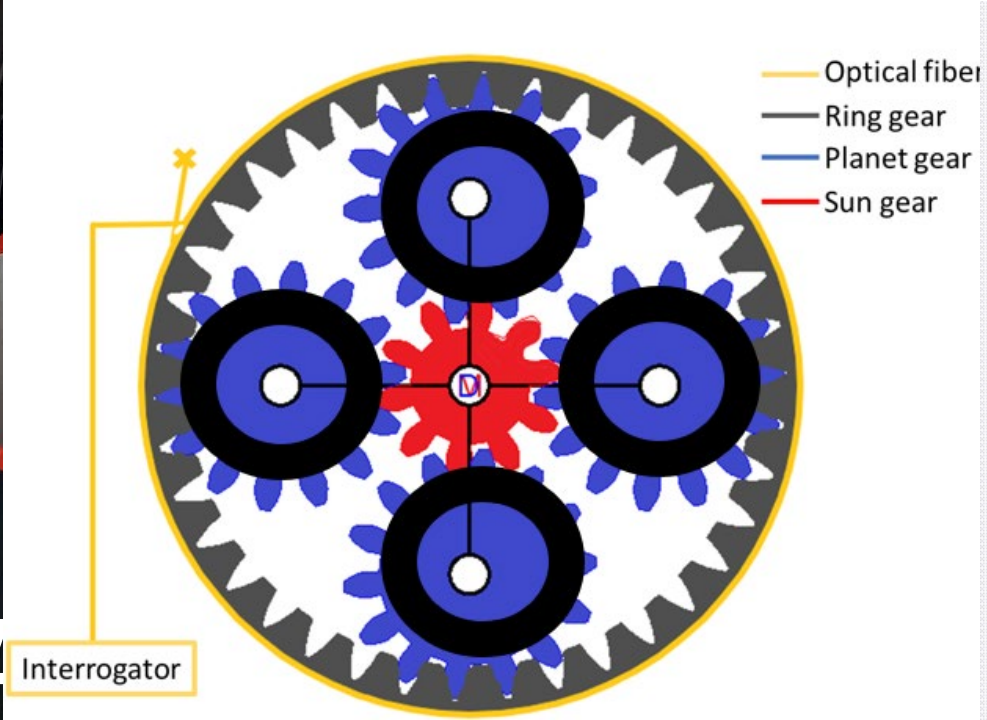
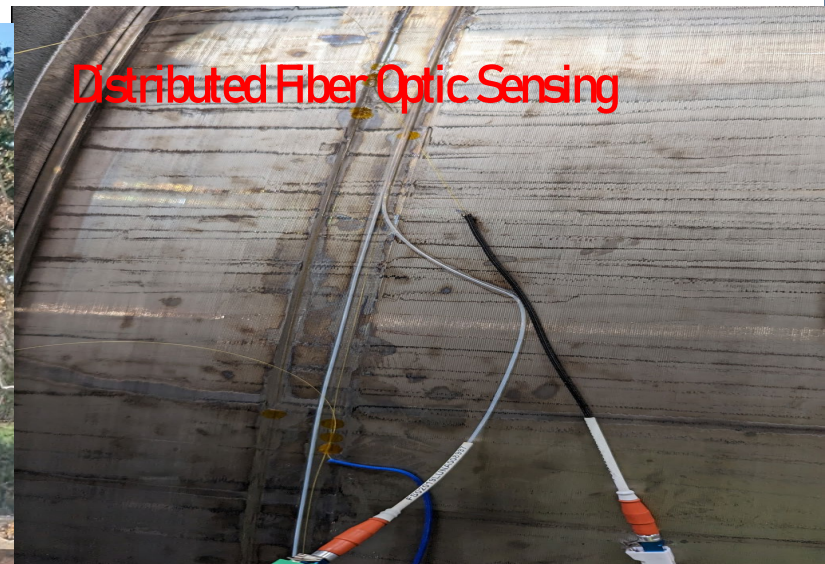
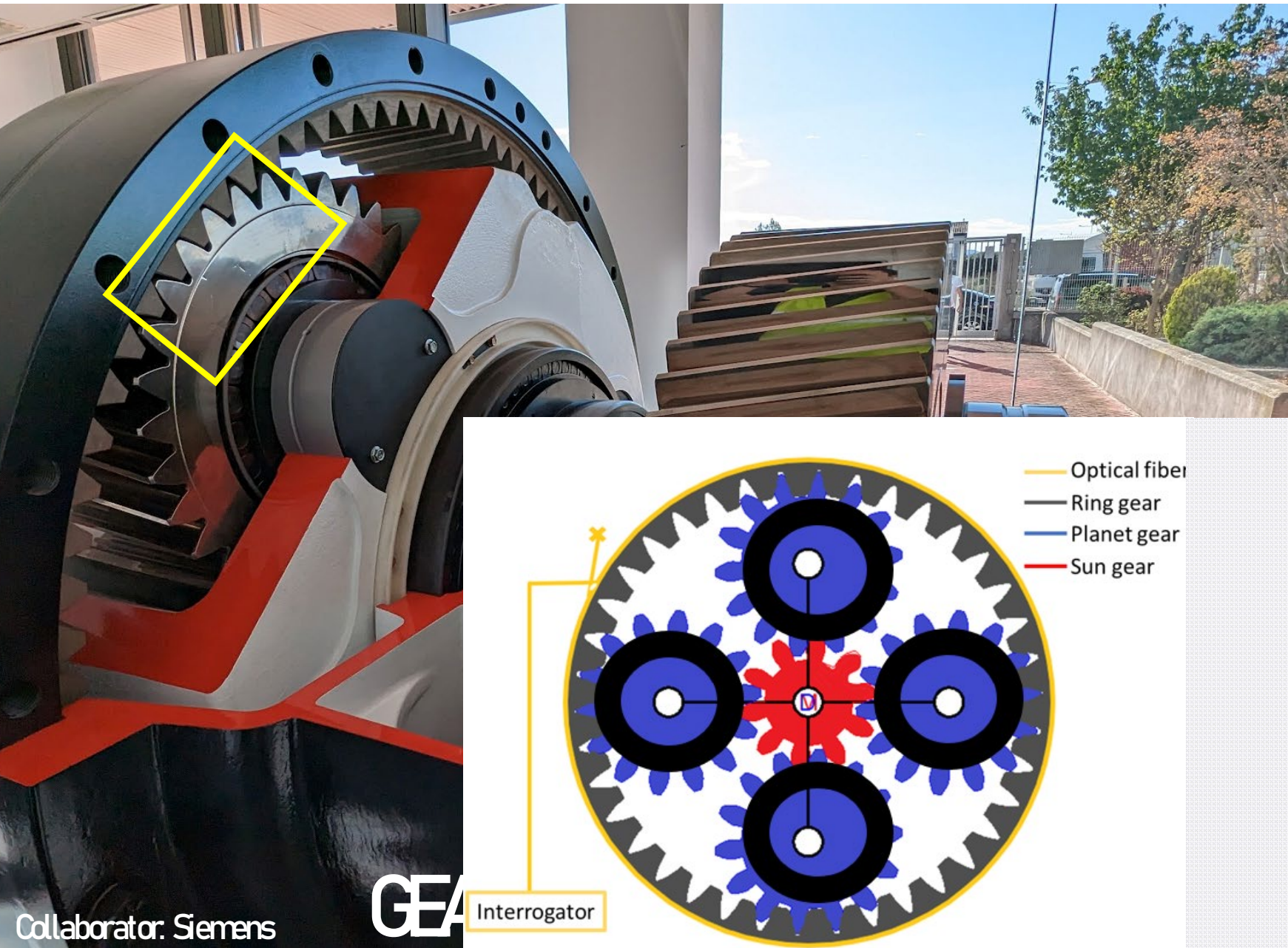


R&D Activities at LBNL - NOVEL SENSING for COST REDUCTION

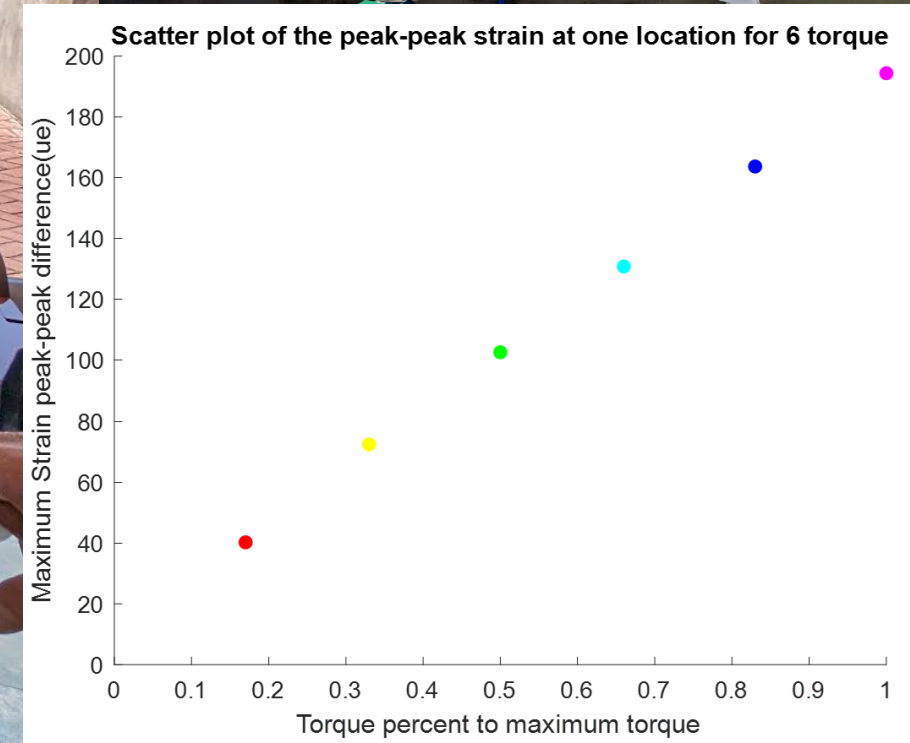


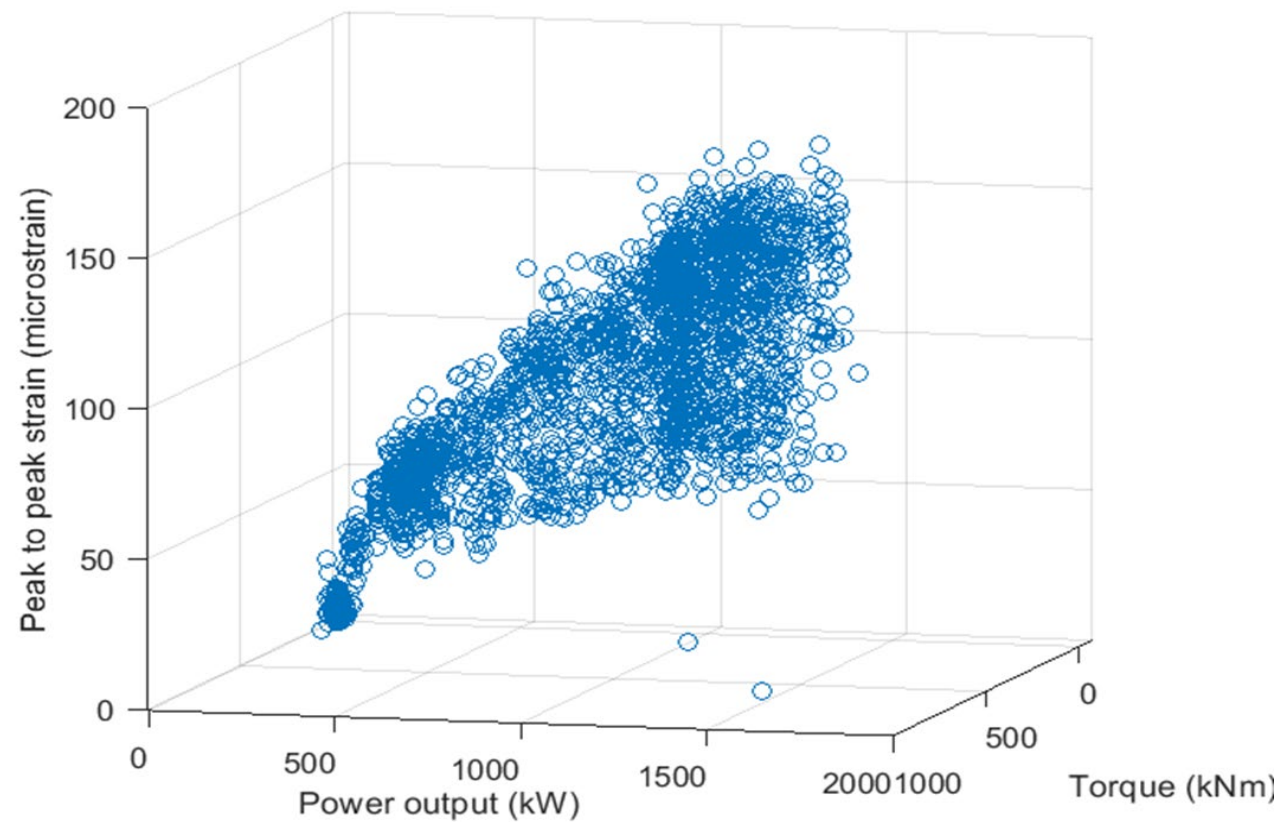
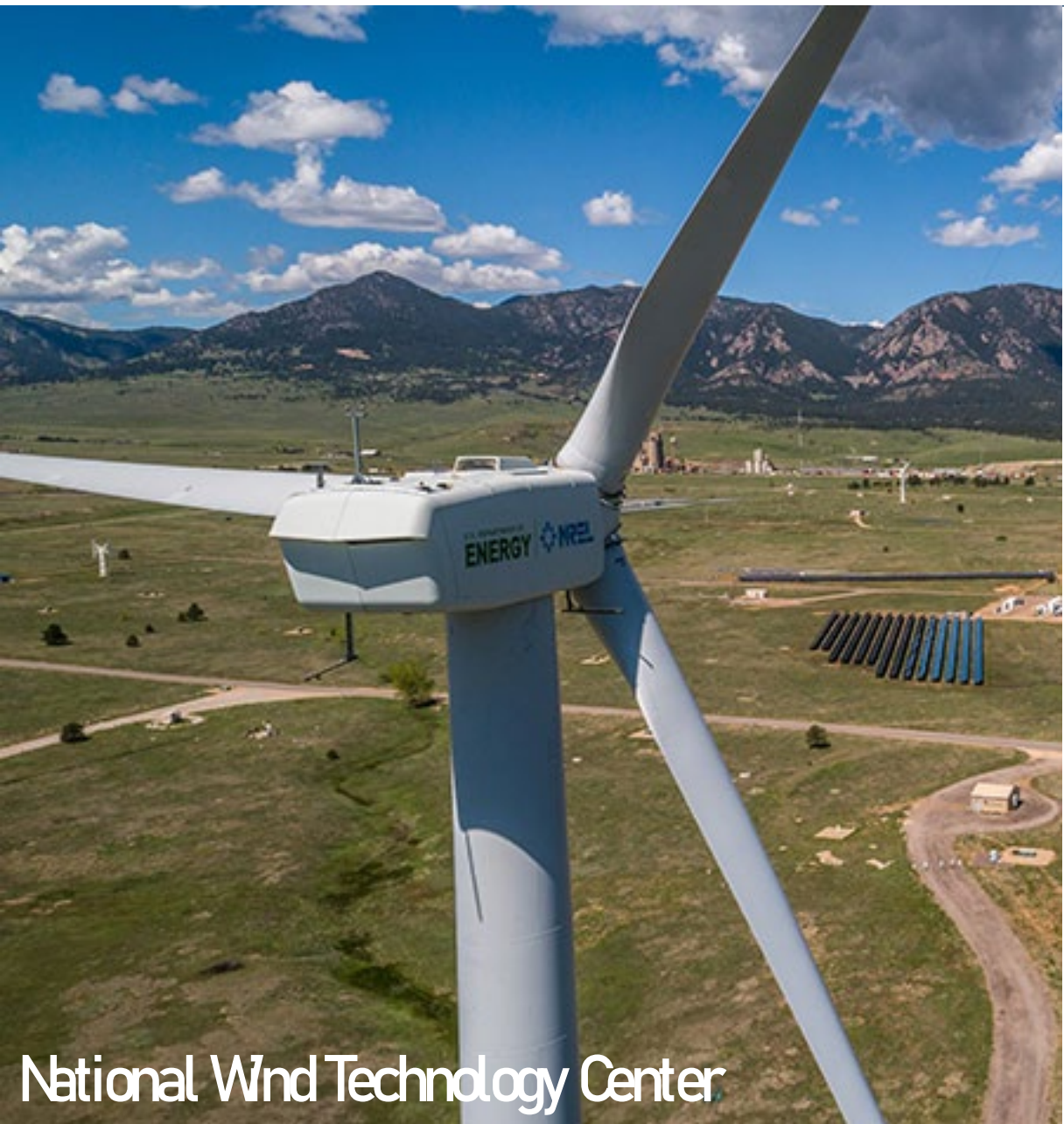
Xu et al, in revision

NOVEL SENSING for COST REDUCTION

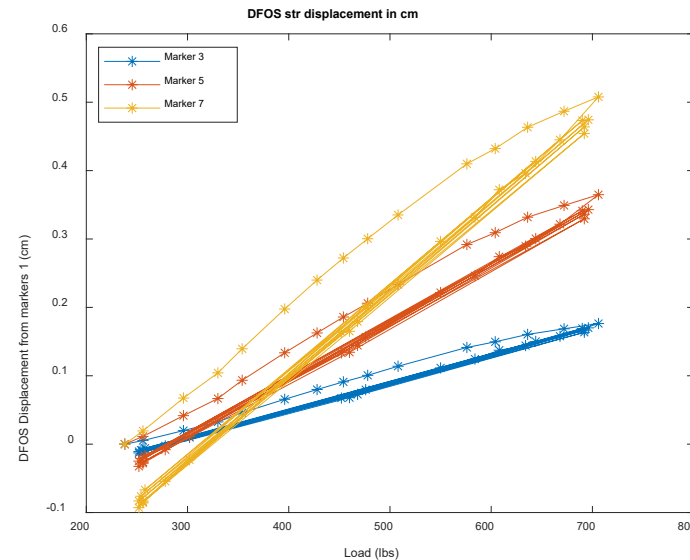
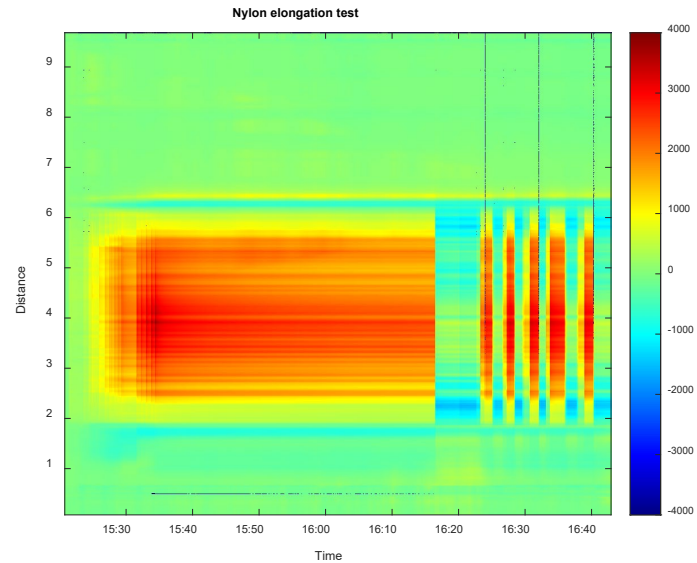


NOVEL SENSING for COST REDUCTION





- Field demonstration on an operating test turbine (1.5 MW) at NWTCC@Flatiron, CO
- Very similar behaviors compared to bench tests



- Load distribution
- Load quantification
- Nuanced rope behaviors
- Shape sensing
- Environmental Impact monitoring

R&D Activities at LBNL -

NOVEL SENSING for ENV. SUSTAINABILITY



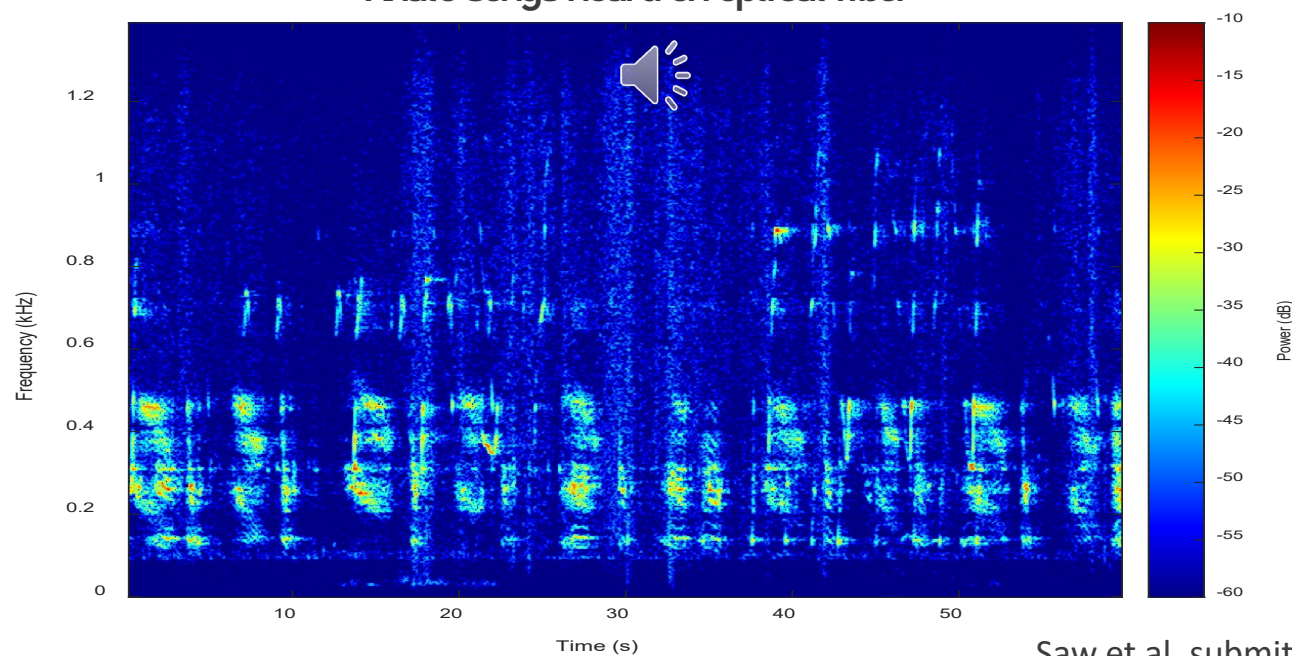
Monterey Bay National Marine Sanctuary



Collaborator: NOAA



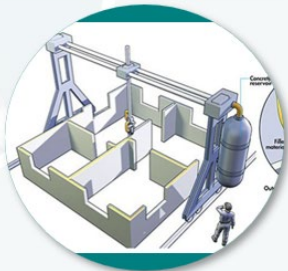
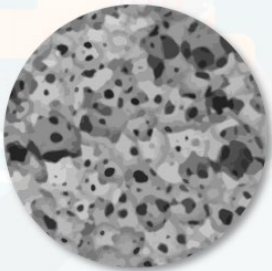
Whale songs heard on optical fiber



Future VISION

System level co-designed floating wind with significant cost reduction and environmental sustainability

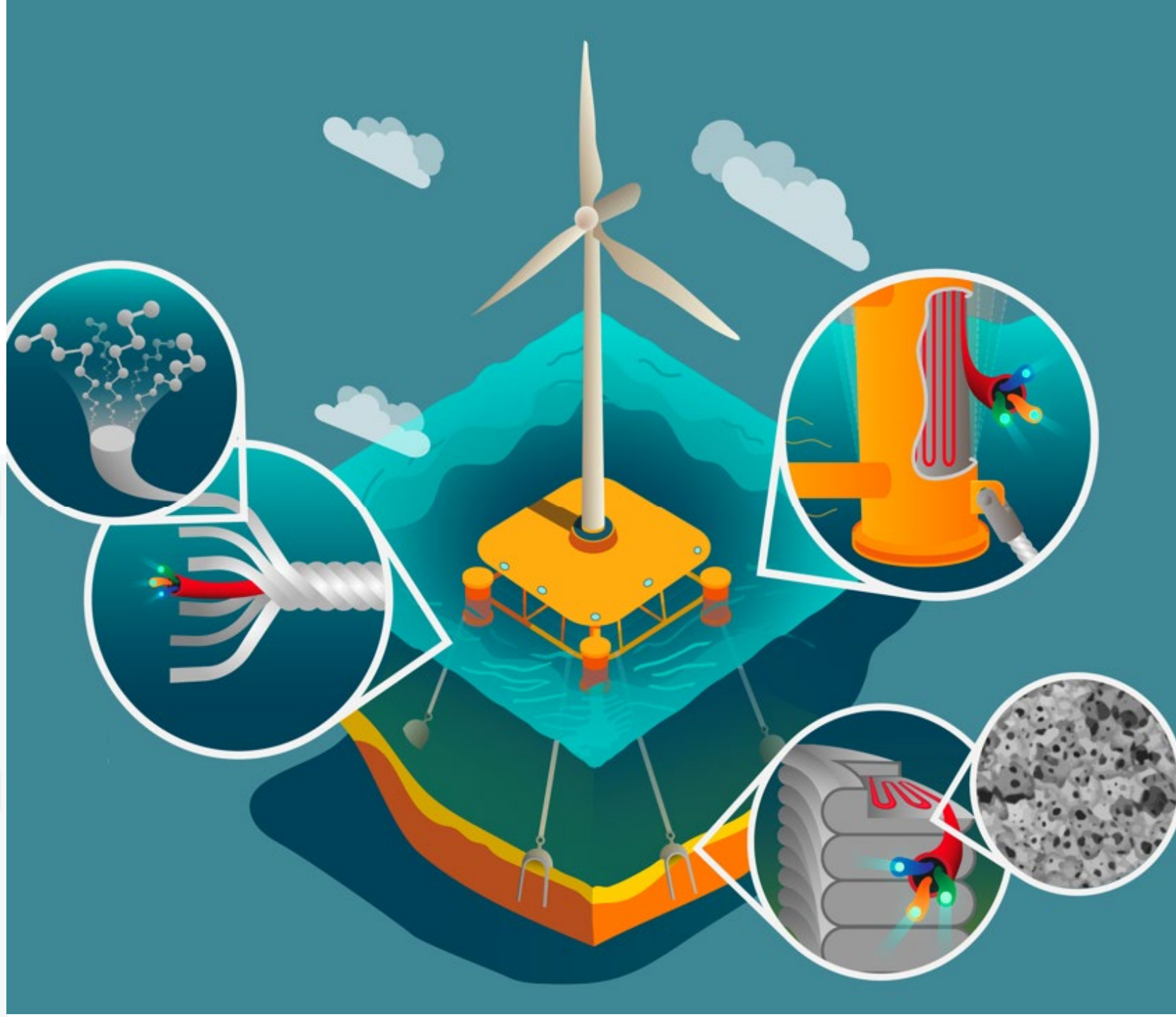
Fundamental Materials



Intelligence & Multi. Functionality



Environmental Sustainability





THANKYOU



CONTACT
YWu3@lbl.gov

Jeremy Snyder @LBN



sperra

Low-Cost, Environmentally-Friendly, Concrete Anchors Made in California

EPC-23-003

PI: Jason Cotrell; jason.cotrell@sperra.com

Leadership

Automated Construction – Renewable Energy – Commercialization



Jason Cotrell

Chief Executive Officer & Founder
MS, Mechanical Engineering, MBA



Gabriel Falzone

Chief Operating Officer
PhD, Materials Science



Vahid Azad

Chief Structural Engineer
PhD, PE, Civil Engineering



Taylor Marchment

Lead R&D Engineer
PhD, 3DCP Civil Engineering



Team

Automated Construction – Renewable Energy – Commercialization



Sonoko Watanabe

Structural Engineer
PhD, Civil Engineering



Mason Bell

Anchor Product Manager
BS, FE Civil Engineering



Evan Marquardt

Energy Storage Product Manager
MSc, Race Car Dynamics, MBA



Charlotte Marston

Proposal Manager | Technical Writer
BS, Biopsychology



Eduardo Rangel

Mechanical Engineer
BS, Mechanical Engineering



Jacob Blum

Material Engineer
BS, Material Engineering



We Are Hiring

Solar Product Manager
New York Printing Lead
R&D Interns



Sperra's California portside 3D concrete printing facility at AltaSea



About Us

**Building a new foundation
for clean energy**

Sperra is a renewable energy startup leveraging our expertise in 3D concrete printing to accelerate clean energy development.

Our Vision:

To build clean energy that is abundant and sustainable for nature and communities.

3D Concrete Printing

- Form-free process enables lean manufacturing with a small footprint
- Increases manufacturing efficiency
- Reduces physical burden
- Digital design: customization, complex geometries, structural optimization
- Sustainable locally sourced materials

Markets

sperra



Offshore
Wind



Offshore
Solar

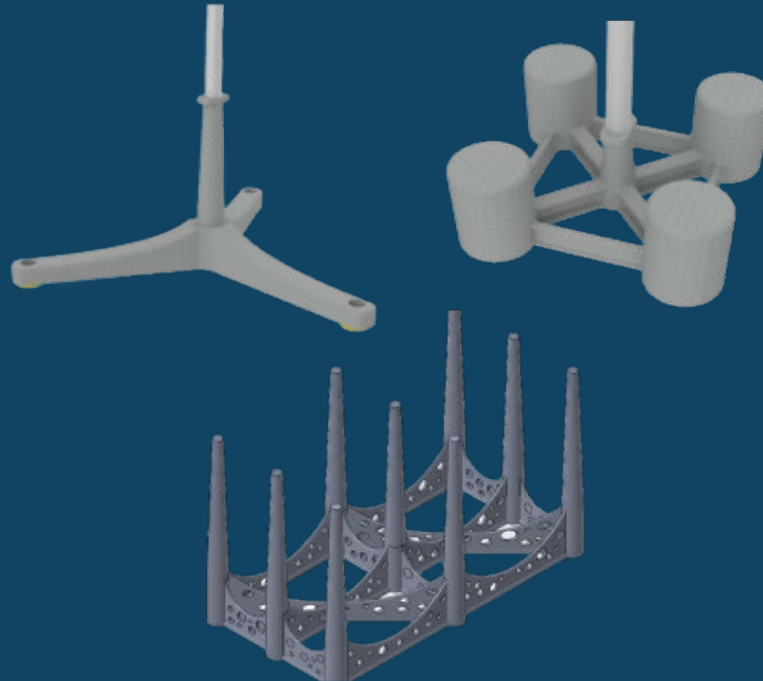


Wave
Energy

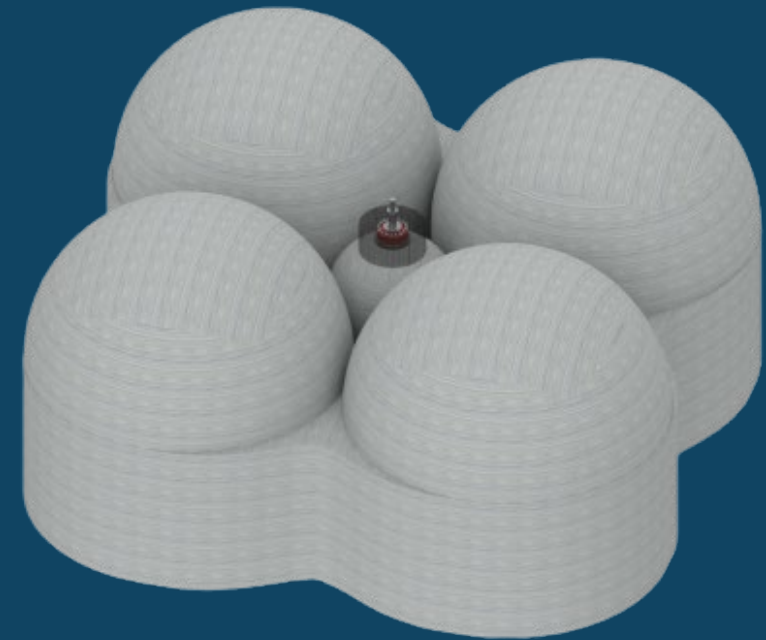
Products



Anchors



Foundations and Docks



Subsea Energy Storage



Project Overview

Project Purpose: To **develop a next-generation suction anchor and torpedo anchor** made from concrete **that cut manufacturing costs** between 37% to 82%, and **slash CO₂ emissions** between 55% to 96% compared to steel anchors.

Project Outcome: Advancement of Technology Readiness Level from 2 to 5 of a **scalable, low-cost, environmentally friendly anchor** that is **suitable for the majority of California's offshore wind** seabed areas, mooring types, and floating wind platforms.

Project Goals

1. Develop the lowest-cost environmentally friendly anchors for deployment in California wind energy areas.
2. Facilitate localized manufacturing in California ports.
3. Expand and accelerate the growth of California's concrete and floating wind workforce, R&D capabilities, and innovation ecosystem



Project Team Organization Chart

sperra

Project Prime

Project Advisory Panel

RWE

NIST
National Institute of
Standards and Technology
U.S. Department of Commerce



TechnipFMC

BOEM
BUREAU OF OCEAN ENERGY MANAGEMENT

CATAPULT
Offshore Renewable Energy

MANSON
CONSTRUCTION CO.

UC San Diego

Hydrodynamic,
Geotechnical
Design & Testing



UC San Diego

InterMoor

Steel Structural
Design & Analysis



MOORINGS
AND ANCHORS

WSP USA

Concrete Structural
Design



UC Irvine

Life Cycle
Assessment



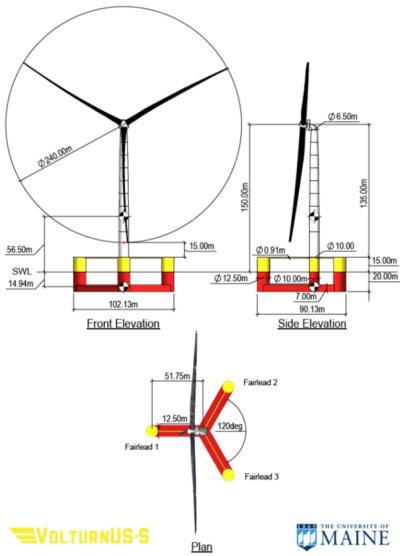
UCIRVINE



Project Progress

Objective: Generate anchor design loads and seismic characteristics for a reference floating wind plant.

Status: Complete



VOLTURNUS-S

THE UNIVERSITY OF MAINE

swi

Figure 3. Target 15 MW wind turbine and tri-pod semi-submersible platform proposed for the reference wind site (Allen et al. 2020).

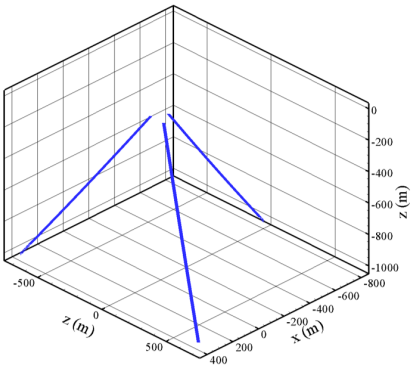


Figure 4. Taut mooring configuration in 1000 m deep water.

Humboldt Wind Energy Area

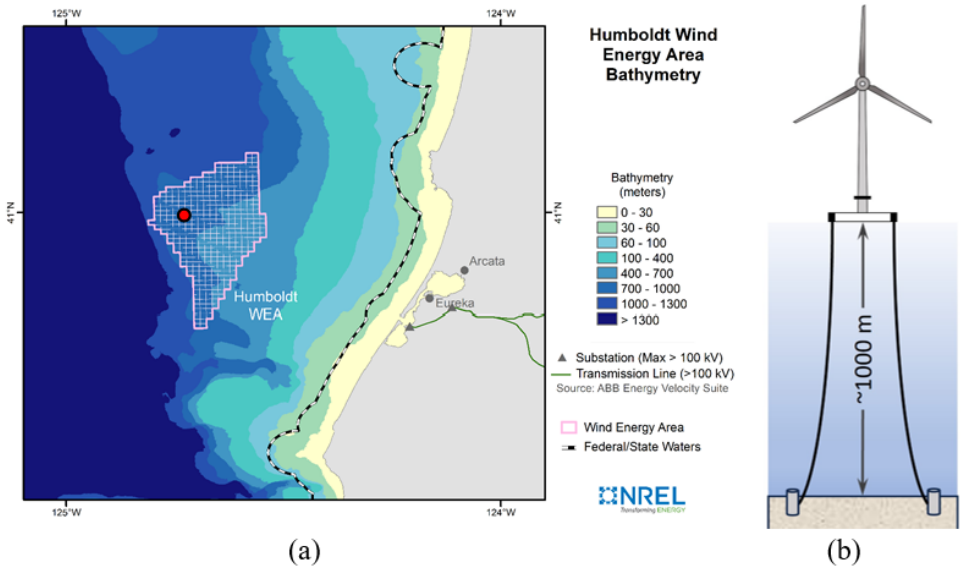


Figure 5. Proposed reference wind site for Humboldt WEA: (a) plan view of the bathymetry with selected site; (b) Schematic elevation view the selected site showing water depth.

Morro Bay Wind Energy Area

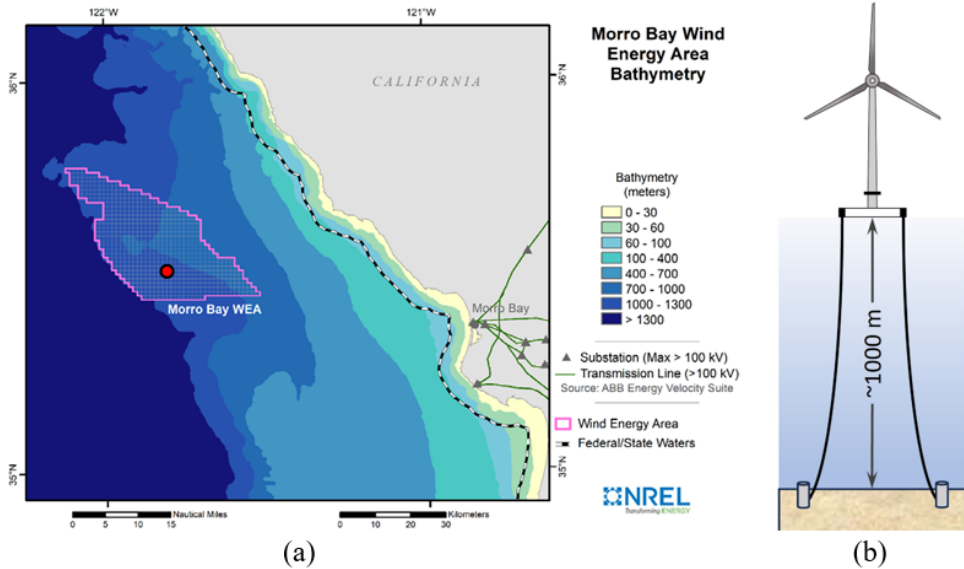


Figure 24. Schematic diagram of reference wind site for Morro Bay WEA: (a) plan view of the bathymetry with selected location; (b) Elevation view showing the depth to the soil layer.

Objective: Generate anchor design loads and seismic characteristics for a reference floating wind plant.

Status: Complete

Table 5. Summary of the anchor loads at various extreme sea conditions.

	Static	Dynamic with wave loading	Dynamic with current loading	Dynamic with current and wind loading	Dynamic with wave, current, and wind loading	Dynamic with current loading and broken cable
Limit State	Normal	ULS 1	ULS 2	ULS 3	ULS 4	ALS
Closest DNV 0437 Limit State	4.1 (F)	6.4 (N)	5.1 (N)	1.1 (N)	1.1 (N)	8.6 (A)
State of the mooring system	Intact	Intact	Intact	Intact	Intact	With fractured cable(s)
Significant wave height (m)	0	10	0	0	10	10
Current speed (m/s)	0	0	1	1	1	1
Wind speed* (m/s)	0	0	0	33	33	33
Estimated peak anchor load (MN)	2.395	2.75	3.32	6.93	7.3	6.9
Partial Safety Factors	1.0	1.35	1.35	1.25	1.25	1.10
Factored Loads (MN)	2.395	3.375	4.482	8.662	9.125	7.590

*Assumes that the turbine is generating power if the wind speed is greater than 0.

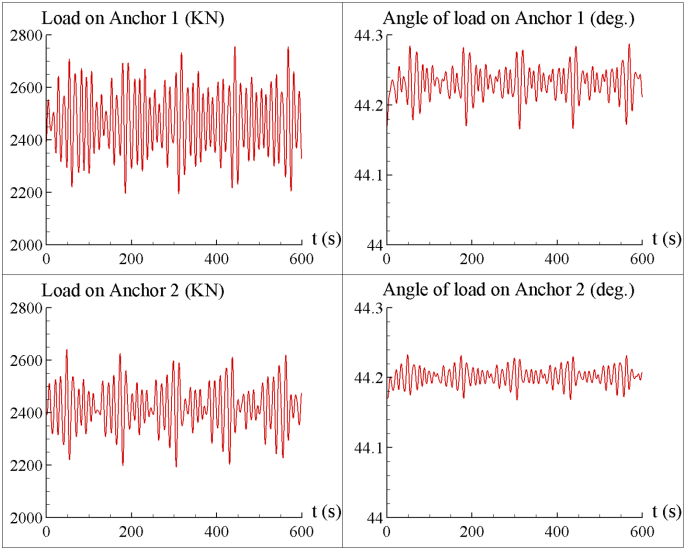


Figure 43. Load on anchors at $H_s = 10$ m.

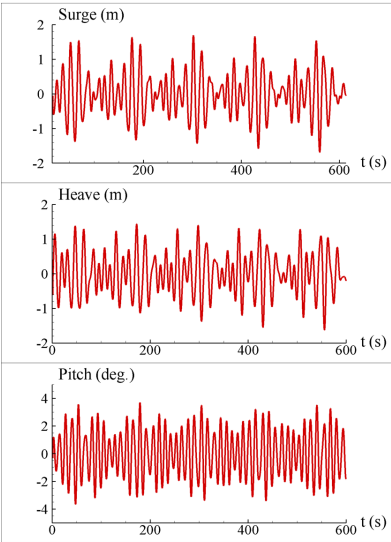


Figure 42. Displacements of the platform at $H_s = 10$ m.

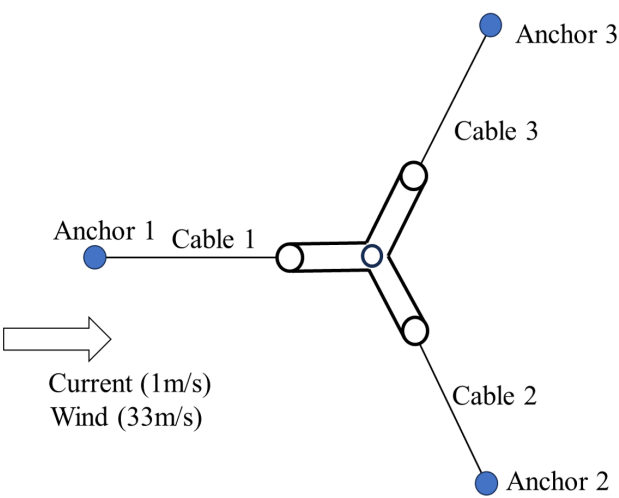


Figure 49. Setup for simulations of the current/wind effects.

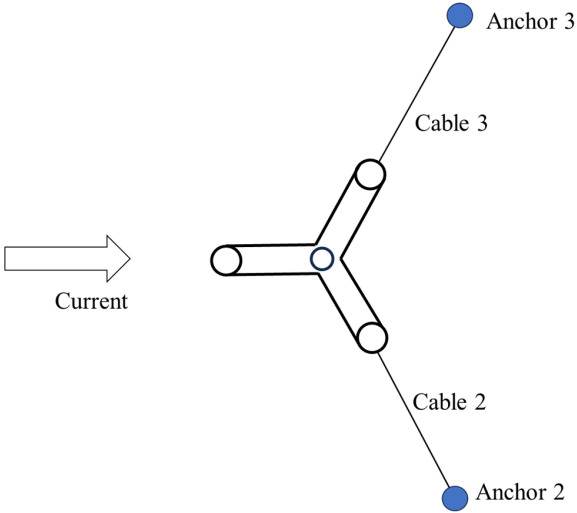


Figure 52. Setup (top view) for the analysis of response due to a fractured cable.

Project Progress

Objective: Generate anchor design loads and seismic characteristics for a reference floating wind plant.

Status: Complete

**Humboldt
Wind Energy Area**

**Morro Bay
Wind Energy Area**

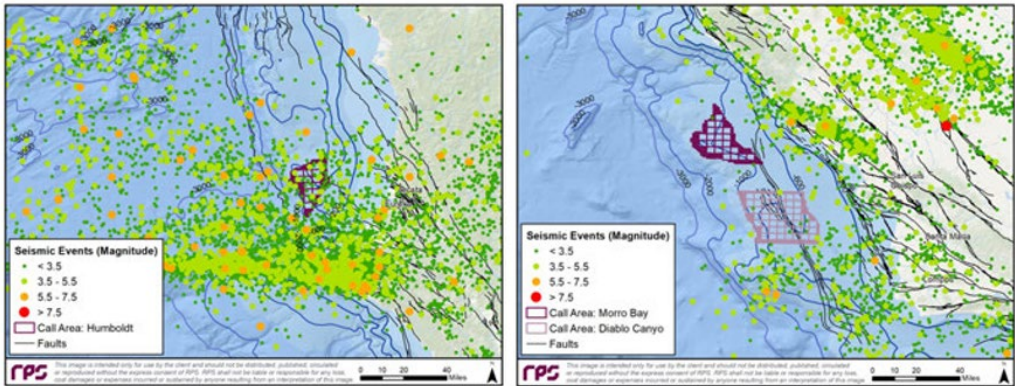


Figure 4.1. Historic earthquakes close to the study areas of Humboldt and Morro Bay (USGS, 2019c; Tajalli Bakhsh et al. 2020).

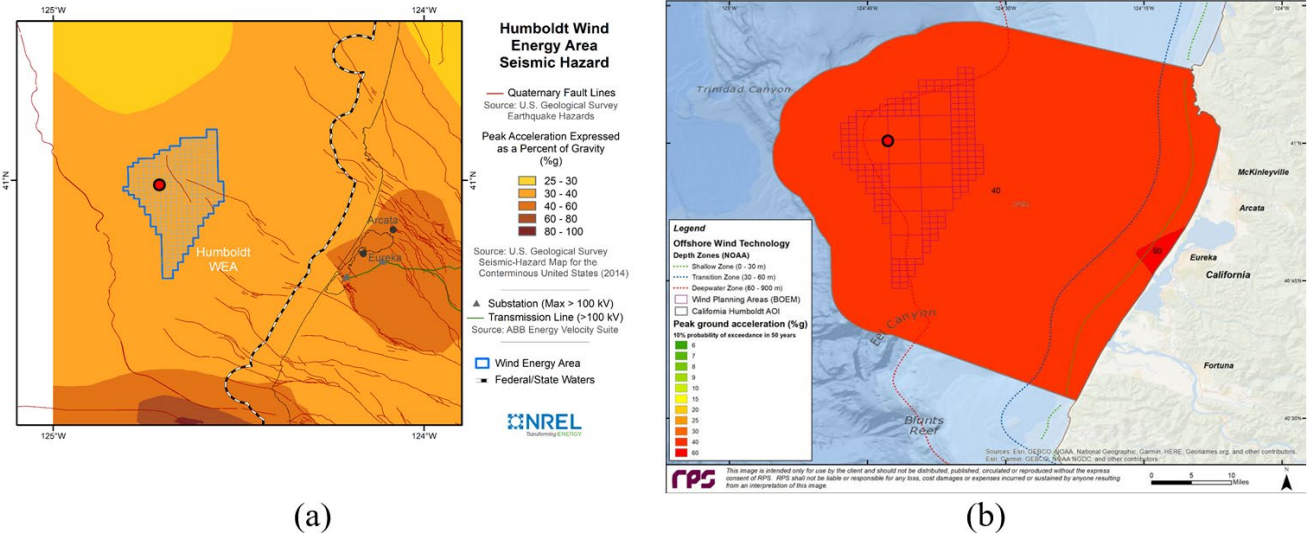


Figure 14. Seismic hazard and quaternary fault lines of the Humboldt WEA: (a) PGA (Cooperman et al. 2022); (b) PGA (Tajalli Bakhsh et al. 2020).

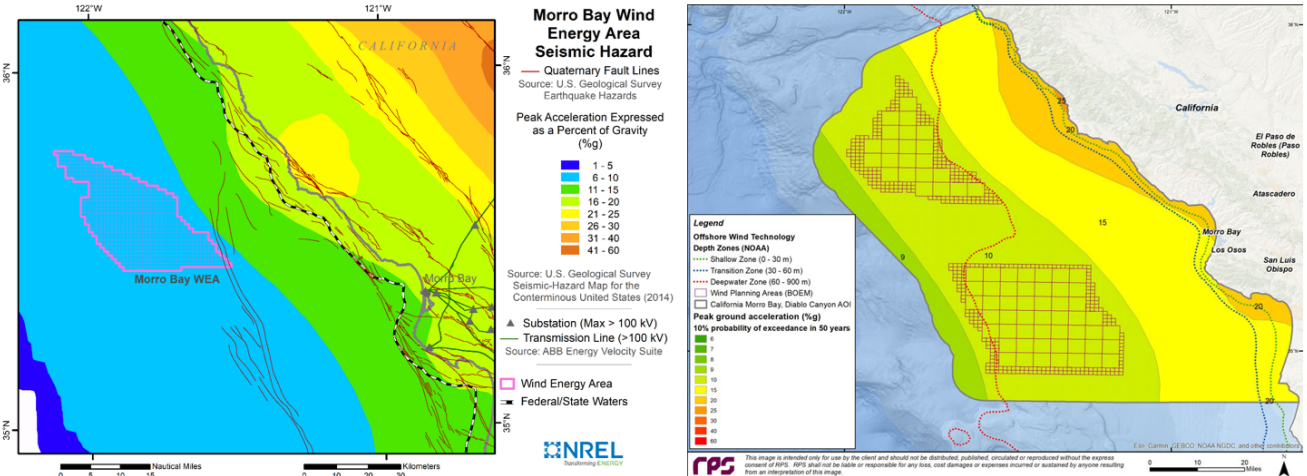


Figure 30. Seismic hazard quantified by PGA and quaternary fault lines of the Morro Bay WEA: (a) PGA (Cooperman et al. 2022); (b) PGA (Tajalli Bakhsh et al. 2020).

Project Progress

Objective: Gather and assess California offshore wind energy area seabed composition information.

Status: Complete

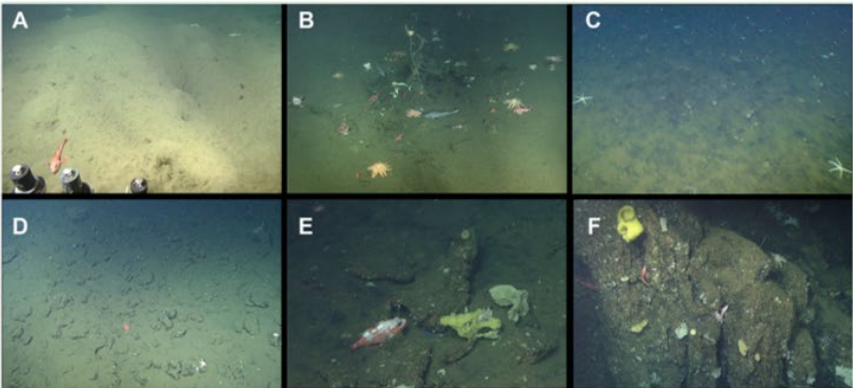


Figure 5.5. Seafloor habitats observed within the study region. A–C are soft substratum: A. hummocky mud (small, frequent mounds, 687 m depth) B. biological detritus and marine litter (935 m) and C. Greenish-black mud draped coarse sand (766 m). D and E are a mix of soft and hard substrata: D. cobble (575 m) and E. bedrock slabs (477 m). F. is the only type of completely hard substratum observed, referred to as bedrock outcrop (447 m) (Kuhn et al., 2022).

Humboldt Wind Energy Area

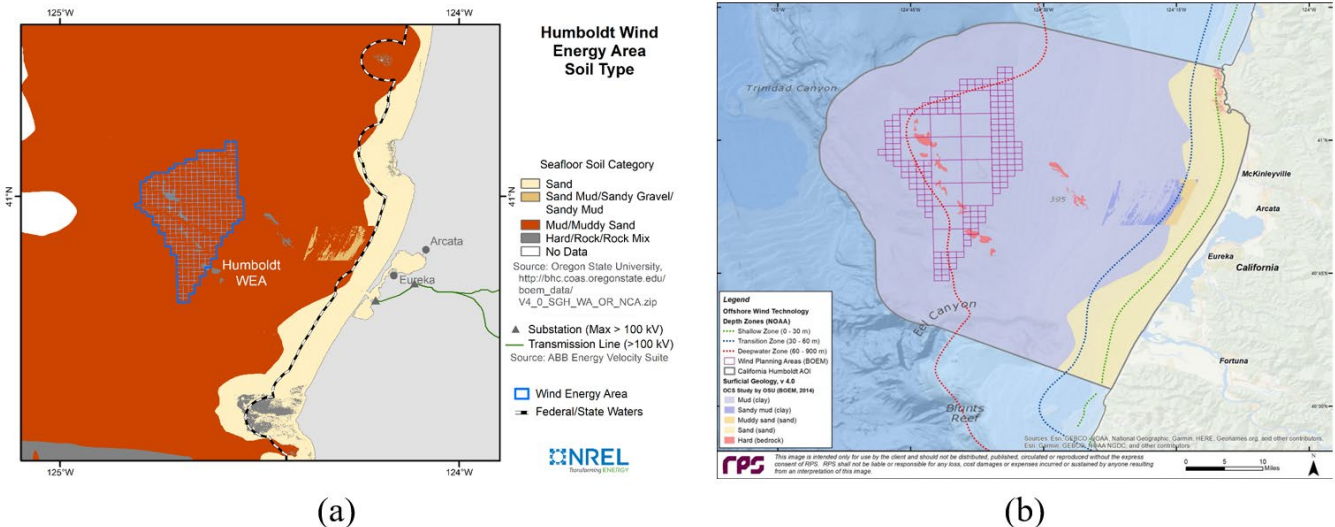


Figure 8. Soil types of the Humboldt WEA and surrounding regions: (a) Seafloor categories (Cooperman et al. 2022); (b) Surficial geology (Tajalli Bakhsh et al. 2020).

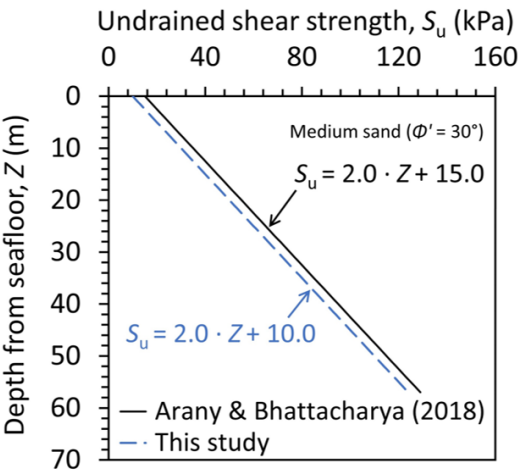
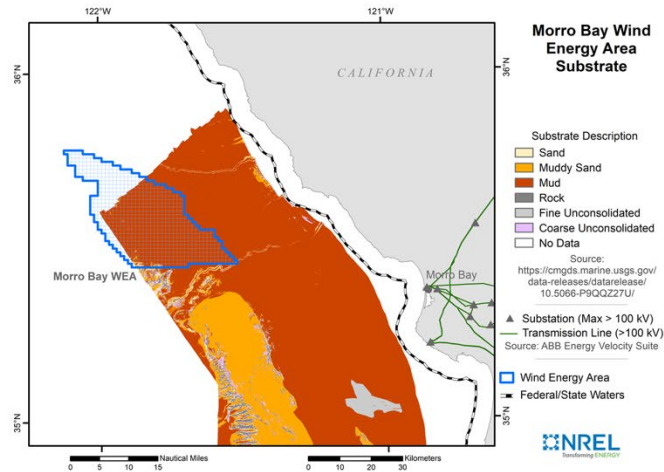


Figure 5.9. Schematic diagram of undrained shear strength of soil with depth from seafloor at Humboldt WEA.

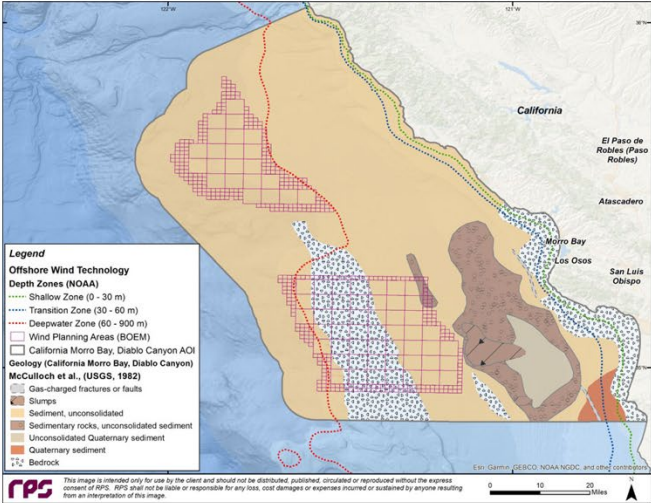
Objective: Gather and assess California offshore wind energy area seabed composition information.

Status: Complete

Morro Bay Wind Energy Area



(a)



(b)

Figure 26. Soil types of the Morro Bay WEAs and surrounding regions: (a) Substrate descriptions (Cooperman et al. 2022); (b) Soil types (Tajalli Bakhsh et al. 2020).

Table 4. Summary of the key soil properties for the two reference wind sites.

General soil type	Humboldt WEA			Morro Bay WEA		
	Fine-grained sandy soil			Low plasticity clayey soil		
Bound	Low	Mean	High	Low	Mean	High
Total unit weight, γ (kN/m ³)	16	17	18	15	16	17
Drained friction angle, ϕ' (°)	30	32	33	28	30	32
Drained cohesion, c' (kPa)	0	0	0		0	
Undrained shear strength at ground surface, s_{u0} (kPa)	8	10	12	3.9	4.9	5.9
Rate of increase in undrained shear strength with depth s_{uz} (kPa/m)	2	2	2	1.9	1.9	1.9
Sensitivity, S	1.1	1.0	1.0	1.2	1.1	1.0

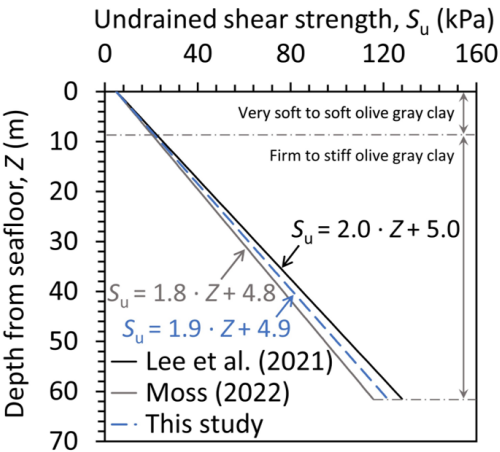


Figure 27. Schematic diagram of undrained shear strength of soil with depth from seafloor at Morro Bay WEA.

Objective: Conceptually design 6 next-generation concrete anchors and 2 steel reference anchors. **Status:** In Progress

Suction Bucket Anchors

Operating Principal Suction anchors are installed into the ocean floor using suction, pile driving or by vibratory installation. When lifted the hollow bottom generates a pressure differential providing additional anchoring capacity.

Reference Steel Design #1

Parameter	Steel
Diameter, m	7
Length, m	20
Embedment, m	19
Avg. Wall, mm	44
Estimated Dry Weight, MT	193
Horiz. Safety Factor (1.6 required)	9.0
Vertical Safety Factor (2.0 required)	2.1
Estimated Cost (FOB), each anchor	\$965,000



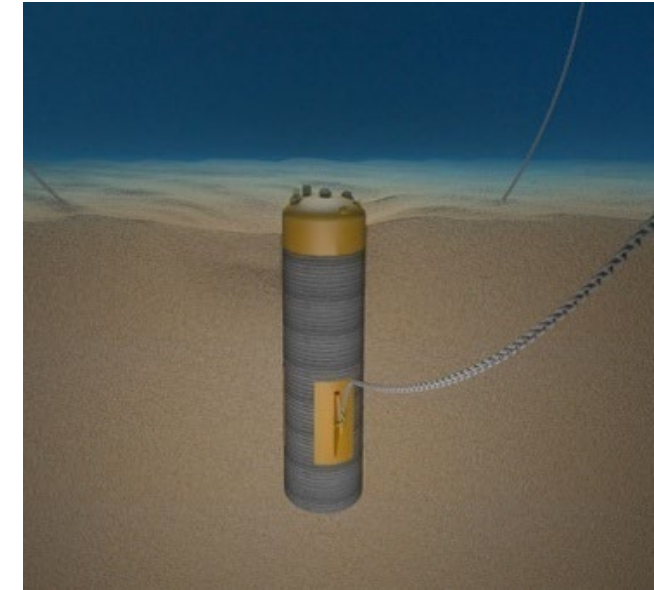
FUNDING PROVIDED BY THE
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ENERGY
COMMISSION**



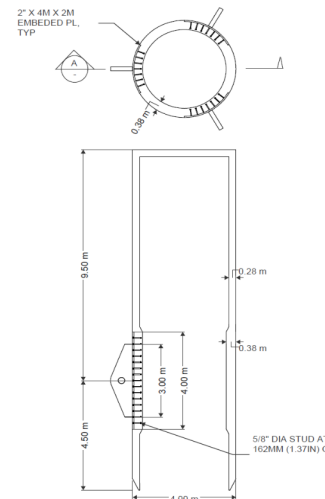
sperra

INNOVATIONS

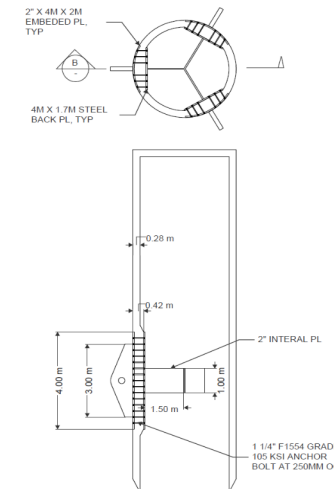
- Uses locally sourced concrete and local labor
- Combines 3DCP, reinforcement, and sprayed concrete to make a composite structure
- Structural optimization/efficient use of materials



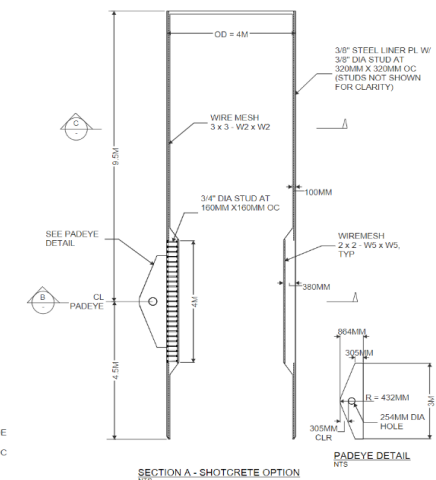
Concrete Design #1



Concrete Design #2



Concrete Design #3

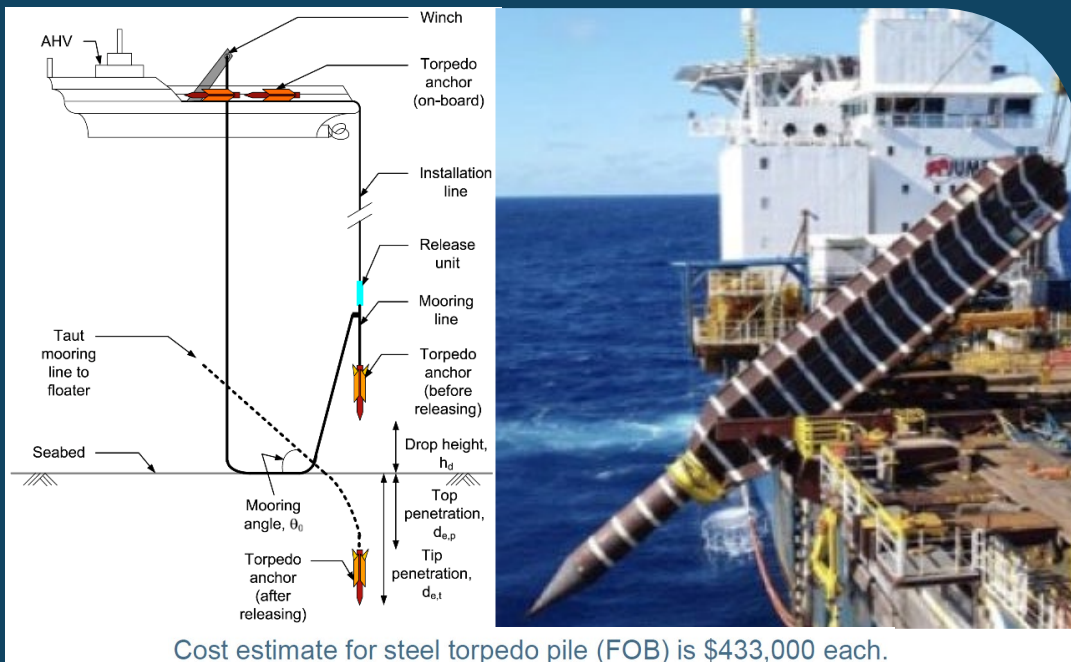


Objective: Conceptually design 6 next-generation concrete anchors and 2 steel reference anchors. **Status:** In Progress

Torpedo Anchors

Operating Principal Torpedo anchors rely on their momentum from being dropped off a ship to embed themselves deep in the ocean floor.

Reference Steel Design #2



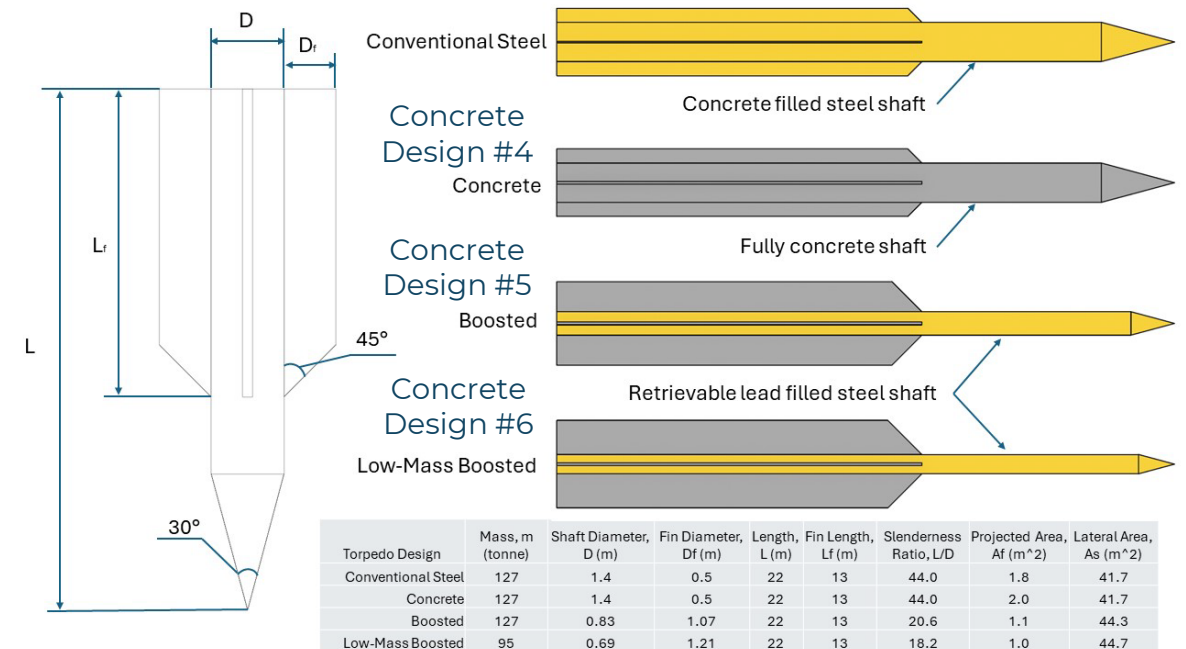
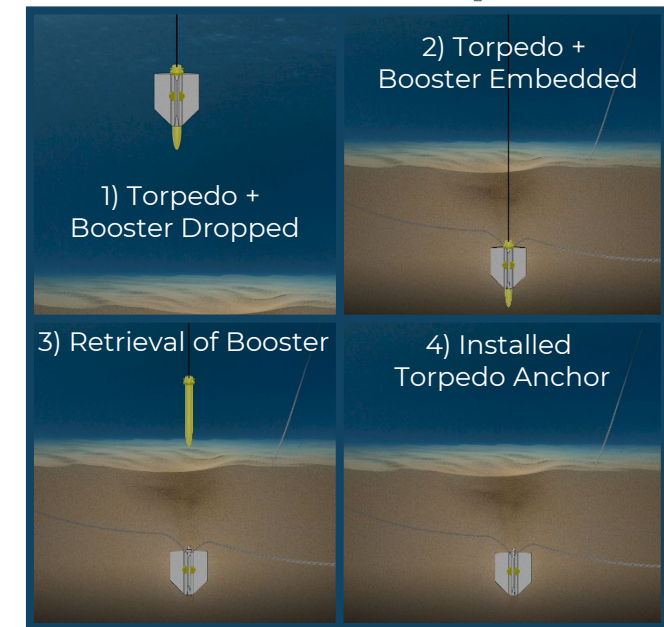
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INNOVATIONS

- Retrievable steel booster
- Hydrodynamic features to increase freefall speed
- Uses locally sourced concrete and local labor
- Combines 3DCP, reinforcement, and sprayed concrete to make a composite structure
- Structural optimization/efficient use of materials





Objective: Demonstrate automated concrete manufacturing methods including 3D concrete spraying, 3D concrete printing, and casting in 3D printed formwork to fabricate anchors. **Status:** In Progress

**1/8 Suction Bucket
Anchor Prototype
3D Concrete Printed**



**1/10 Torpedo Anchor
Prototype 3D
Concrete Printed**



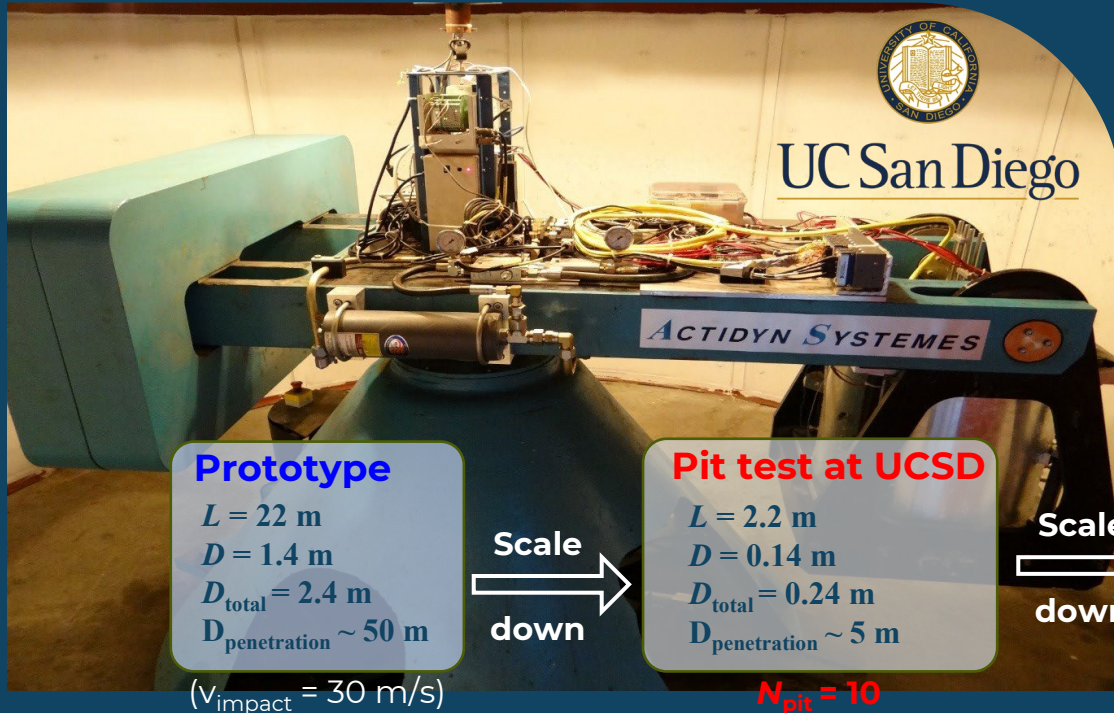
**1/10 Torpedo Anchor
Prototype cast in 3D
printed formwork**



Objective: Perform lab experiments to validate structural, seismic, embedment, and load models.

Geotechnical Centrifuge Testing

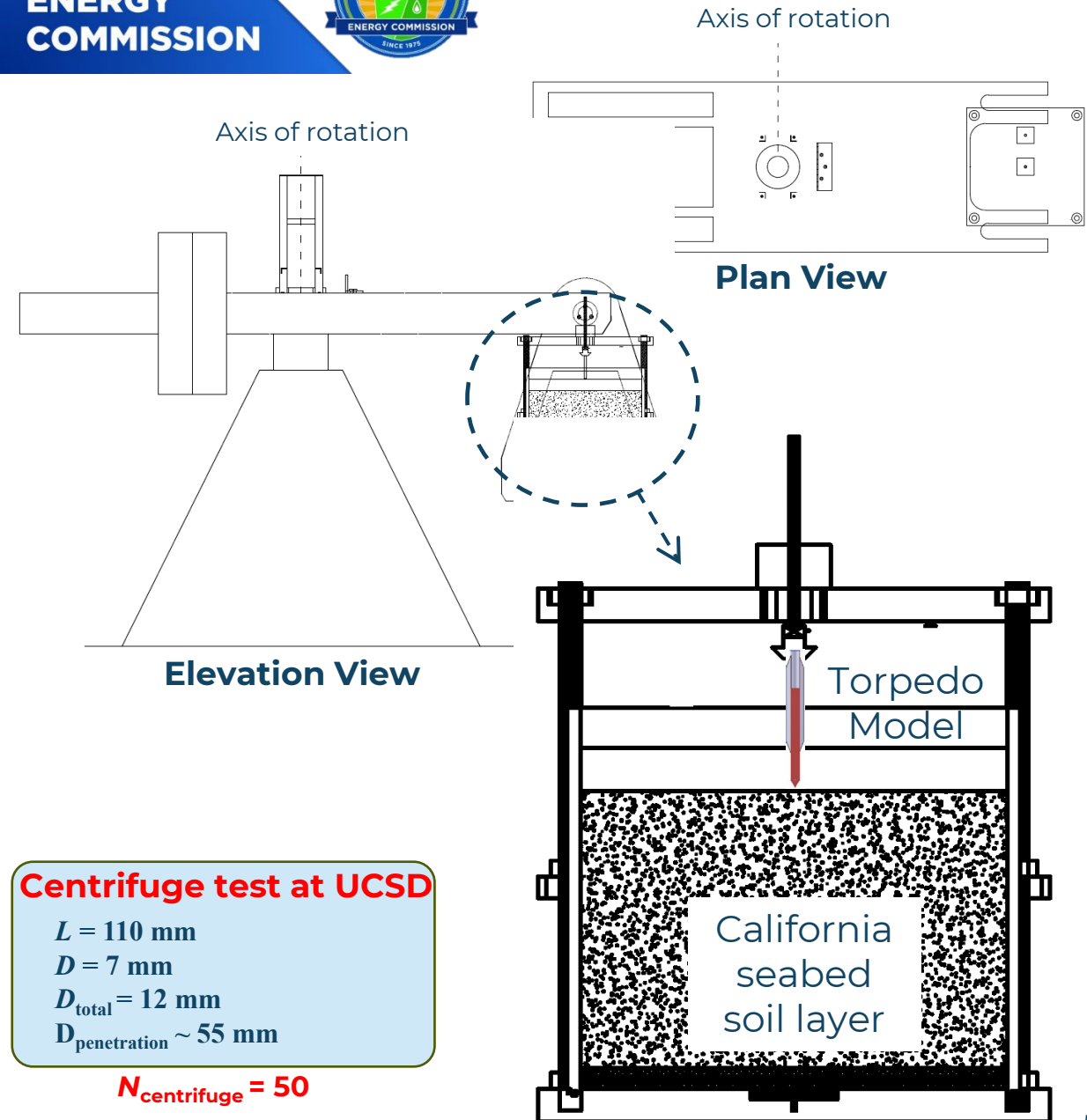
- Advanced physical modelling technique for studying the behavior of reduced-scale models under realistic stress states.



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Objective: Disseminate project information to the developer advisory panel and publicly.

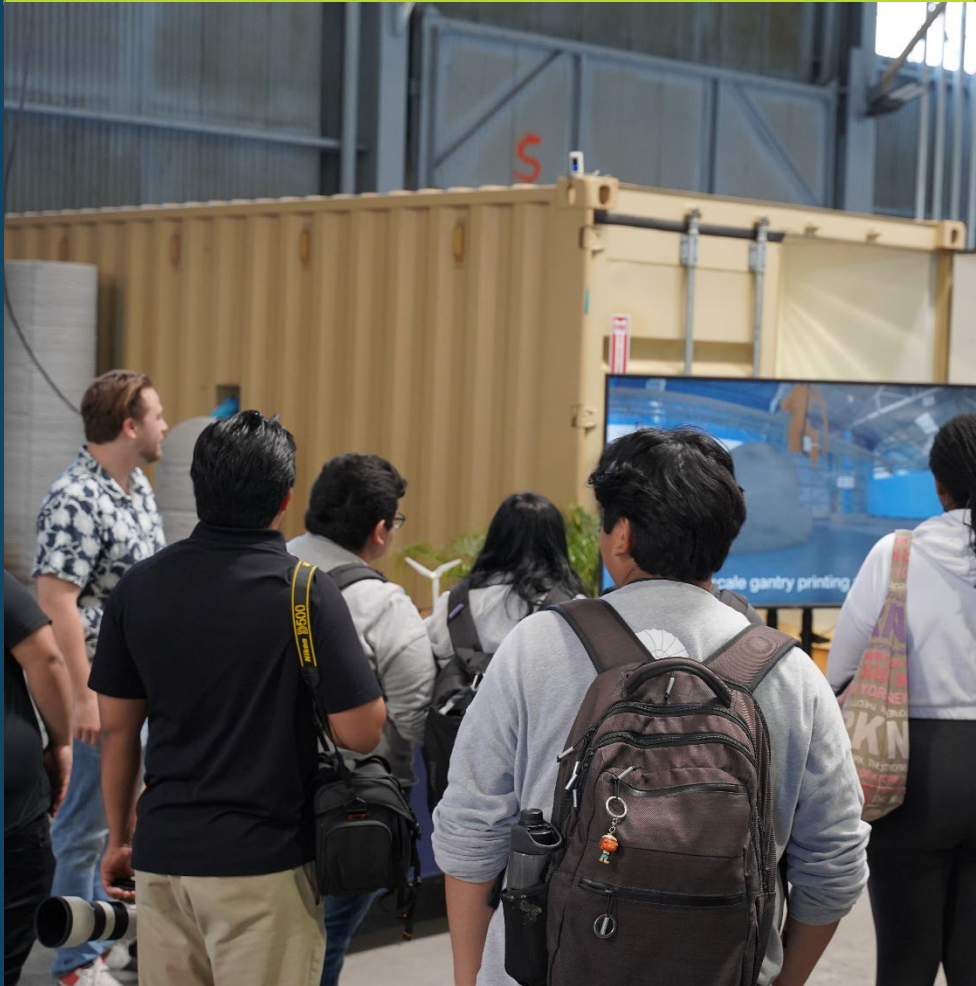
25+ industry events attended / presented at



3 appearances on Live TV



Over 1,000 tours of our R&D facility and counting





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Thank you!

**Low-Cost, Environmentally-Friendly,
Concrete Anchors Made in California**

EPC-23-003

Jason Cotrell

CEO & Founder, Sperra

Jason.Cotrell@sperra.com

<https://www.linkedin.com/in/jason-cotrell>

Mason Bell

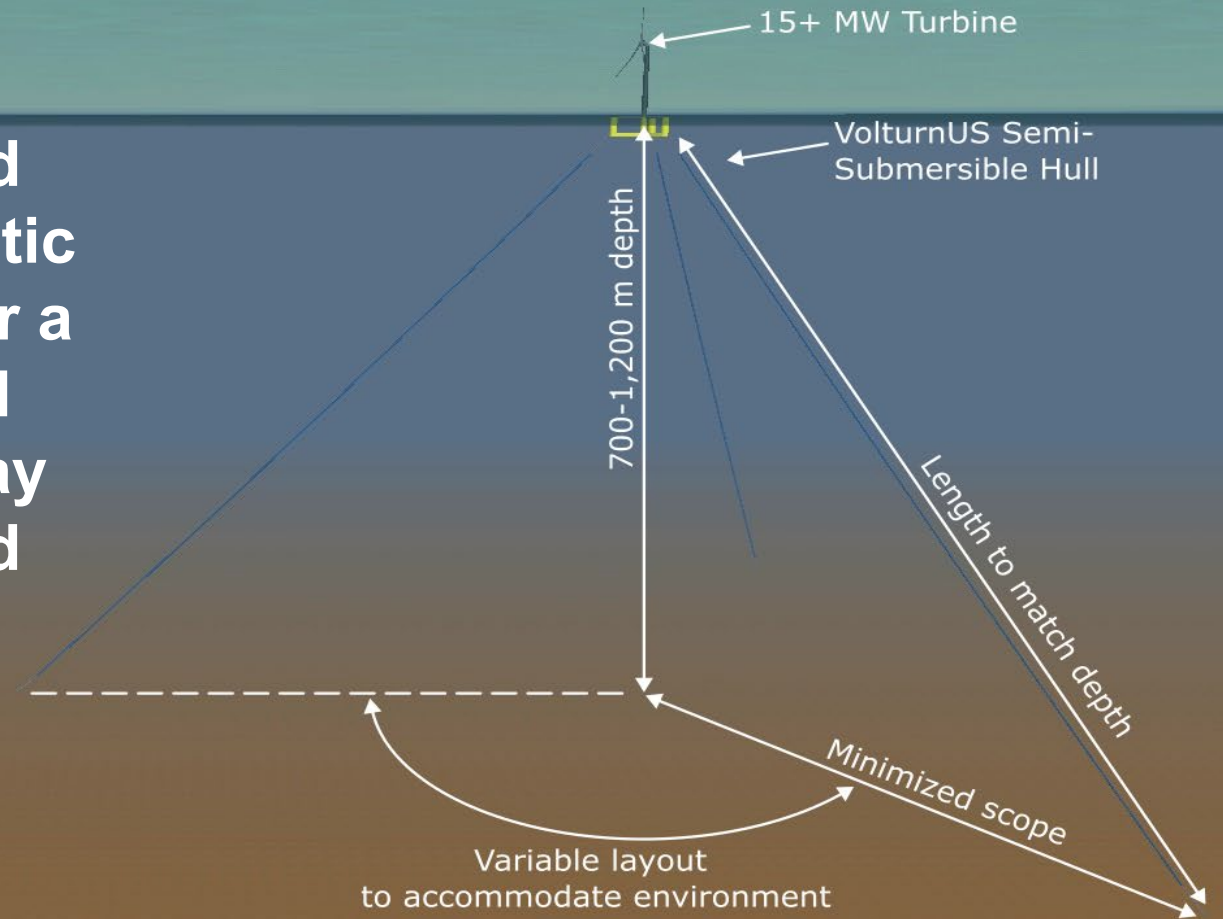
Anchor Product Manager, Sperra

Mason.Bell@sperra.com

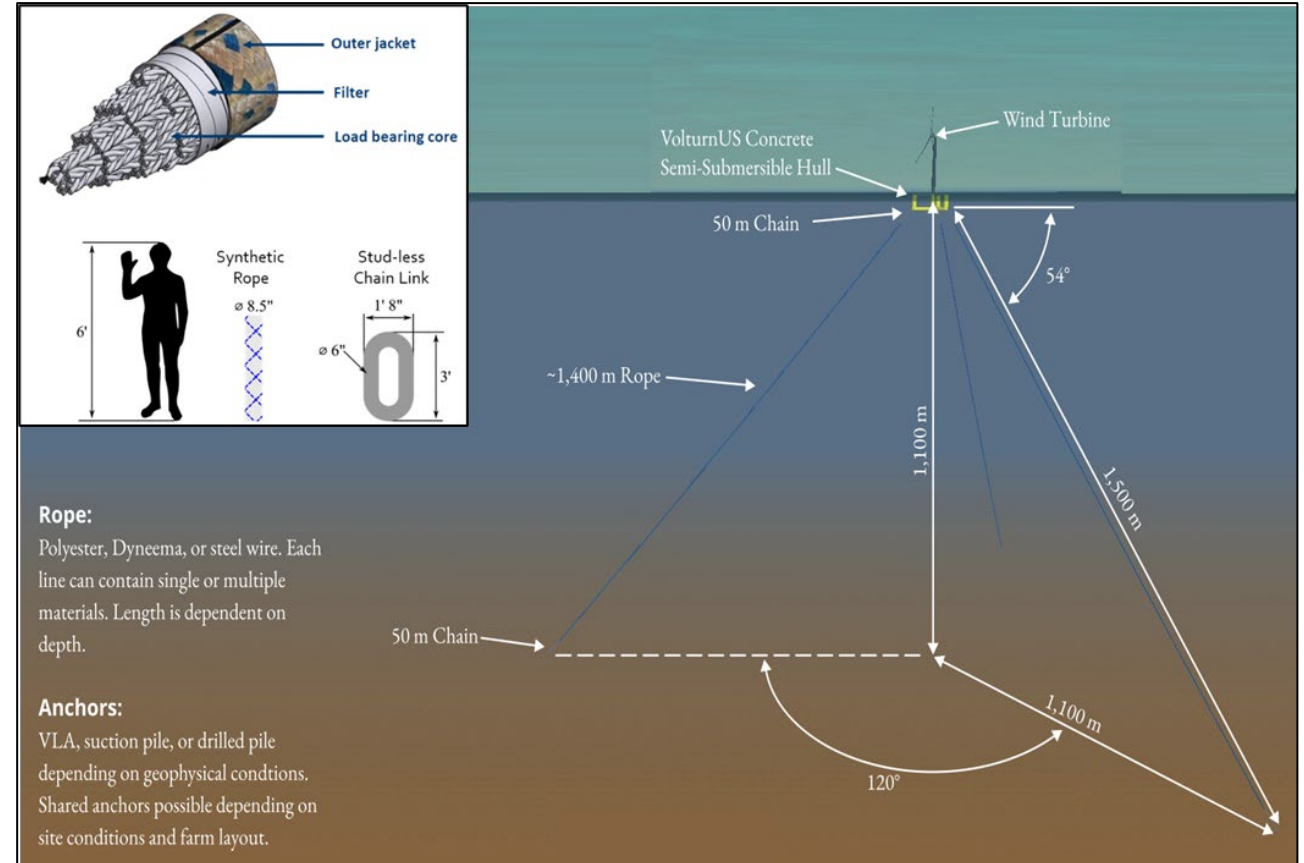
<https://www.linkedin.com/in/mason-bell-sperra/>





Design, Validation, and Certification of a Synthetic Mooring Line System for a 15+ MW Floating Wind Turbine in the Morro Bay and Humbolt Bay Wind Energy Areas

Dr. Spencer Hallowell,
University of Maine



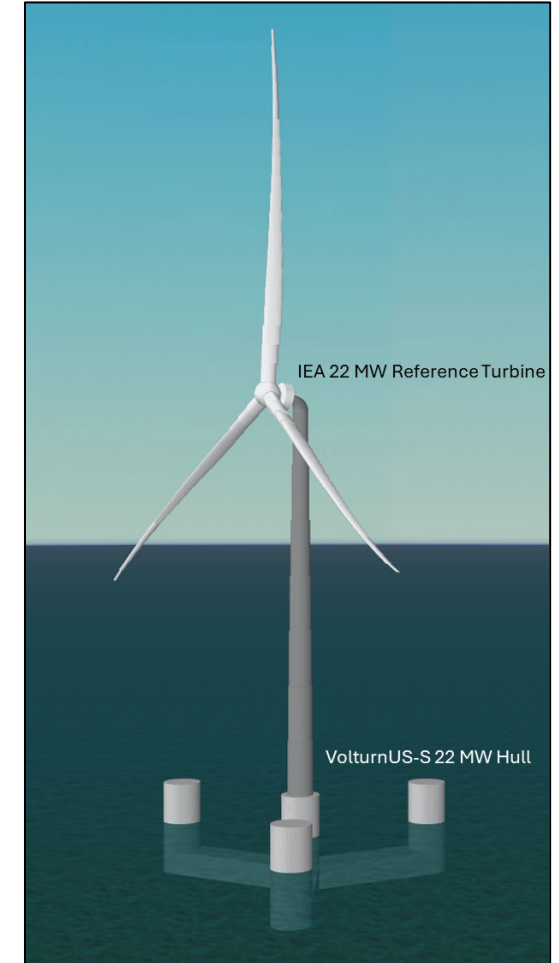
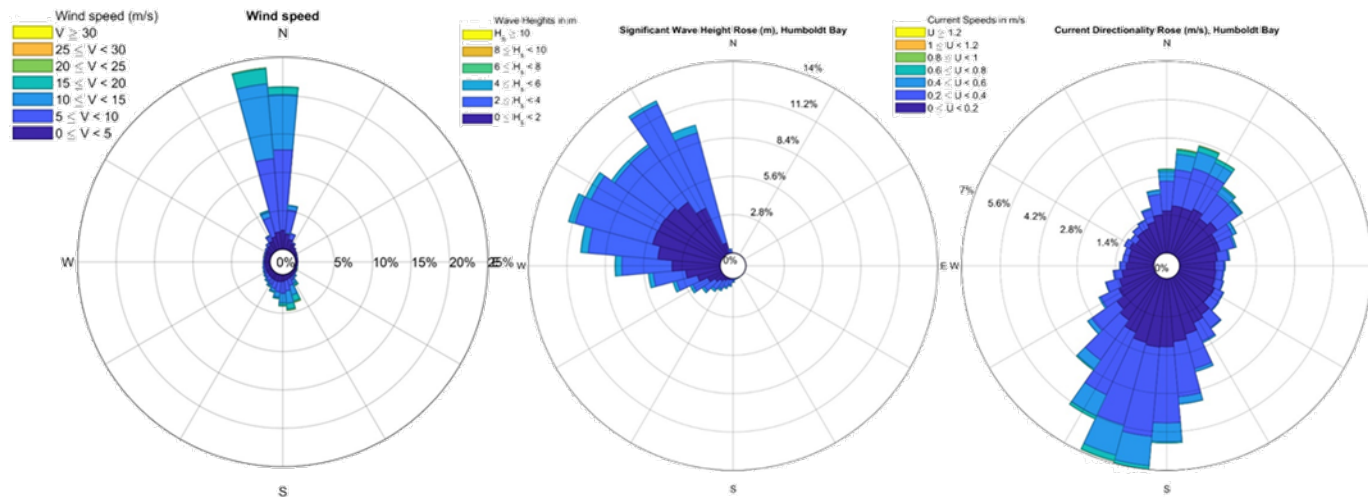
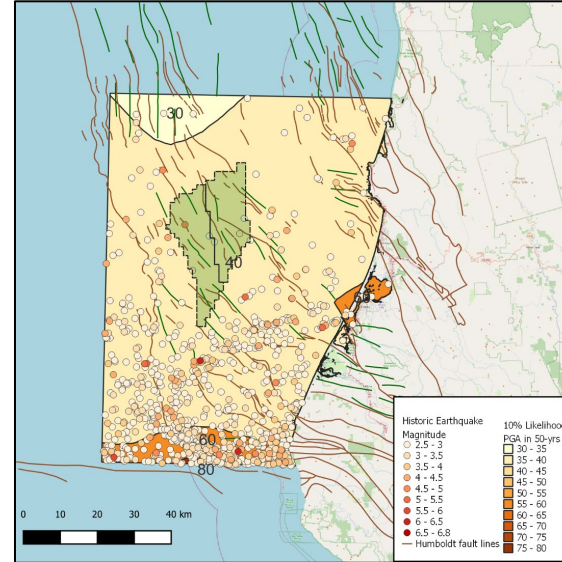
- 5 GW of offshore wind requires 1,000 km of mooring lines
- Develop a taut-synthetic mooring system to 50% FEED level
- Emphasize minimizing jewelry and connections, and increasing ease of installation
- Minimize environmental impact to the ocean resource



Affiliation	Role
	<ul style="list-style-type: none"> • Principle Investigator • Coordinate subcontractors • Responsible for: <ul style="list-style-type: none"> • Mooring design at 25% and 50% FEED Level • 1:47 Scale Model Basin Test at Harold Alfond W² • Environmental Risk Assessment
	<ul style="list-style-type: none"> • Mooring design support • Cradle to grave installation, O&M, and decommissioning philosophy • Anchor design specific to mooring and CA environment, including seismicity • Mooring integrity management plan and risk workshops
	<ul style="list-style-type: none"> • Synthetic rope properties custom to mooring design • Support design of synthetic mooring components • Support cradle to grave installation, O&M, and decommissioning philosophy • Mooring integrity management plan and risk workshops
	<ul style="list-style-type: none"> • Design document review: <ul style="list-style-type: none"> • Basis of design, mooring design, installation, O&M, and decommissioning philosophy, scale model test report, integrity management plan, design drawings • Provide subject experts for Risk Assessment Workshop • Approval in Principle (AIP) letter attesting to feasibility of design

- Lays out design assumptions for 25% and 50% FEED
- Reviewed and approved by ABS as part of AIP

Return Period (years)	U_{150} (m/s)	H_s (m)	T_p (s)	Surface Current (m/s)
1	27.5	5.9	12.7	0.9
10	31.3	7.9	14.8	1.1
50	33.2	10.6	17.1	1.2
100	33.9	12.2	18.4	1.3
500	35.3	15.7	20.8	1.4



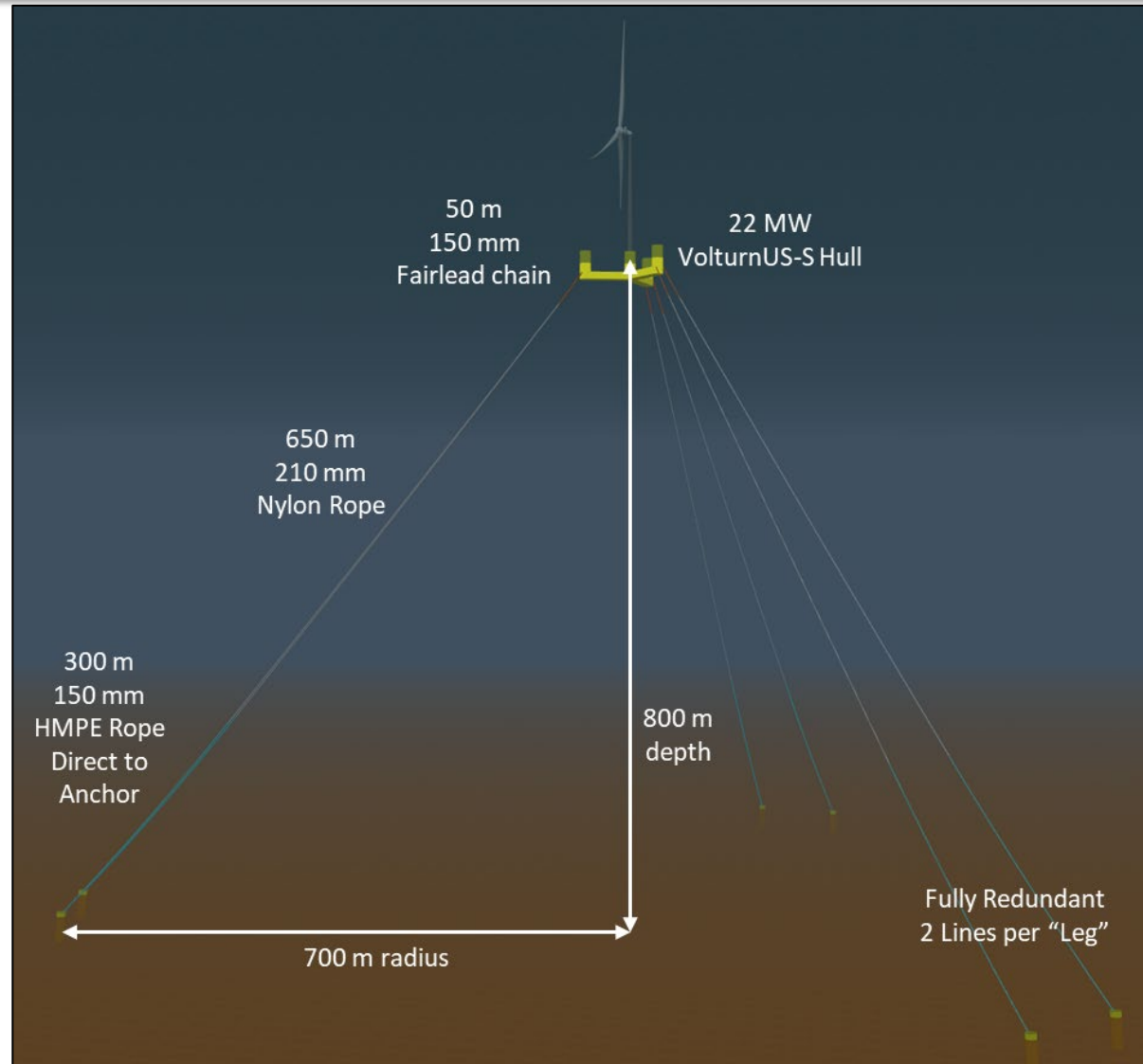
Turbine Condition	ABS DLC¹
1) Power production	1.2
	1.6
6) Parked, standing still or idling	6.1
	6.2
10) Redundancy	10.1
SLC	I1
Seismic	S3
	S4
Environmental	E3

¹ From American Bureau of Shipping. *Guide for Building and Classing Floating Offshore Wind Turbines*, Chapter 5 Section

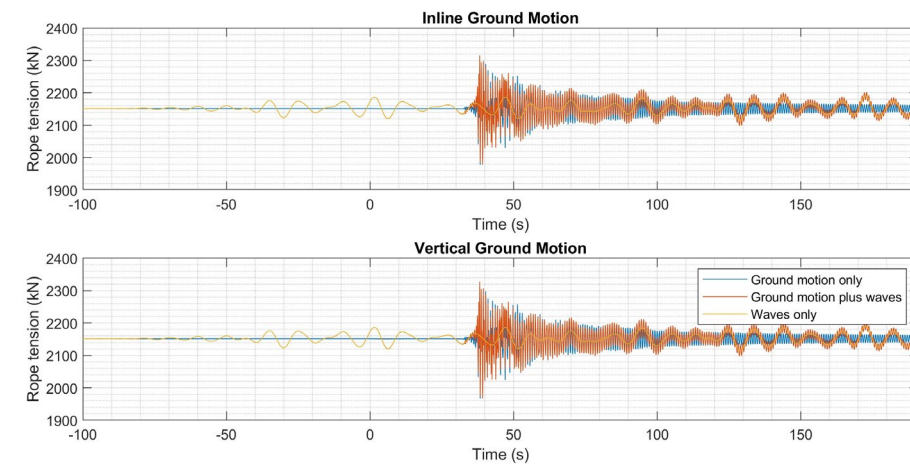
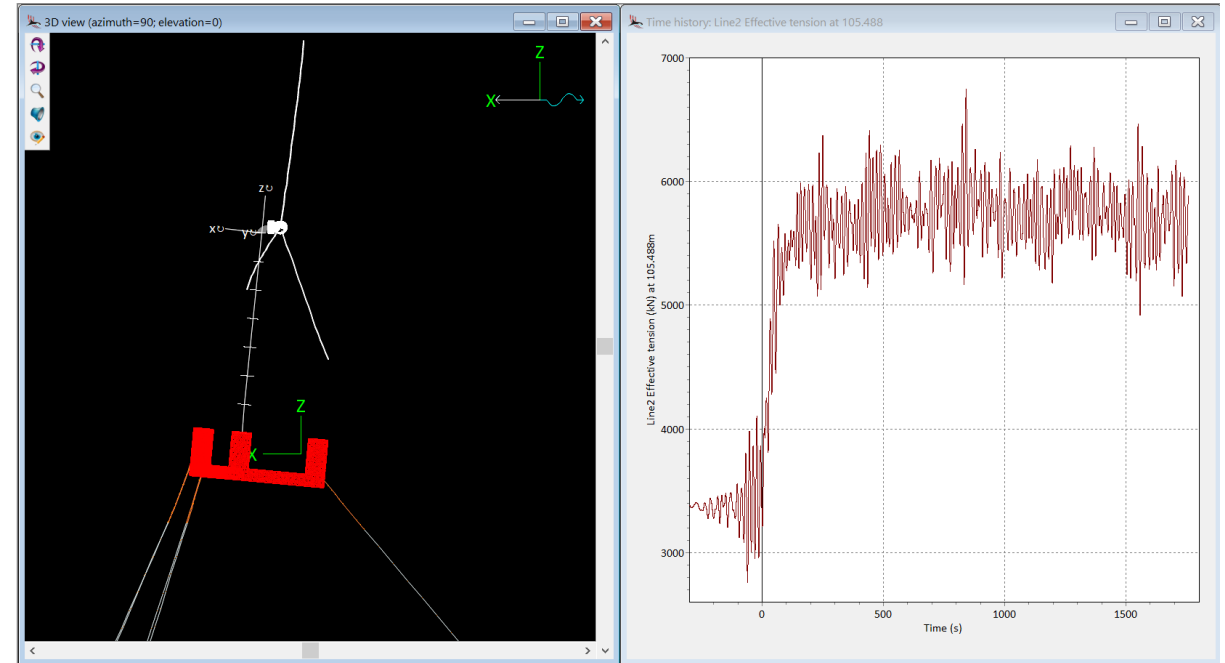
2. July 2020 edition

For each turbine condition:

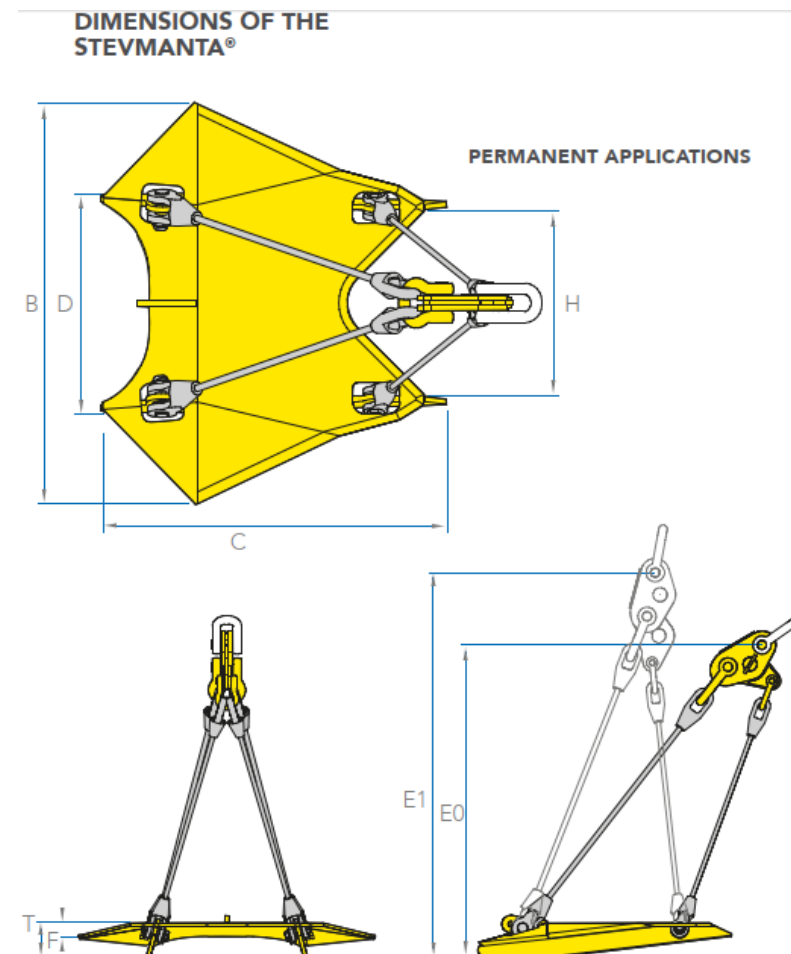
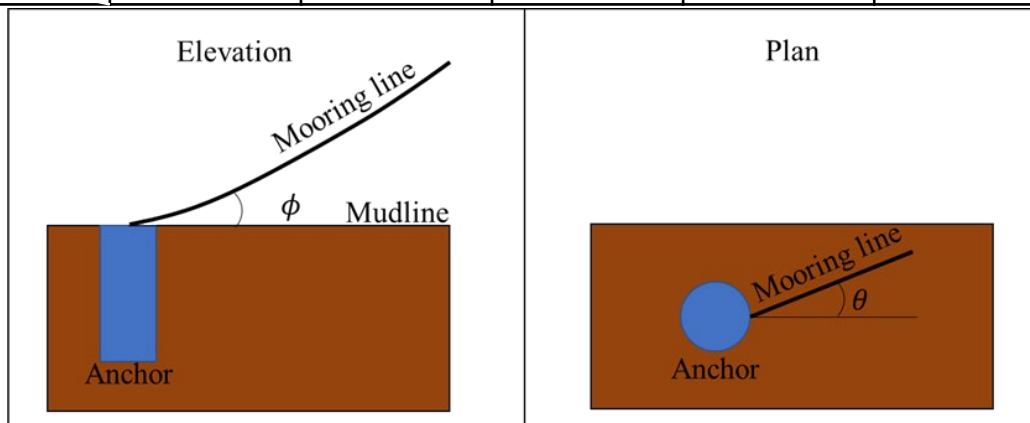
- Wind
- Waves
- Wind and wave directionality
- Current
- Water level
- Safety factor

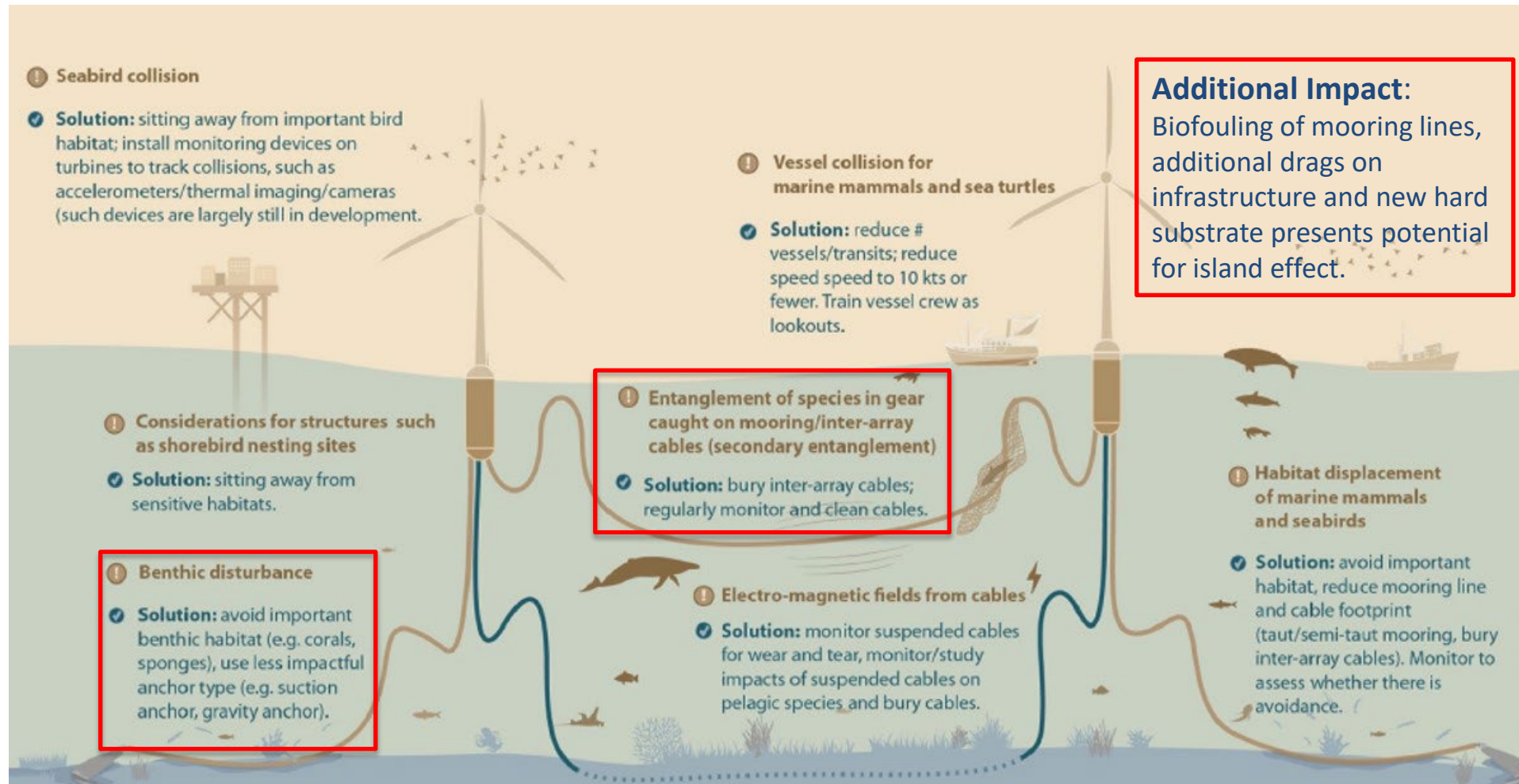


- Redundancy: 1-line failed condition
 - Peak tension occurs *after* turbine is arrested from transient state
 - Mean tension is greatly increased in line failed configuration (nearly doubled)
 - Stationkeeping is maintained
 - Factored tensions are less than other DLCs
- M6.2 Earthquake ground motions amplify line tensions by ~10%
- Peak tensions during average operational state much less than extreme cases (1.6 and 6.1)
- Further work to investigate combinations with higher seastates needed



	Independent Variable	Dependent Variable	Dependent Variable	Dependent Variable	
		$T(t)$	$\phi(t)$	$\theta(t)$	
DLC 1.6	T_{max}	3130	47.3	-0.1	Controlling DLC
	ϕ_{max}	3121	47.4	-0.1	
	θ_{max}	2262	46.3	0.2	
DLC 6.1	T_{max}	4481	47.3	0.2	
	ϕ_{max}	4413	47.4	0.2	
	θ_{max}	3284	46.5	0.3	
SLC	T_{max}	6405	47.4	0.0	
	ϕ_{max}	6389	47.7	0.0	
	θ_{max}	4297	47.0	0.5	
Overall Maxima		6405	47.7	0.5	SLC
Overall Envelope	T_{max}	6405	47.4	0.0	
	ϕ_{max}	6389	47.7	0.0	
	θ_{max}	4297	47.0	0.5	SLC



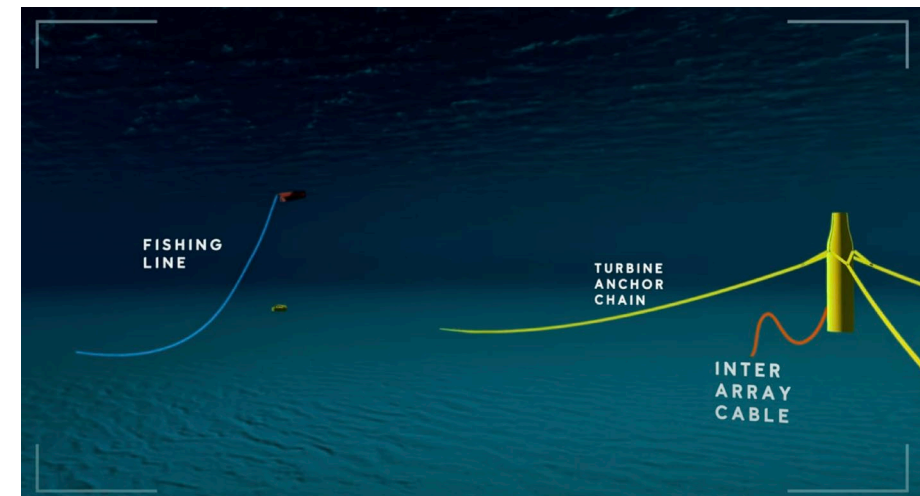
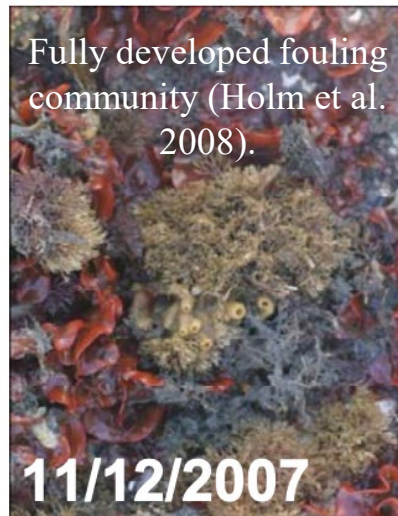
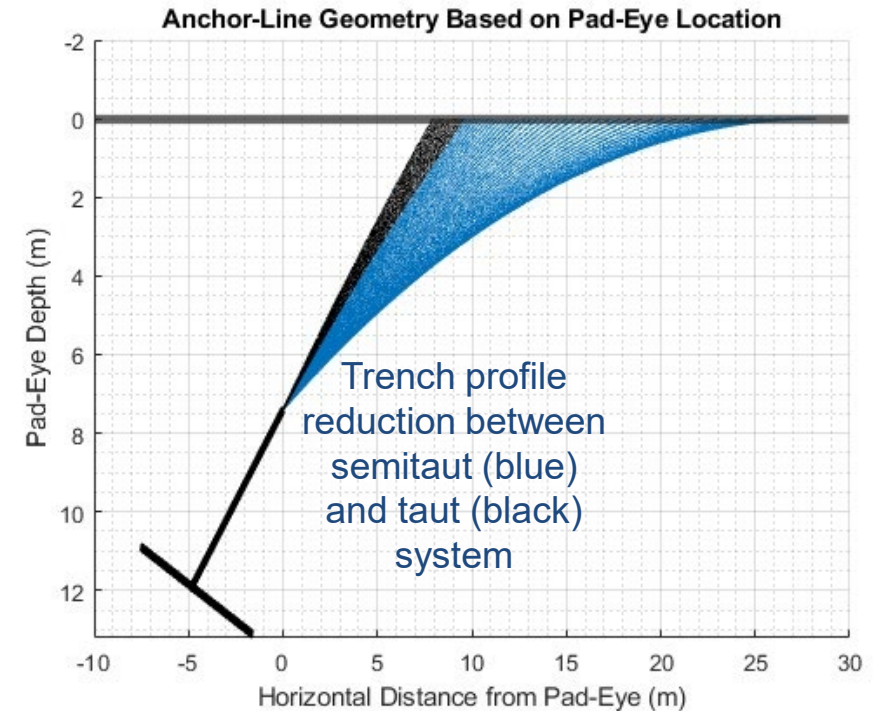


Additional Impact:

Biofouling of mooring lines, additional drags on infrastructure and new hard substrate presents potential for island effect.

Potential floating offshore wind environmental impacts (figure from Maxwell et al. 2022).

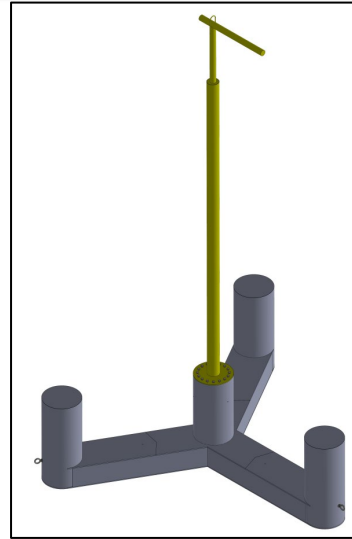
- Trenching impacts are reduced from 275 m³ to 50 m³ per mooring between semi-taut and taut systems (825 m³ vs. 300 m³ total)
- Anchor impact of 790 m³ over 3 anchors vs. 1590 m³ over 6 anchors
- Surface sediment (biologically active) impacts are reduced while deep sediment (not biologically active) impacts are consistent

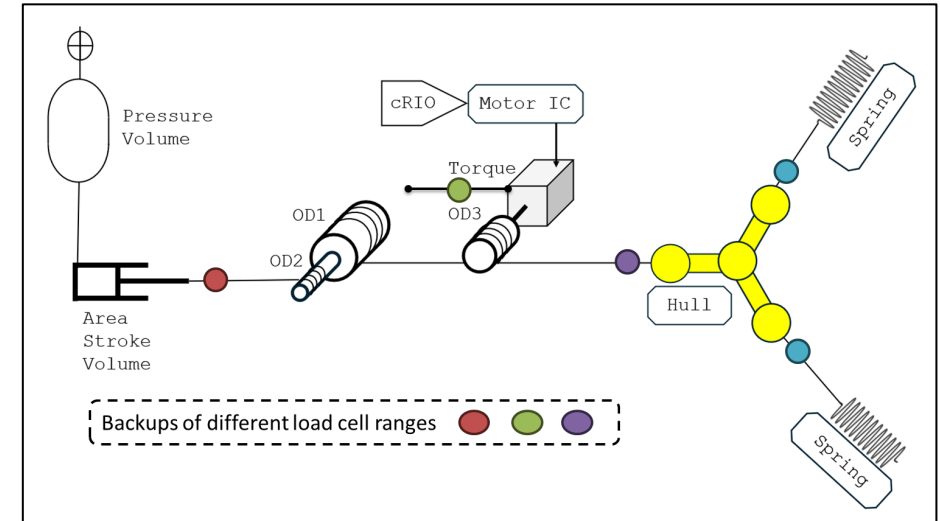
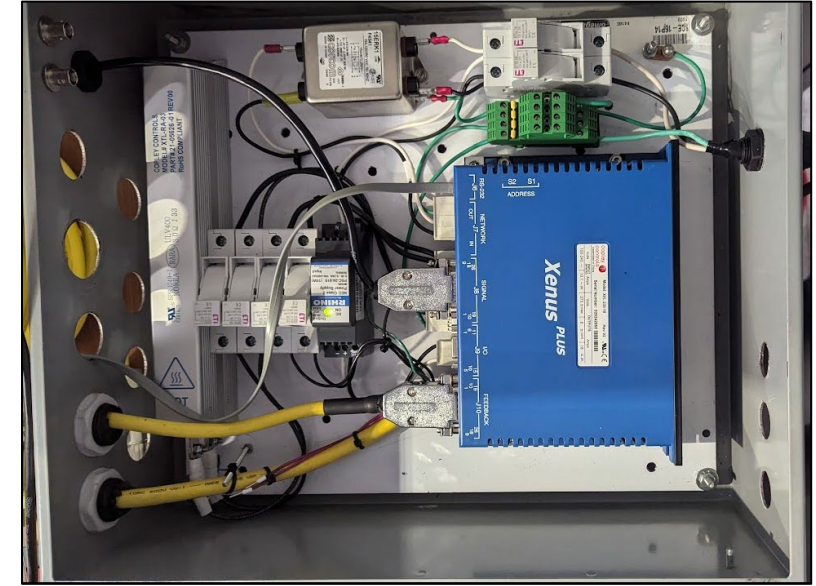
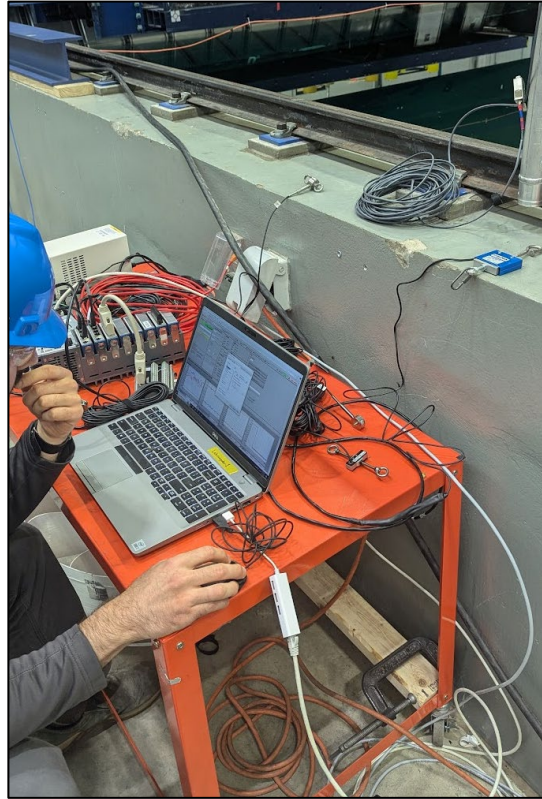


General System	Full Scale	Test Scale	Units
Hull Displacement	31678	0.3319	m ³
Total Mass	31857724	333.78	kg
CGx	-0.326629323	-0.007	m
CGz	17.69	0.387	m
Ixx	84568506706	424.26	kg m ²
Iyy	84337872499	423.10	kg m ²
Izz	66907031143	335.65	kg m ²

RNA	Full Scale	Test Scale	Units
Hub height	189.23	4.14	m
RNA mass	1207946.484	12.66	kg
CGx	-8.614344308	-0.188	m
Cgy	-0.11	-0.002	m
CGz	189.7	4.15	m

Tower	Full Scale	Test Scale	Units
Tower Length	149.4	3.27	m
Tower mass	1586518.217	16.62	kg
CGz	97.1	2.125	m

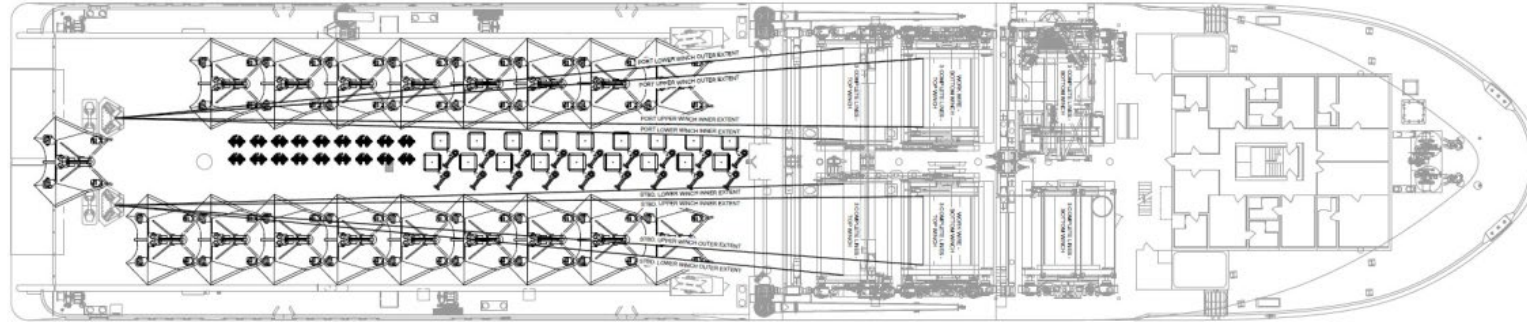




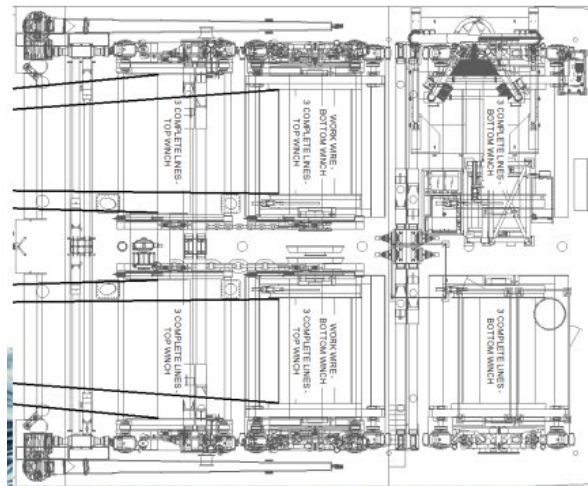
Mooring Line Components

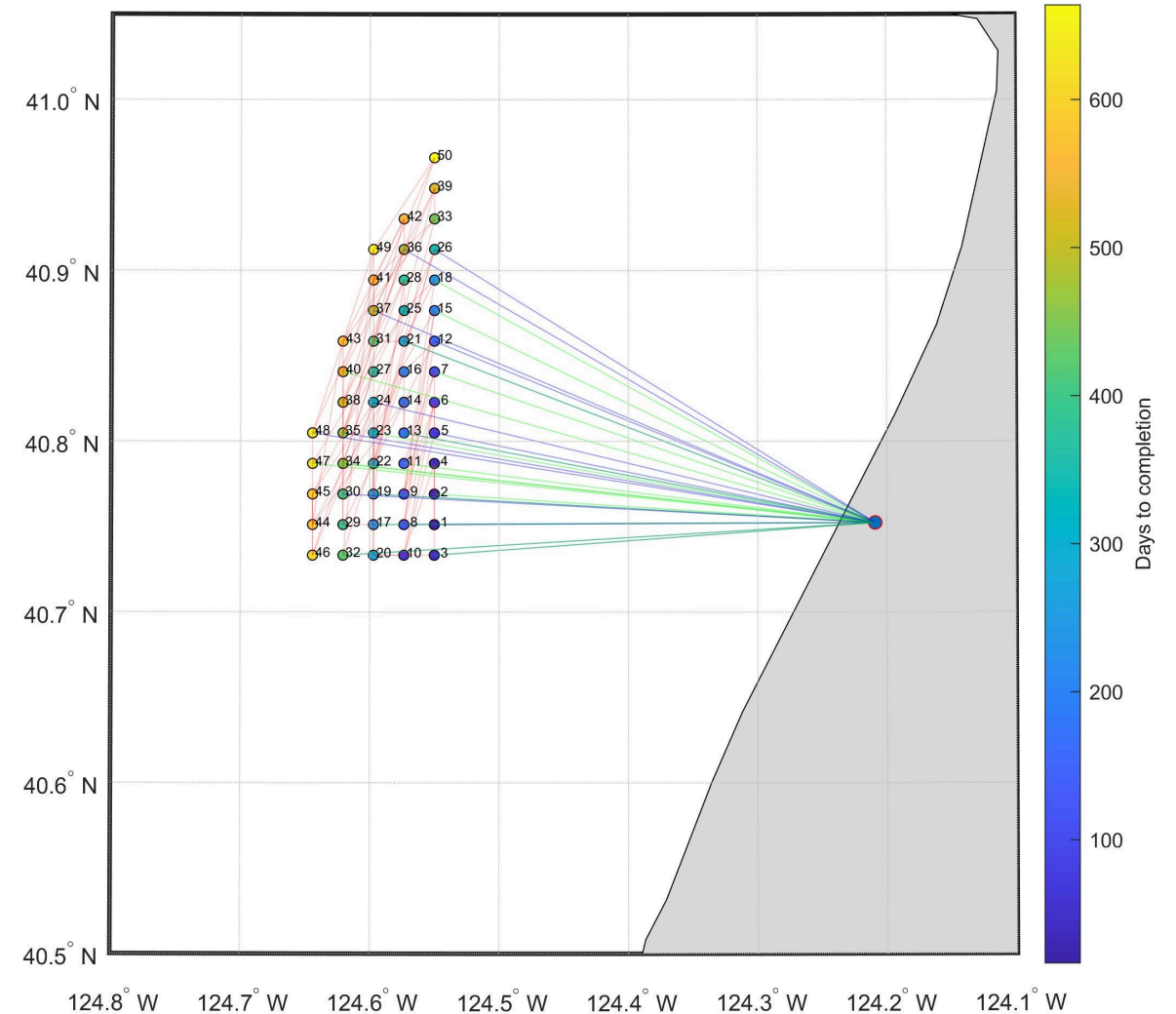
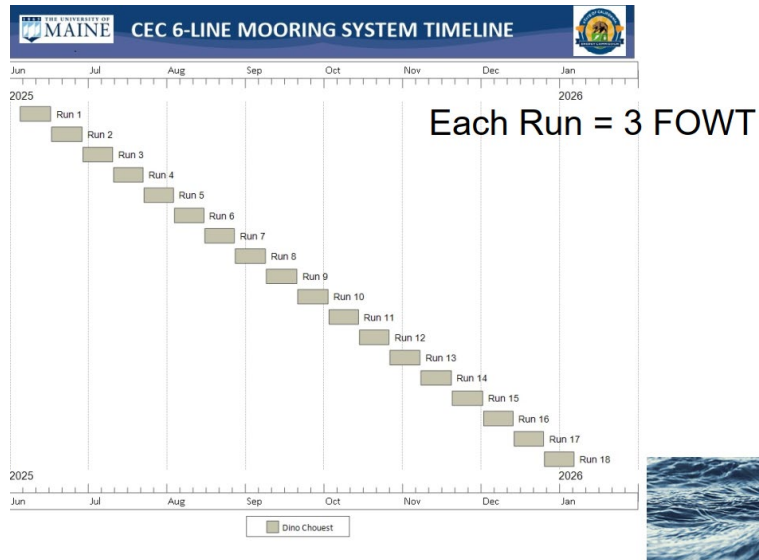
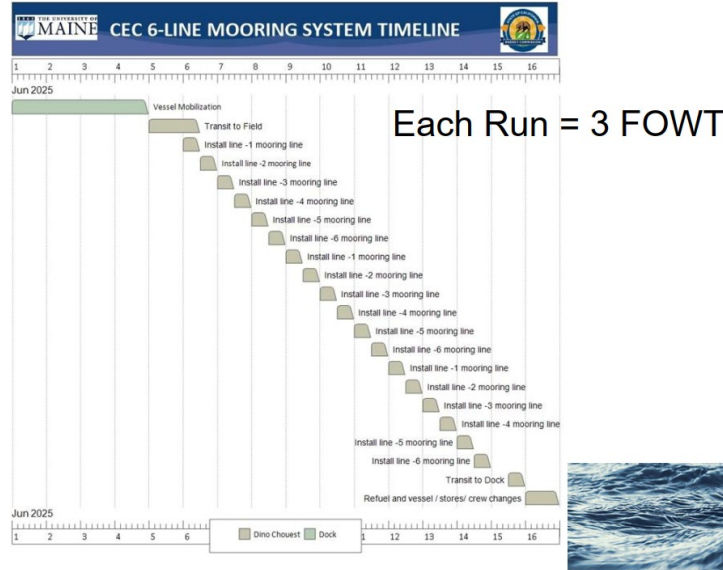


Dino – Deck Layout




QTY18 - 20 sq. m Stevmantas
QTY18 - Subsea Connectors
QTY18 - Complete Mooring Lines





- 1:47 Scale basin test of 22 MW turbine with active control mooring system
- Finalized install, commissioning, decommissioning plan, mooring integrity management report, risk workshop
- Environmental risk analysis
- 50% FEED design of mooring system incorporating learnings from all the above
- ABS AIP



1:4 scale VoltturnUS+ under construction.
Will be deployed with fully redundant
nylon semi-taut mooring system.

- Katherine Greenwald, Matthew Haro, Mark Danielson and CEC team
- Technical Advisory Committee
- Jack Clark, Everett Rzeszowski, Damian Brady, Nathan Faessler and the rest of the UMaine team
- Delmar, Bridon and ABS teams

Mooring Sensors for Environmental Awareness (MoorSEA) Project Updates

Environmental Data Memo and Simulation Modeling
- Progress to Date -

Presenters:

Greyson Adams – *Schatz Center*

Erica Escajeda, Ph.D. – *H.T. Harvey & Associates*



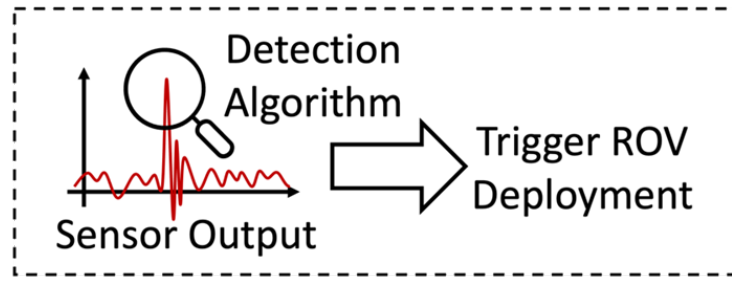
H. T. HARVEY & ASSOCIATES

Ecological Consultants

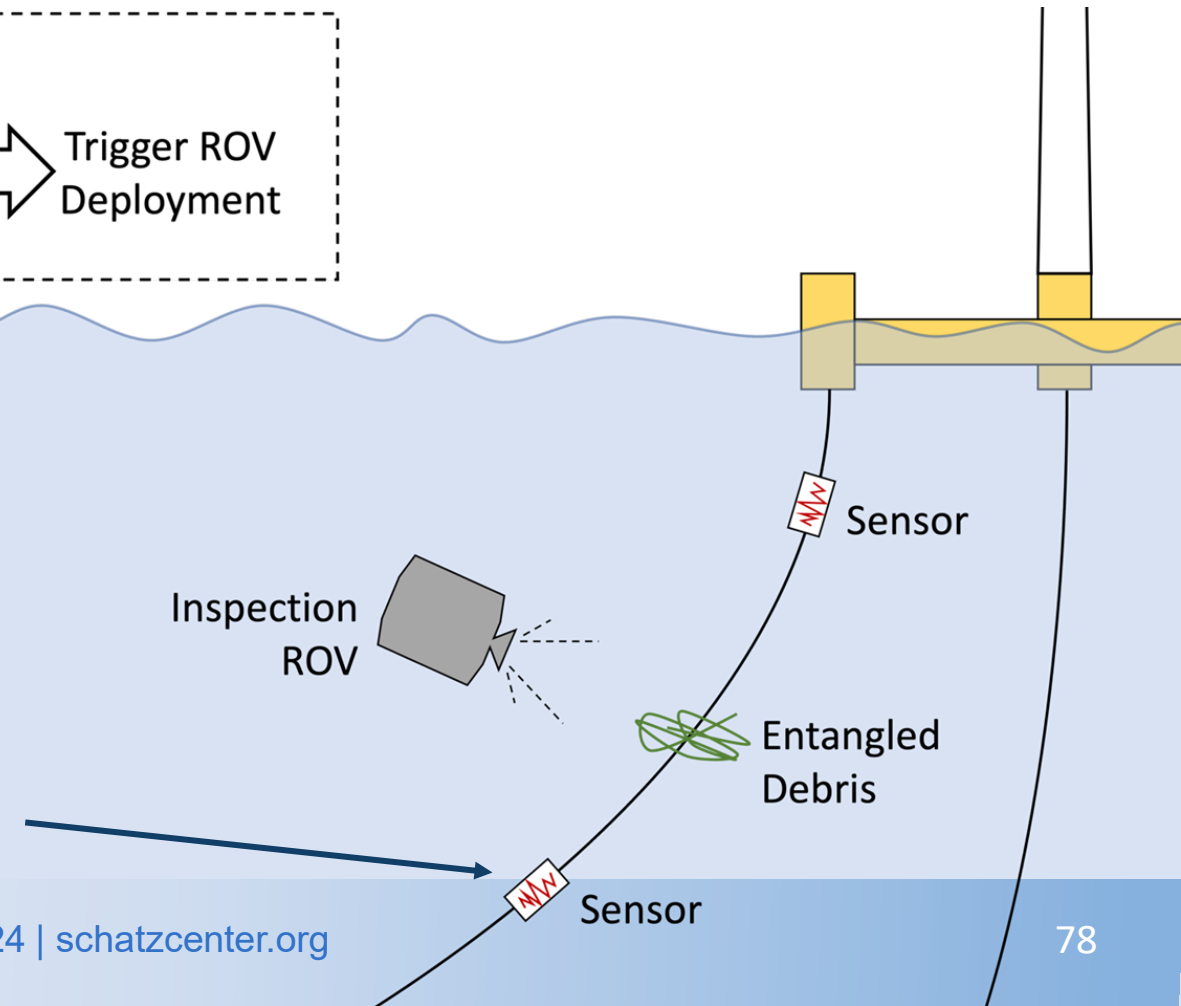
<http://schatzcenter.org/wind/> - <https://www.harveyecology.com/>

Mooring Sensors for Environmental Awareness (MoorSEA)

A potential monitoring solution



- 1) Model baseline and entanglement scenarios
- 2) Develop detection sensor package
- 3) Detection algorithm identifies entanglement
- 4) System notifies human operator
- 5) Operator dispatches inspection ROV



Entanglement and Floating Offshore Wind

Secondary Entanglement



Marine life becoming entangled with marine debris that is snagged on a mooring line or inter-array cable.

Floating Offshore Wind Installations

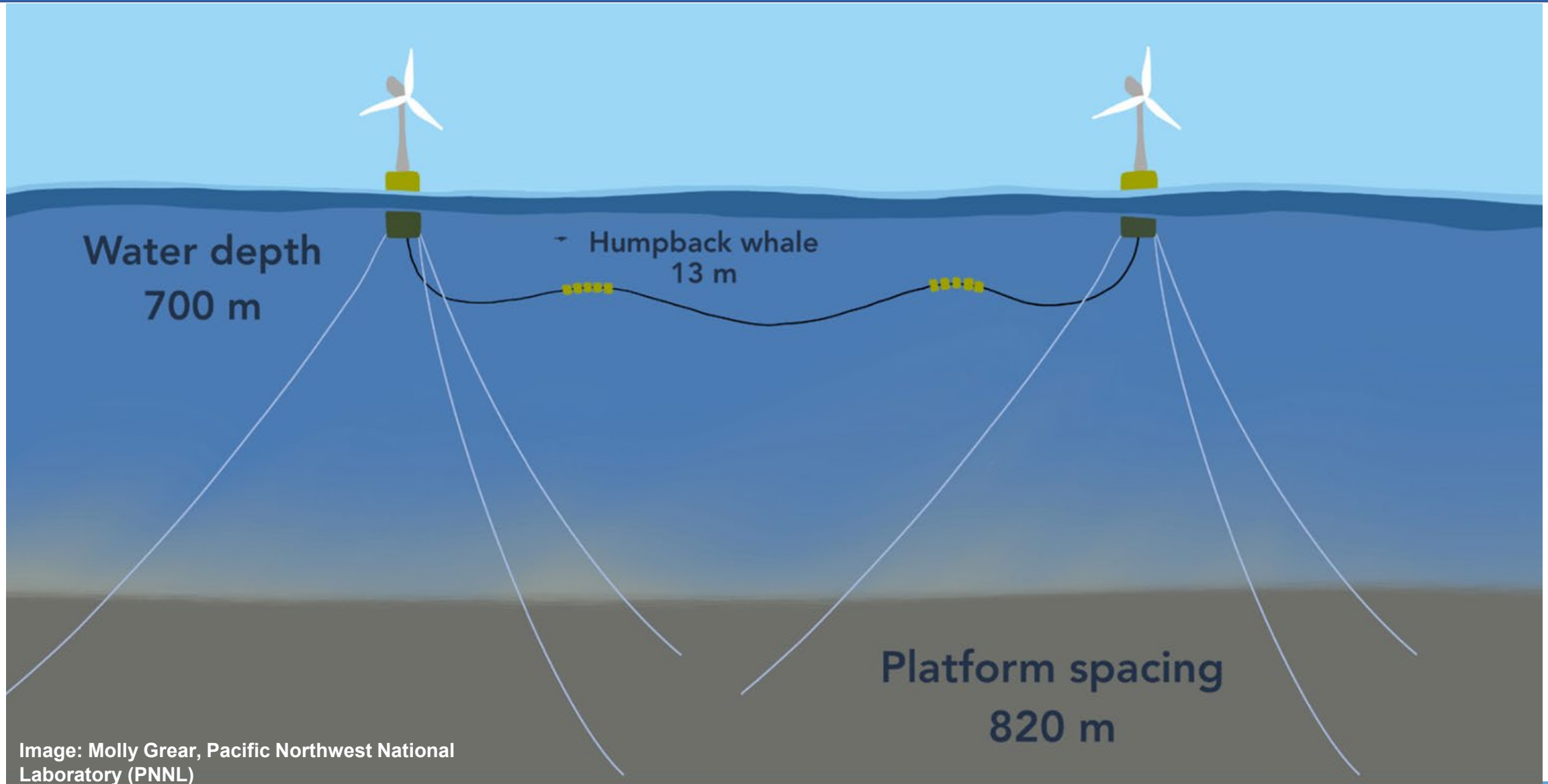
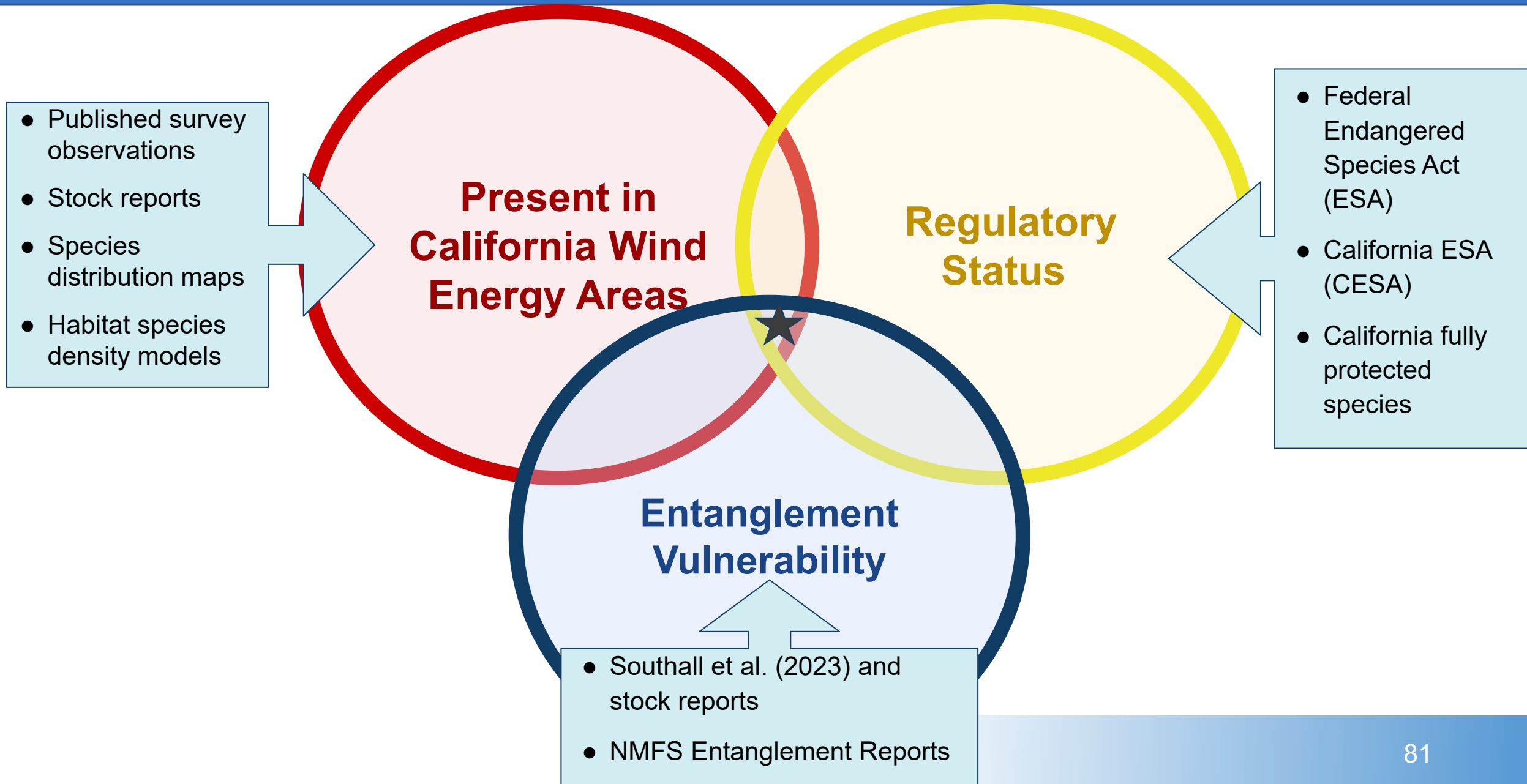


Image: Molly Gear, Pacific Northwest National Laboratory (PNNL)

Key Species Selection Process



Selected Key Species

Baleen Whales

Humpback Whale



Blue Whale



Pinnipeds

California Sea Lion



Northern Elephant Seal



Toothed Whales & Dolphins

Killer Whale



Sperm Whale



Pacific White-Sided
Dolphin



Marine Reptiles

Leatherback Turtle



Fishing Gear and Other Marine Debris

Goal: identify the **types of fishing gear and other debris that are most likely to become entangled with FOSW infrastructure** on the U.S. West Coast

No information on gear/debris entanglement on offshore infrastructure so we examined reports on marine mammal entanglements with fishing gear

The following gear types are most often involved in reported entanglement events:

- Crab pots
- Longline gear
- Drag nets

**Efforts to collect info on fishing gear and other marine debris are ongoing*



Force Calculations

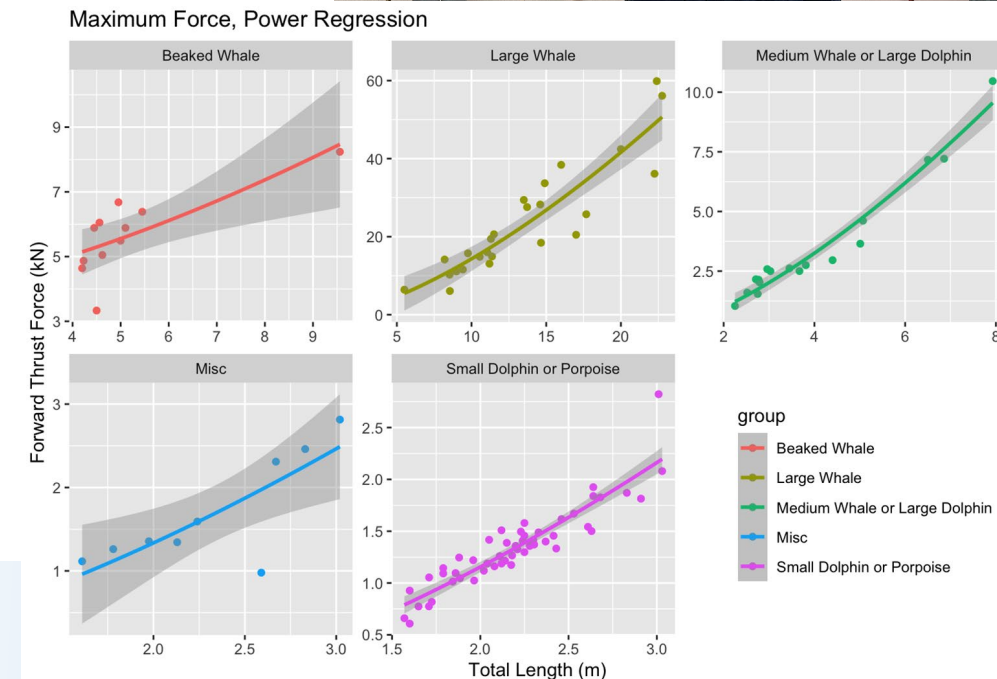
Goal: estimate **minimum and maximum force of each megafauna species** to inform entanglement modeling efforts

Methods:

1. Measure the cross-sectional area of the largest vertebrae → gives low and high force estimates for the measured individual (Arthur et al. 2015)
2. Measure length of that individual
3. Model relationship between length and force for each size class using linear and power regression



Graduate student researcher Ben Prigdonoff holding whale vertebrae



Modeling Results – Current & Ongoing

11.48 HydroStat Baseline 1 hour sim (modified 10:50 AM on 9/9/2024 by OrcaFlex 11.4d)
Replay time: 8000.000s

OrcaFlex 11.4c: Moor 3 Plus X sim (modified 3:12 PM on 9/21/2024 by OrcaFlex 11.4d)
Replay time: 8000.000s

Baseline Conditions/No Entanglement:

Wave Spectrum: JONSWAP

Significant Wave Height: 2.3 meters (m)

Zero-Crossing Period: 5.9 seconds (s)

Wind Speed: 10 m/s

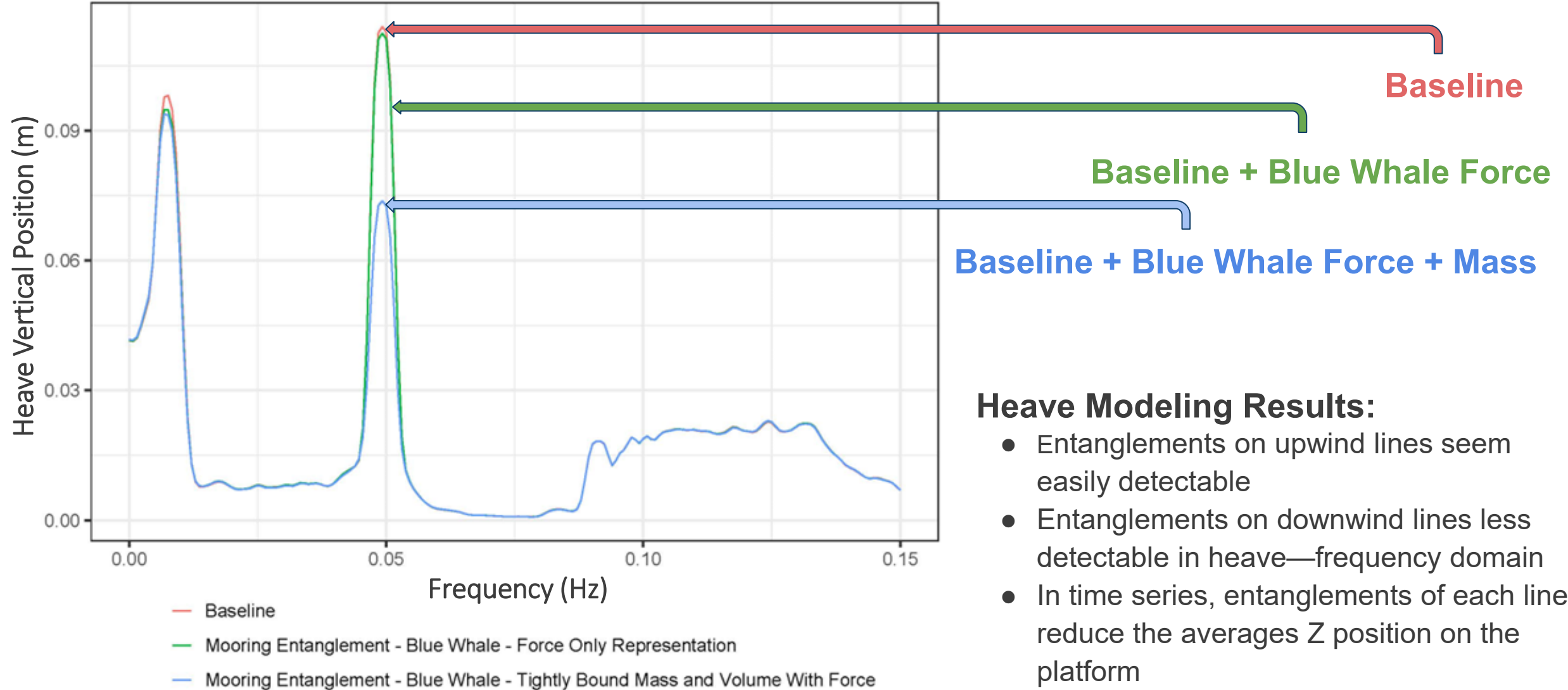
Baseline Conditions + Entanglement Scenario:

Force of 48.6 kN Applied in the (+)X Direction on the Downwind Mooring Line at a Depth of 100 m

Simulation Setup:

- 15-MW reference wind turbine on top of an UMaine's VoltturnUS-S semi-submersible platform
- Semi-taut mooring system configuration, materials include chain fairlead sections and polyester mooring lines

Modeling Results – Current & Ongoing



Heave Modeling Results:

- Entanglements on upwind lines seem easily detectable
- Entanglements on downwind lines less detectable in heave—frequency domain
- In time series, entanglements of each line reduce the averages Z position on the platform

Looking Forward

Next Steps:

1. Complete sensitivity analyses
2. Finalize primary entanglement modeling and simulations
3. Continue collaboration with PNNL to finalize variables of interest and identify sensors
4. Refine dynamic animal entanglement scenario models and finalize a simplified model

Thank You!

Project Sponsor:



CALIFORNIA
ENERGY COMMISSION

Agreement No. EPC-23-006



Full report expected early 2025:

<https://schatzcenter.org/publications/>

Project Team:

Schatz Team: Arne Jacobson (Lead), Greyson Adams (Project Manager), Charles Chamberlin, Maia Cheli, Maysam Mousaviraad, Eli Wallach, Ben Pridonoff, Ben Hung, Zane Husome, Elias Henderson. **H.T. Harvey Team:** Sharon Kramer, Erica Escajeda.



CAL POLY
HUMBOLDT

Project Partners:



H. T. HARVEY & ASSOCIATES
Ecological Consultants





TRITON ANCHOR™

November 5th, 2024 CEC FOSW Project Webinar
Zachary Miller – CTO

Advanced Anchoring System for California Floating Offshore Wind



Company introduction

We team up with leaders across the industry to advance technologies and derive innovations that are practical and target the pain points of the renewable space



Headquartered in Massachusetts, USA
with additional offices in NY, PA, RI, and TX

Our Mission is to provide cost effective anchoring systems and subsea technologies to the offshore renewable energy industries that are environmentally friendly and enable innovation across the value chain

Programs & grants



U.S. DEPARTMENT OF
ENERGY



**NATIONAL
OFFSHORE WIND**
RESEARCH & DEVELOPMENT CONSORTIUM



MASSACHUSETTS
**CLEAN ENERGY
CENTER**



CALIFORNIA
**ENERGY
COMMISSION**



Ocean Energy
Safety Institute



TEAMER
Testing & Expertise for Marine Energy

MOUs, partners, & collaborators



ABS



INTERMOOR



CROWLEY



TECHNIP
ENERGIES

UC DAVIS

CENTER FOR
GEOTECHNICAL MODELING



TEXAS A&M UNIVERSITY



THE
UNIVERSITY
OF RHODE ISLAND



University of
Massachusetts
Amherst



Katapult



RICE | ALLIANCE
Rice Alliance for Technology and Entrepreneurship



CALWAVE



Glosten



Triton Systems
Driven to Innovate



**HALEY
ALDRICH**



TRITON ANCHOR



Project Purpose

Develop an economically responsible and ecologically mindful anchor solution for California's floating offshore wind industry. This anchor solution will be **tailored to California's dynamic seismic environment** with a key focus on **ensuring local manufacturability**.

1. An efficient and proven anchor design based on site-specific soil data and seismic ground models from the California Wind Energy Areas (WEA) to optimize the use of material and configuration to best suite California's environmental and supply chain parameters.
2. A cost-effective, high-uplift capacity anchoring solution that gives developers and platform designers the ability to utilize taut, tension leg, and shared anchoring systems instead of large footprint catenary configurations that interfere with fishing and transportation industries and can disturb much of the seafloor.
3. A modular fabrication system to strengthen the local supply chain and labor industries with the ability to manufacture and assemble the anchors within California and the rate payer's regions.
4. An ecologically responsible, virtually silent installation methodology to enable more cost-effective installation practices with less interference with local and migrating marine life.



Program Objectives & Goals

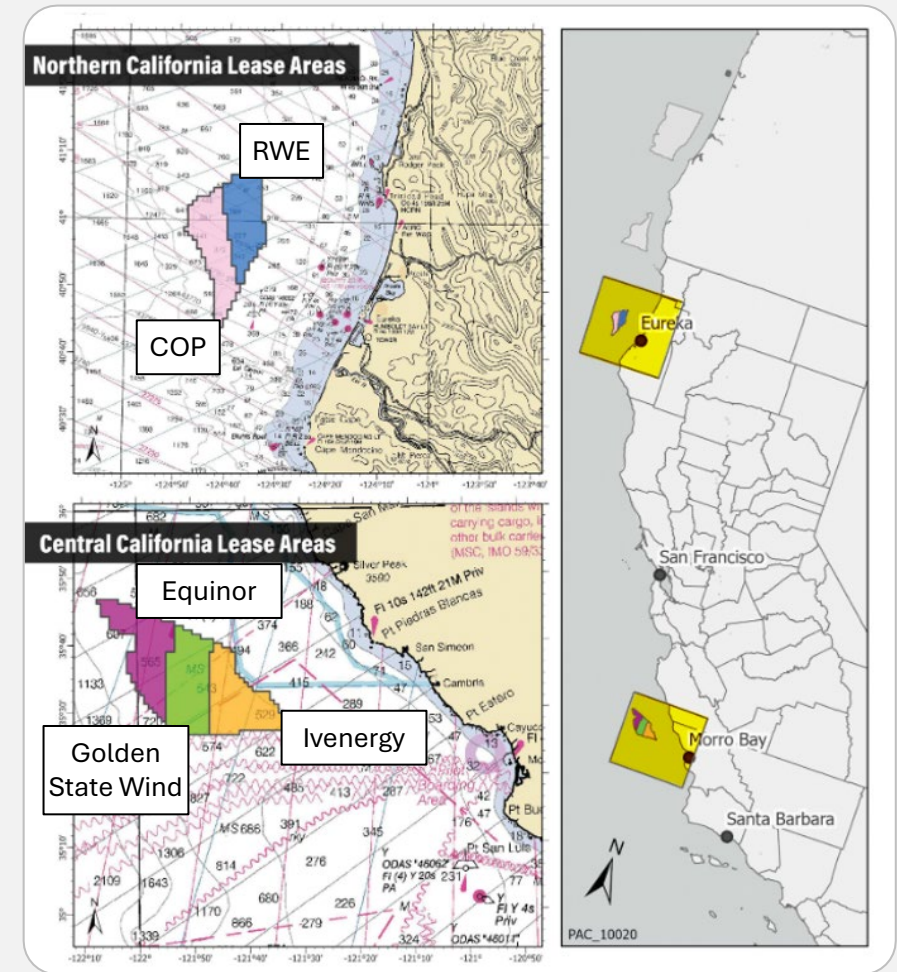
1. Determine site-specific offshore geotechnical conditions with offshore investigation.
2. Identify, evaluate, and map marine life and habitats most critical to offshore anchor installations and operations for floating wind.
3. Identify, evaluate, and map information related to seismic hazards with respect to anchoring systems.
4. Determine liquefaction susceptibility of the offshore soils and site-specific response spectrum.
5. Develop anchor designs with reduced seabed space and shared mooring spreads.
6. Design site specific anchor designs validated through centrifuge testing and finite analysis modeling.
7. Create a feasible supply chain roadmap and local community's benefits summary.



Task 2 – Geotechnical Investigation

Desktop study & In-field Offshore Campaign

- **Desktop study of Geotechnical Properties**
 - Soil composition
 - Seismic Events
- **In-field Geotechnical Investigation Campaign**
 - Cone Penetration Testing (CPT) to determine soil strength and layers
 - Shear Wave Velocity Measurements to determine seismic effects on soil make-up

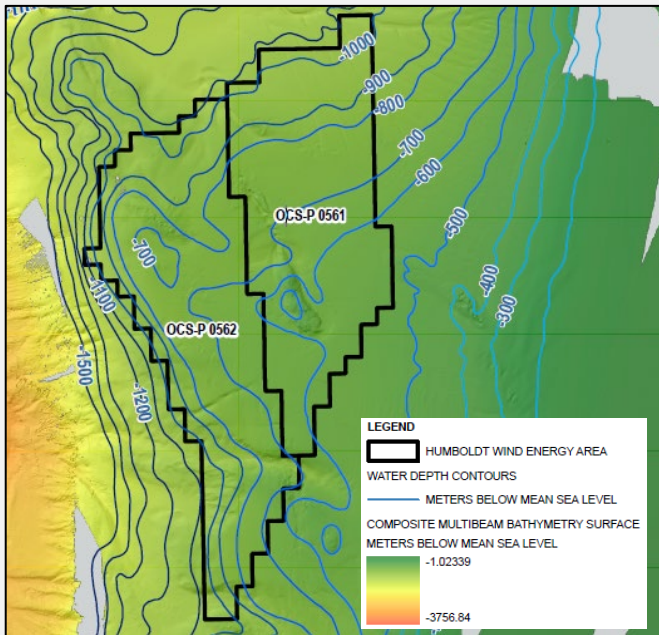




Task 2 – Geotechnical Investigation

Water depth and bathymetry

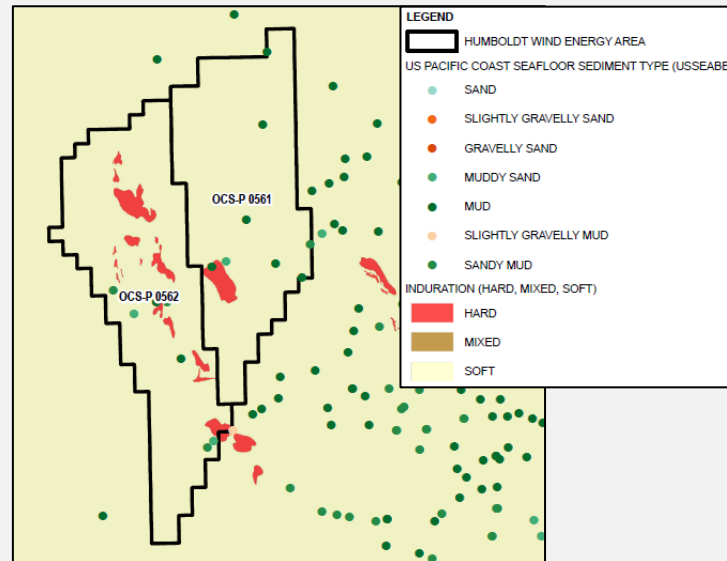
- **Water Depth:** Approximately 500 to 1,100 meters (1,640 to 3,609 feet)
- **Seafloor Slope:** 0 to 10 degrees, with localized slopes over 20 degrees



Summary of Humboldt WEA

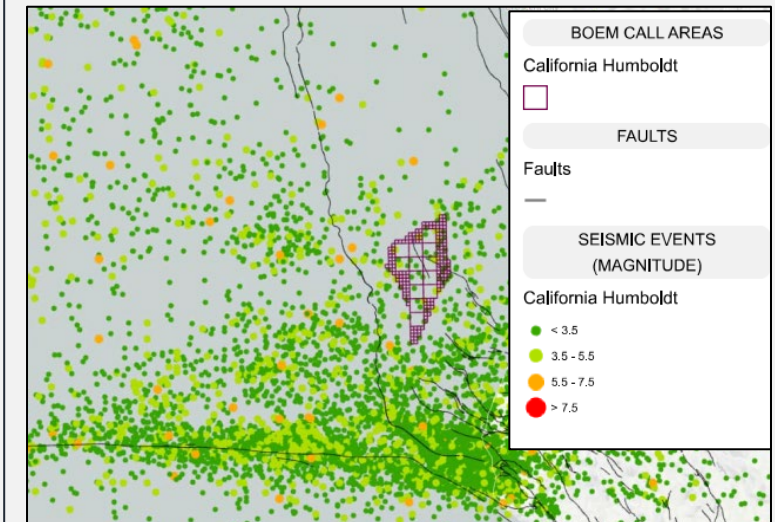
Sediment type

- **Sediment Type:** Mostly soft sediment ("mud") with localized hard areas (rock, outcrops, boulders)
- **Sediment Depth:** Greater than 500 feet



Seismic events

- **Faults:** ~10 mapped fault segments within the WEA
- **Seismic Activity:** Frequent low-magnitude events
- Low Liquefaction Risk



NOTES

ALL LOCATIONS AND DIMENSIONS ARE APPROXIMATE. SOURCE: CALIFORNIA OFFSHORE WIND ENERGY GATEWAY (<https://caoffshorewind.databasin.org/>). BACKGROUND SOURCE: ESRI. COMPOSITE MULTIBEAM BATHYMETRY SURFACE AND DATA SOURCES: 2018 AND 2019 MULTIBEAM DATA COLLECTED BY THE NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION (NOAA) AND THE U.S. GEOLOGICAL SURVEY (USGS). USSEABED SOURCE: <https://www.fisheries.noaa.gov/inport/item/49600>. AERIAL IMAGERY SOURCE: NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION (NOAA). SEAFLOOR INDURATION SOURCE: OREGON STATE UNIVERSITY, ACTIVE TECTONICS AND SEAFLOOR MAPPING LAB (ATSM); NOAA FISHERIES, BUREAU OF OCEAN ENERGY MANAGEMENT. SEAFLOOR INDURATION SOURCE: OREGON STATE UNIVERSITY, ACTIVE TECTONICS AND SEAFLOOR MAPPING LAB (ATSM); NOAA FISHERIES, BUREAU OF OCEAN ENERGY MANAGEMENT.

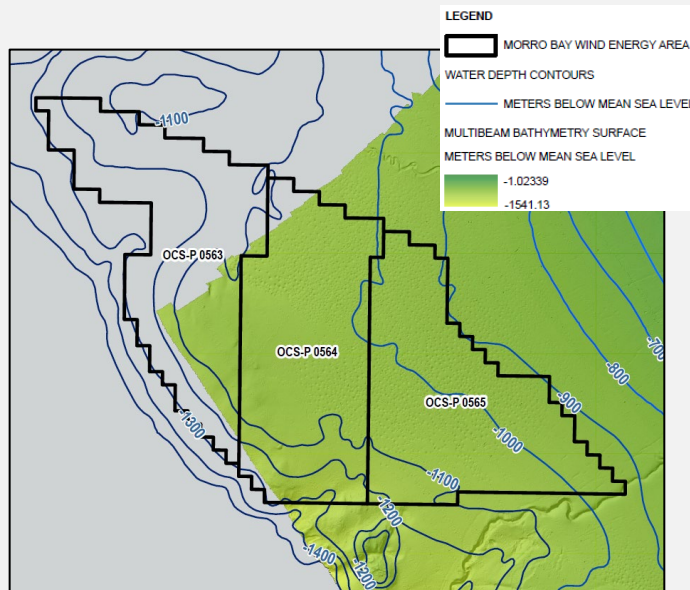


Task 2 – Geotechnical Investigation

Summary of Morro Bay WEA

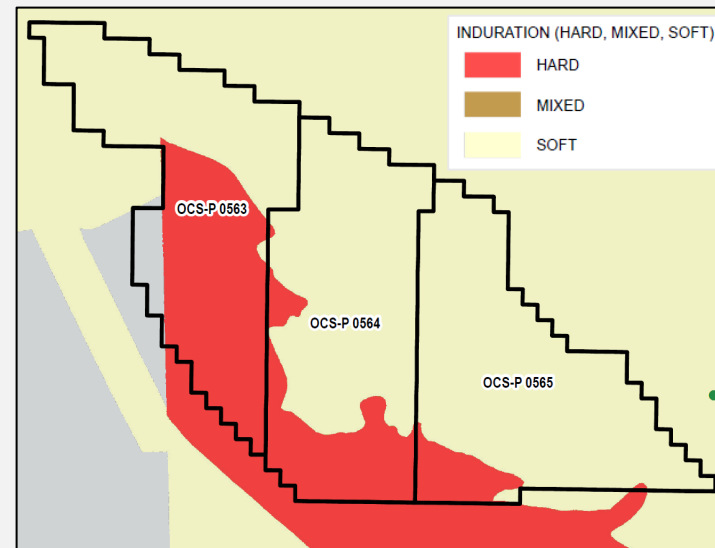
Water depth and bathymetry

- **Water Depth:** Approximately 900 to 1,300 meters (2,953 to 4,265 feet)
- **Seafloor Slope:** 0 to 5 degrees, with higher localized slopes



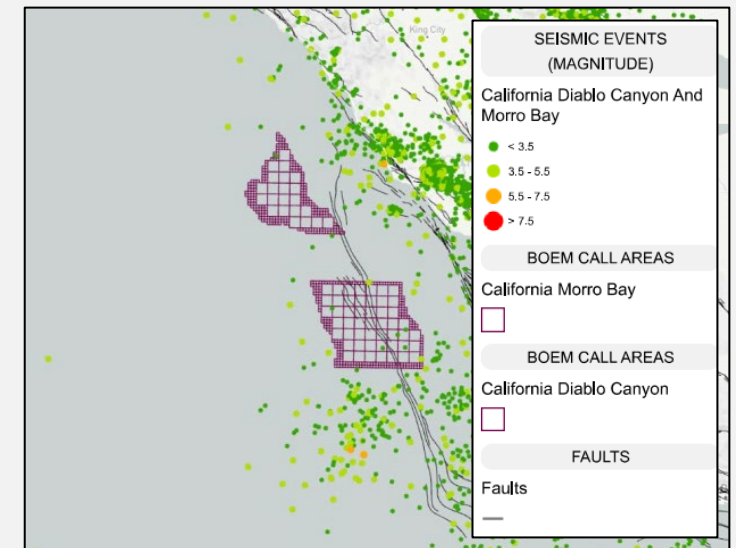
Sediment type

- **Sediment Type:** Mostly soft sediment ("mud") with localized hard areas in southern and western portions
- **Sediment Depth:** Greater than 100 m



Seismic events

- **Faults:** ~6 mapped fault segments within the WEA
- **Seismic Activity:** Within vicinity of Hosgri-San Gregorio Fault system; low-frequency low-magnitude events



NOTES

ALL LOCATIONS AND DIMENSIONS ARE APPROXIMATE.. SOURCE: CALIFORNIA OFFSHORE WIND ENERGY GATEWAY (<https://caoffshorewind.databasin.org/>). BACKGROUND SOURCE: ESRI. USSEABED SOURCE: <https://www.fisheries.noaa.gov/inport/item/49600>. SEAFLOOR INDURATION SOURCE: MONTEREY BAY NATIONAL MARINE SANCTUARY (<https://caoffshorewind.databasin.org/datasets/06ba54fb5f9b4bf2bd75ae85fc5261af/>). AERIAL IMAGERY SOURCE: NATIONAL OCEANIC AND ATMOSPHERIC ADMINISTRATION (NOAA) SEDIMENT THICKNESS SOURCE: NOAA NATIONAL CENTERS FOR ENVIRONMENTAL INFORMATION (NCEI) SEDIMENT THICKNESS MEASURED AS TWO-WAY TRAVEL TIME USING AN ASSUMED SEISMIC VELOCITY OF 2,000 M/S (1 MS = 1 METER)



Task 2 – Geotechnical Investigation

Major Geological Hazard Considerations:

- Ground Shaking
- Liquefaction
- Submarine Landslides
- Tsunamis

Summary:

- Humboldt and Morro Bay deep-water areas mainly consist of fine grained soil and rock material, therefore their potential for liquefaction is considered low.
- Ground motion primarily affects the anchors, which are the embedded portion of the foundation, Nevertheless, the ground shaking hazard needs to be assessed for both northern and southern study areas

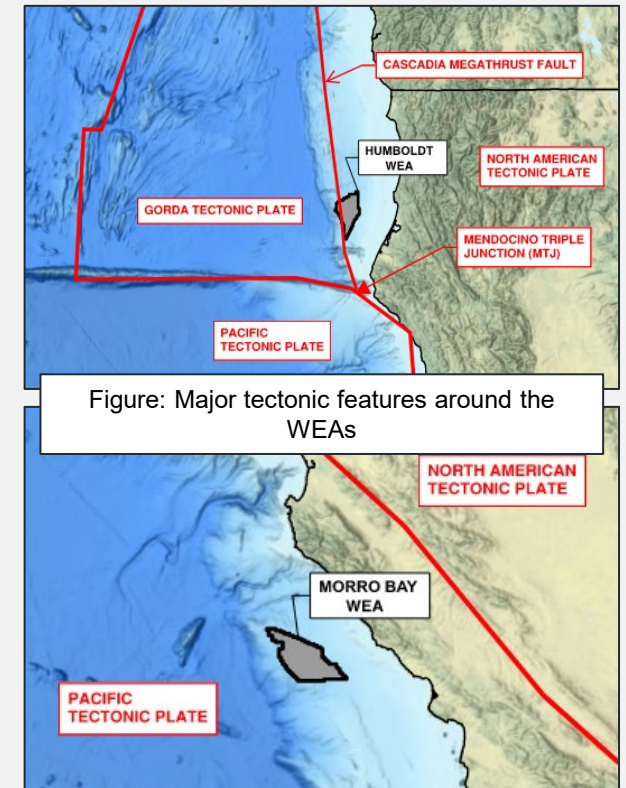
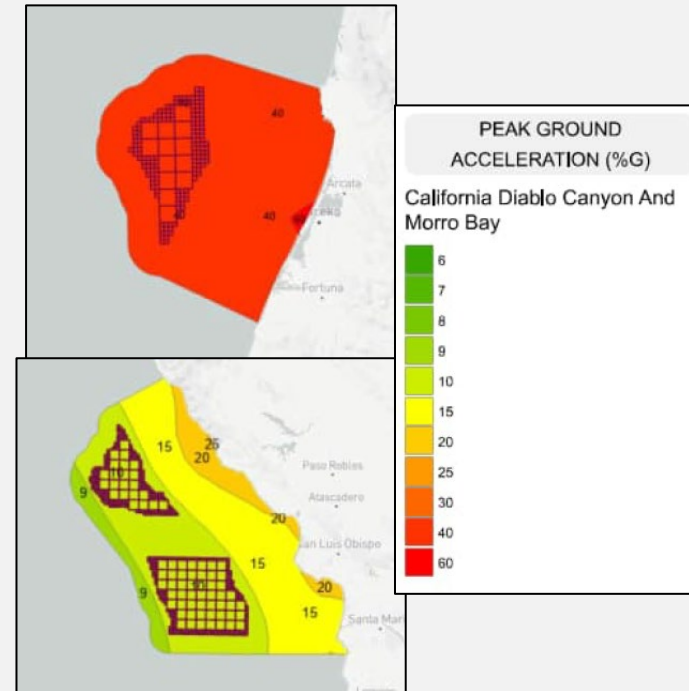


Figure: Major tectonic features around the WEAs

Primary references

- United States Geological Survey (USGS)
- National Oceanic and Atmospheric Administration (NOAA)
- Monterey Bay Aquarium Research Institute (MBARI)
- Bureau of Ocean Energy Management (BOEM)



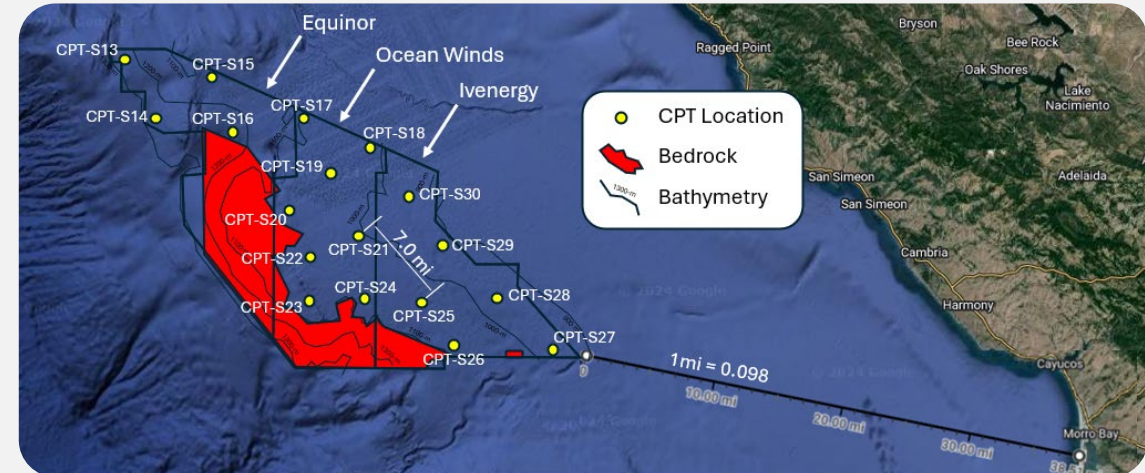
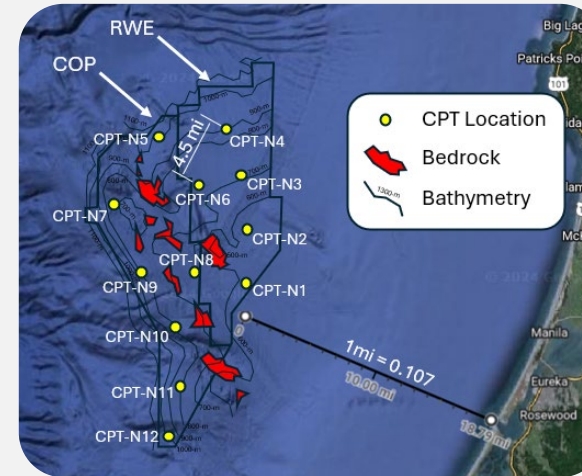
Task 2 – Geotechnical Investigation

Offshore Investigation Planning

Operation Parameters:

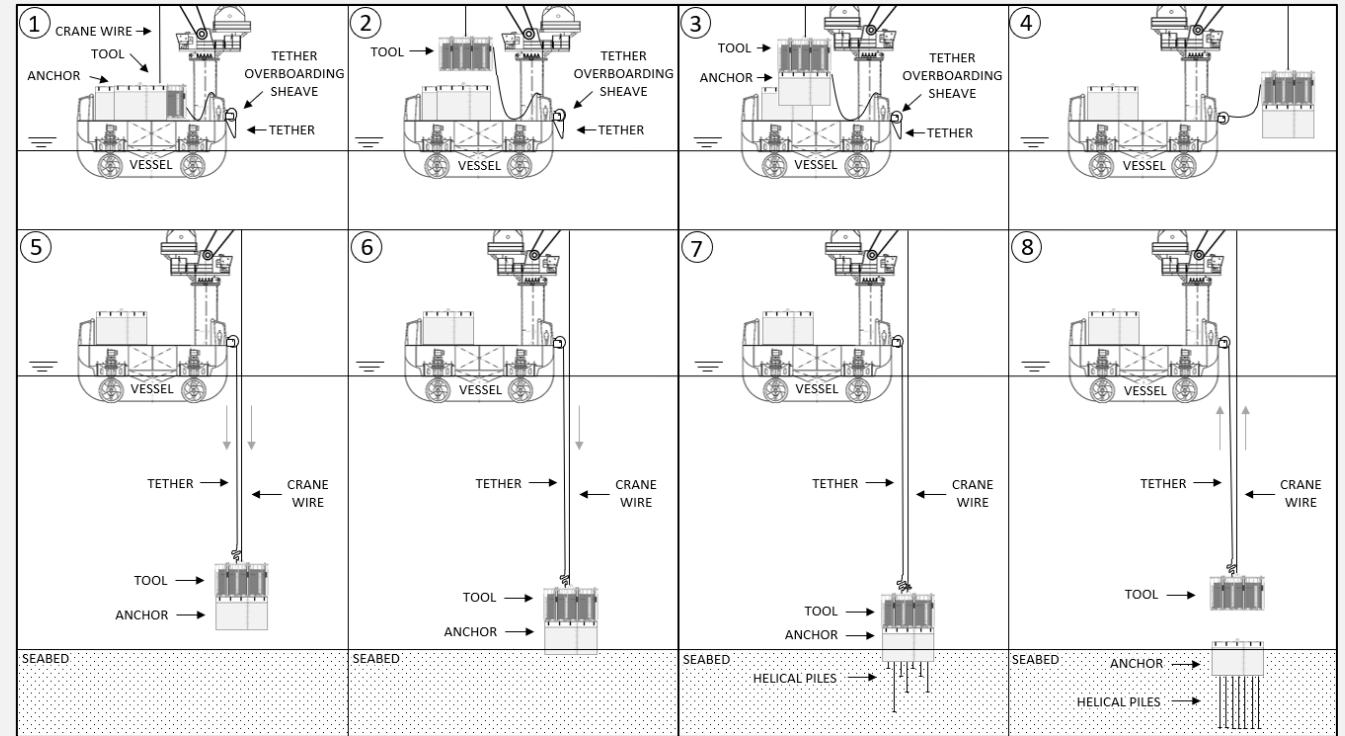
Average CPTs/day [#]:	4
Maximum 'at-depth' transit speed [knots]:	1.5
Maximum 'on-surface' transit speed [knots]:	10
Launch to Depth [hrs]:	2.5
Recovery Time from Depth [hrs]:	2.5
Budgeted Count of Days [days]:	15
Estimated Individual CPT Time [hrs]:	6
Distance from North to South [miles]:	400

Geotechnical Investigation Campaign Scenarios			Number of CPTs	
Scenario	CPT Expectation	Region	North	South
1	Minimum	North & South	12	18
2	Maximum	North & South	17	24
3	Minimum	North	40	-
4	Maximum	North	48	-
5	Minimum	South	-	35
6	Maximum	South	-	44





- Helical piles quantities: 6 to 30
- Helical pile lengths: 7 to 25 meters
- Skirt diameters: 3 to 13 meters
- Skirt lengths: 3 to 10 meters
- Total anchor weights: 3 to 70 metric tons





Task 3 – Marine Life and Habitat Assessment

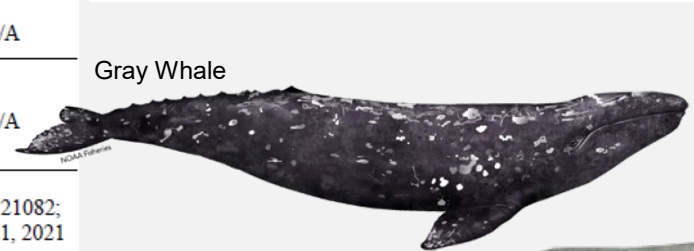
Species and Habitat

Federally listed species and critical habitats that have the potential to be affected by the proposed project are listed below:

Common Name	Scientific Name	Test Sites Present	Status	Final Rule	Critical Habitat in Study Area
Blue whale	<i>Balaenoptera musculus</i>	Morro Bay, Humboldt	EN	35 FR 18319; December 2, 1970	N/A
Fin whale	<i>Balaenoptera physalus</i>	Morro Bay, Humboldt	EN	35 FR 18319; December 2, 1970	N/A
Gray whale Eastern – North Pacific DPS	<i>Eschrichtius robustus</i>	Morro Bay, Humboldt	EN	35 FR 18319; December 2, 1970	N/A
Humpback whale – Mexico DPS	<i>Megaptera novaeangliae</i>	Morro Bay, Humboldt	TH	81 FR 62260; September 8, 2016	86 FR 21082; April 21, 2021
Humpback whale – Central America DPS	<i>Megaptera novaeangliae</i>	Morro Bay, Humboldt	EN	81 FR 62260; September 8, 2016	86 FR 21082; April 21, 2021
Sperm whale	<i>Physeter macrocephalus</i>	Morro Bay, Humboldt	EN	35 FR 18319; December 2, 1970	N/A
Guadalupe fur seal	<i>Arctocephalus townsendi</i>	Morro Bay, Humboldt	TH	50 FR 51252; December 16, 1985	N/A
Leatherback sea turtle	<i>Dermochelys coriacea</i>	Morro Bay, Humboldt	EN	35 FR 8491; June 2, 1970	77 FR 4170 January 26, 2012
North Pacific loggerhead sea turtle DPS	<i>Caretta caretta</i>	Morro Bay	EN	76 FR 58868; September 22, 2011	N/A



Blue Whale



Gray Whale



Fin Whale



Guadalupe Fur Seal



Sperm Whale



North Pacific Loggerhead Sea Turtle

Statuses: DPS = Distinct Population Segment, EN = endangered, TH = threatened, FR = final rule; CH = critical habitat.

Photo Credits to NOAA



Task 3 – Marine Life and Habitat Assessment

Underwater Noise: Sources of underwater noise from the project would be minimal and anticipated to only include **vessels** and **installation of the helical screws**.

- **Installation of the anchor** → Expected to be within the same frequency intensity ranges as geotechnical survey sources (standard penetration tests/cone piezometer tests) which is below the level that would result in injury or behavioral disturbance to any species considered here.
- **Vessels** → Sounds from mobile sources, like vessels, are continuous and, therefore, vessel noise is characterized as a non-impulsive sound source.

Source (Vessel)	Source Level Range (dB re 1 μ Pa SPL _{rms})
Large vessels (149 to 294 feet)	177 to 188
Small support vessels (<100 feet)	150 to 180
Tug	177 to 188

Key: dB re 1 μ Pa SPL_{rms} = decibels relative to 1 micropascal root mean squared sound pressure level

Installation of our Anchor:

Vessel traffic would be minimal as only 1-2 vessels are required to complete the installation of a single anchor.

Installation noise associated with the installation tool will be evaluate, indications show that the noise to be in normal levels

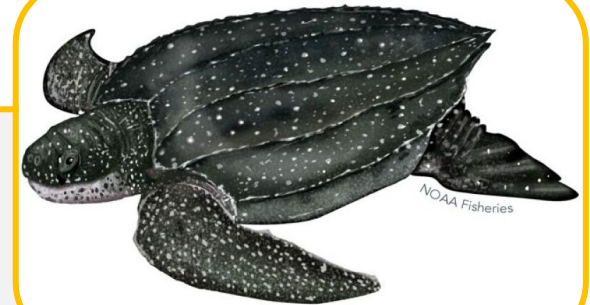


Task 3 – Marine Life and Habitat Assessment

Common name	Scientific name	Determination
Blue Whale	<i>Balaenoptera musculus</i>	NLAA
Fin Whale	<i>Acipenser brevirostrum</i>	NLAA
Gray Whale – Western North Pacific DPS	<i>Eschrichtius robustus</i>	NLAA
Humpback Whale – Mexico DPS	<i>Megaptera novaeangliae</i>	NLAA
Humpback Whale – Central America DPS	<i>Megaptera novaeangliae</i>	NLAA
Southern Resident killer whale	<i>Orcinus orca</i>	NLAA
Sperm whale	<i>Physeter macrocephalus</i>	NLAA
Guadalupe Fur Seal	<i>Arctocephalus townsendi</i>	NLAA
Leatherback Sea Turtle	<i>Dermochelys coriacea</i>	NLAA
Loggerhead Sea Turtle – North Pacific DPS	<i>Caretta caretta</i>	NLAA

Key: NLAA = not likely to adversely affect.

critical habitat species



Following our 3rd party analysis performed by WSP of the silent and precise installation of Triton's helical anchor system;

- All NLAA Marine Wildlife Species = *insignificant impact to habitats*
- Specific NLAA **Critical Habitat** Species = *all effects are extremely unlikely*

Photo Credits to NOAA



Task 4 – Local Communities Impact

Economic Impacts:

Scenario 1: 5GW by 2030

- 334 Platforms --> 1,334 Anchors

	Employment	Labor Income	Value Added	Output
Direct	1,645	\$142,918,417	\$98,398,769	\$253,658,304
Indirect	601	\$54,054,002	\$84,541,684	\$155,058,871
Induced	843	\$60,156,848	\$110,634,420	\$178,360,849
Total	3,089	\$257,129,267	\$293,574,873	\$587,078,024

*Equivalent to 620 workers employed for 5-years

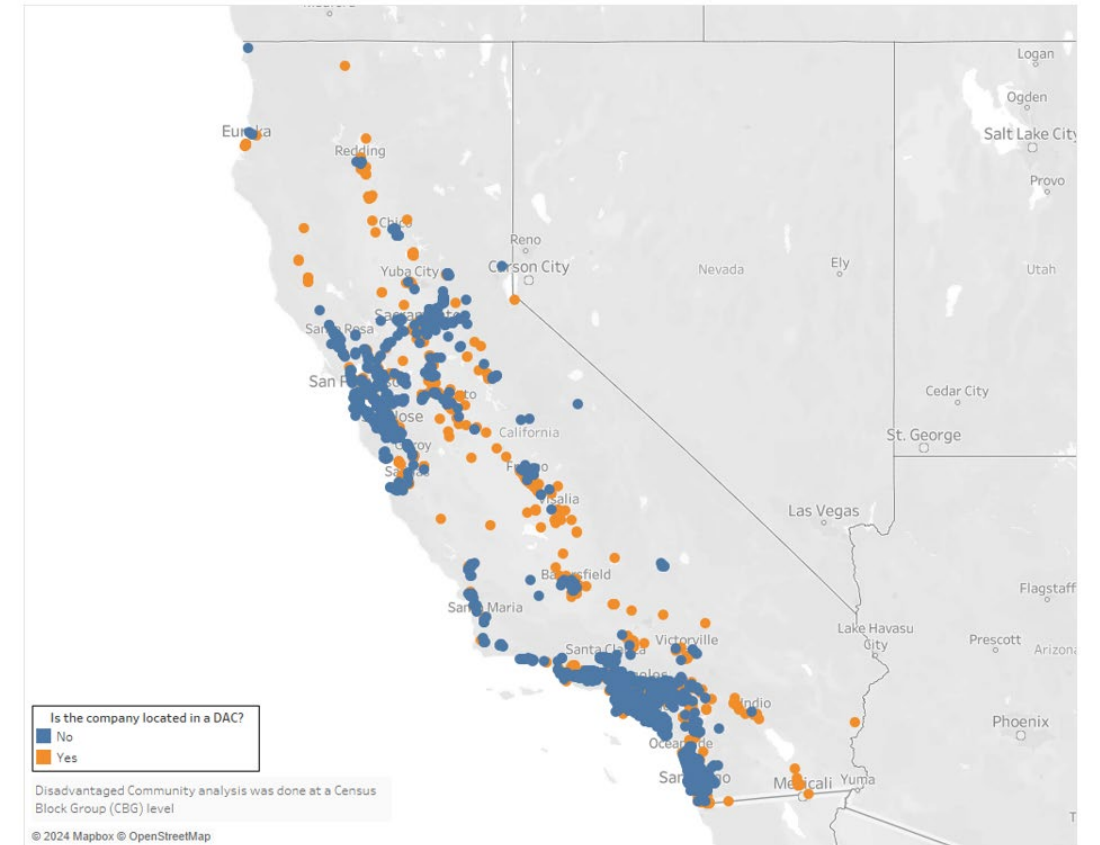
Scenario 2: 25GW by 2045

- 1,667 Platforms --> 6,667 Anchors

	Employment	Labor Income	Value Added	Output
Direct	8,209	\$713,308,385	\$491,110,022	\$1,266,013,152
Indirect	2,998	\$269,784,495	\$421,949,066	\$773,901,609
Induced	4,210	\$300,243,909	\$552,178,377	\$890,202,201
Total	15,417	\$1,283,336,789	\$1,465,237,465	\$2,930,116,962

*Equivalent to 770 workers employed for 20-years

Map of All Relevant Manufacturing Firms



DAC: Disadvantaged Community



Task 7 – Floater Mooring Analysis

Goal: Determine site-specific anchor load cases for semi-submersible (SS) platforms and tension leg platforms (TLPs)

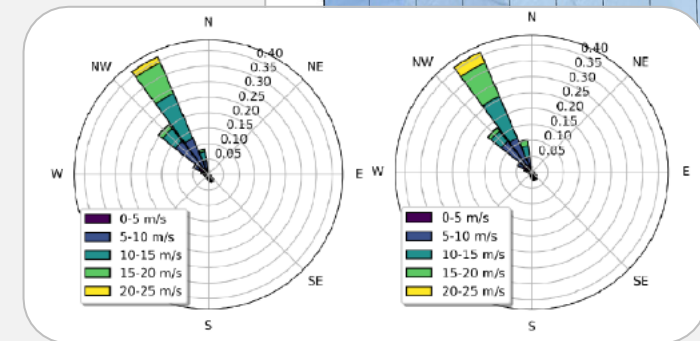
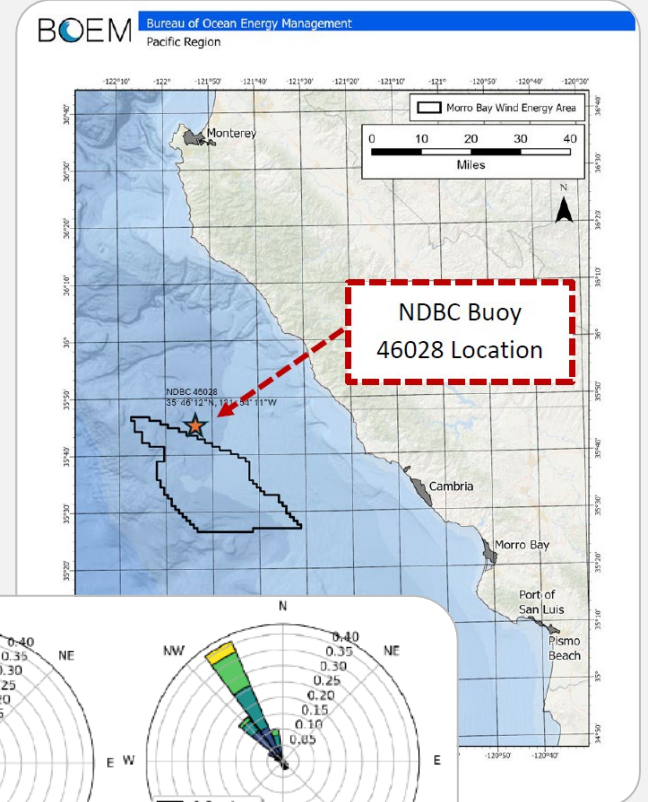
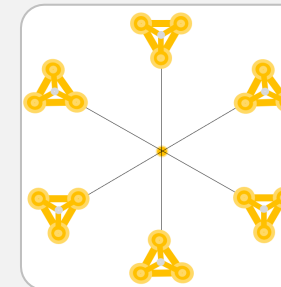
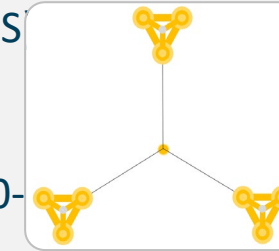
- Assuming an IEA 15-MW turbine semi-submersible platform in 1,000-m WD.

Scenario 1: 3-line shared anchor, 1,500-m line length

Vertical	Horizontal
[kN]	[kN]
16,443	5,518

Scenario 2: 6-line shared anchor, 2,100-m line length

Vertical	Horizontal
[kN]	[kN]
12,762	9,385





Zachary Miller

Email: zmiller@tritonanchor.com

Nathan Krohn

Email: nkrohn@tritonanchor.com

Triton Anchor LLC

330 Billerica Road
Chelmsford, MA 01824

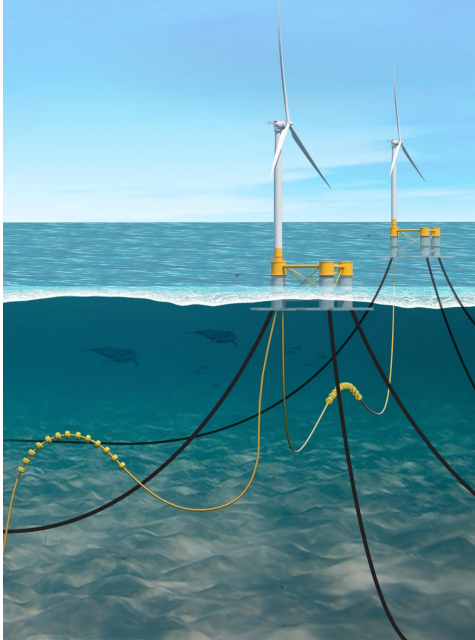




Comprehensive Shared-Mooring Solutions to Minimize the Cost, Risk, and Footprint of GW-Scale Floating Wind Farms

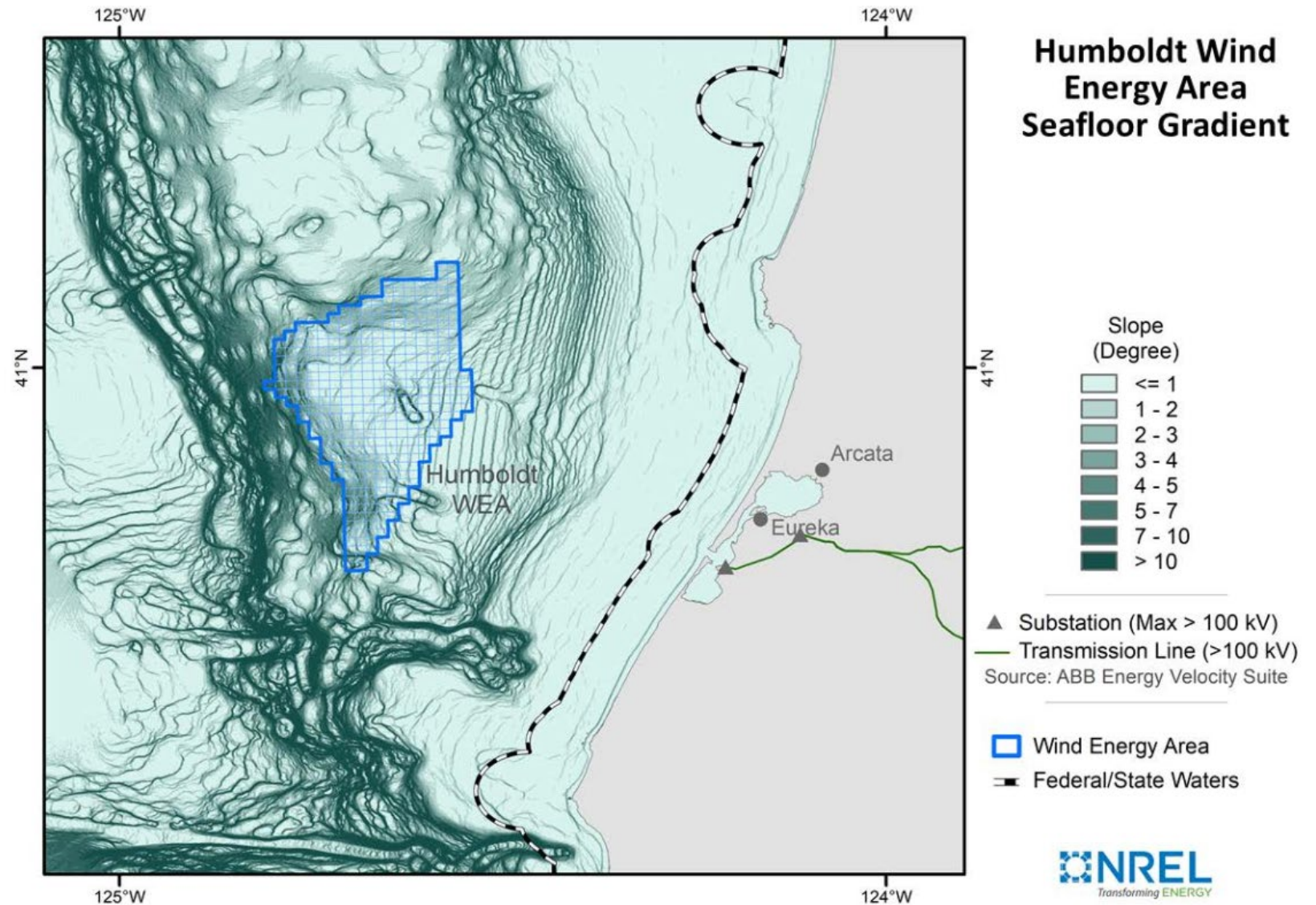
Matt Hall
National Renewable Energy Laboratory
November 5, 2024

Mooring Floating Wind Turbines in California

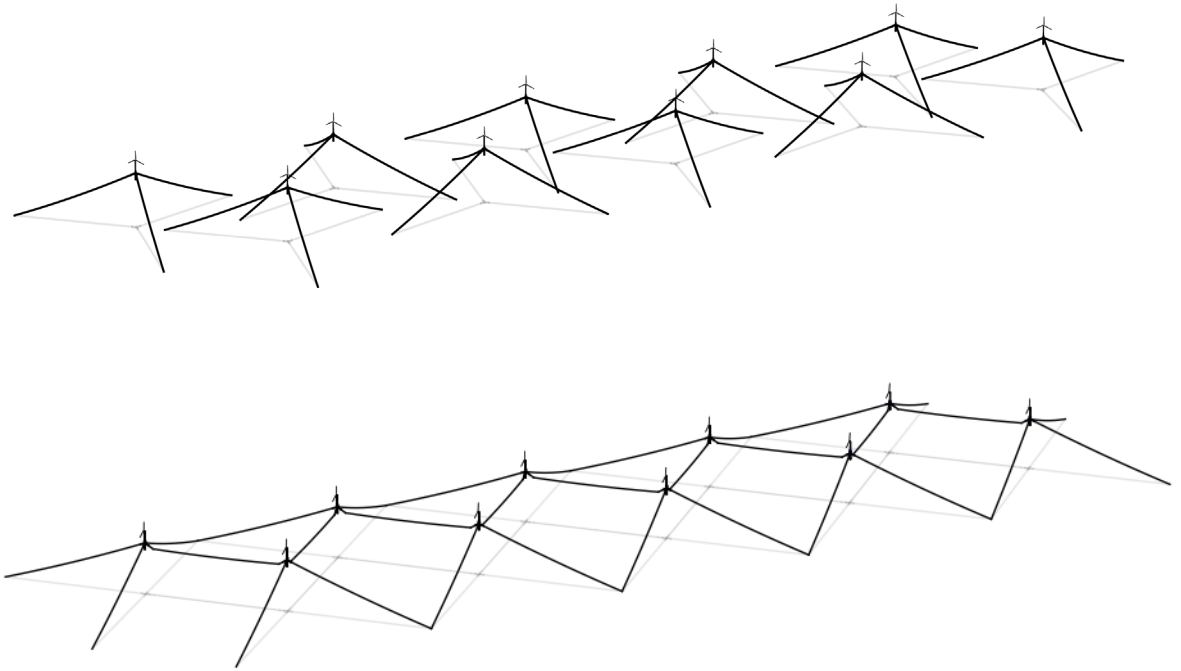
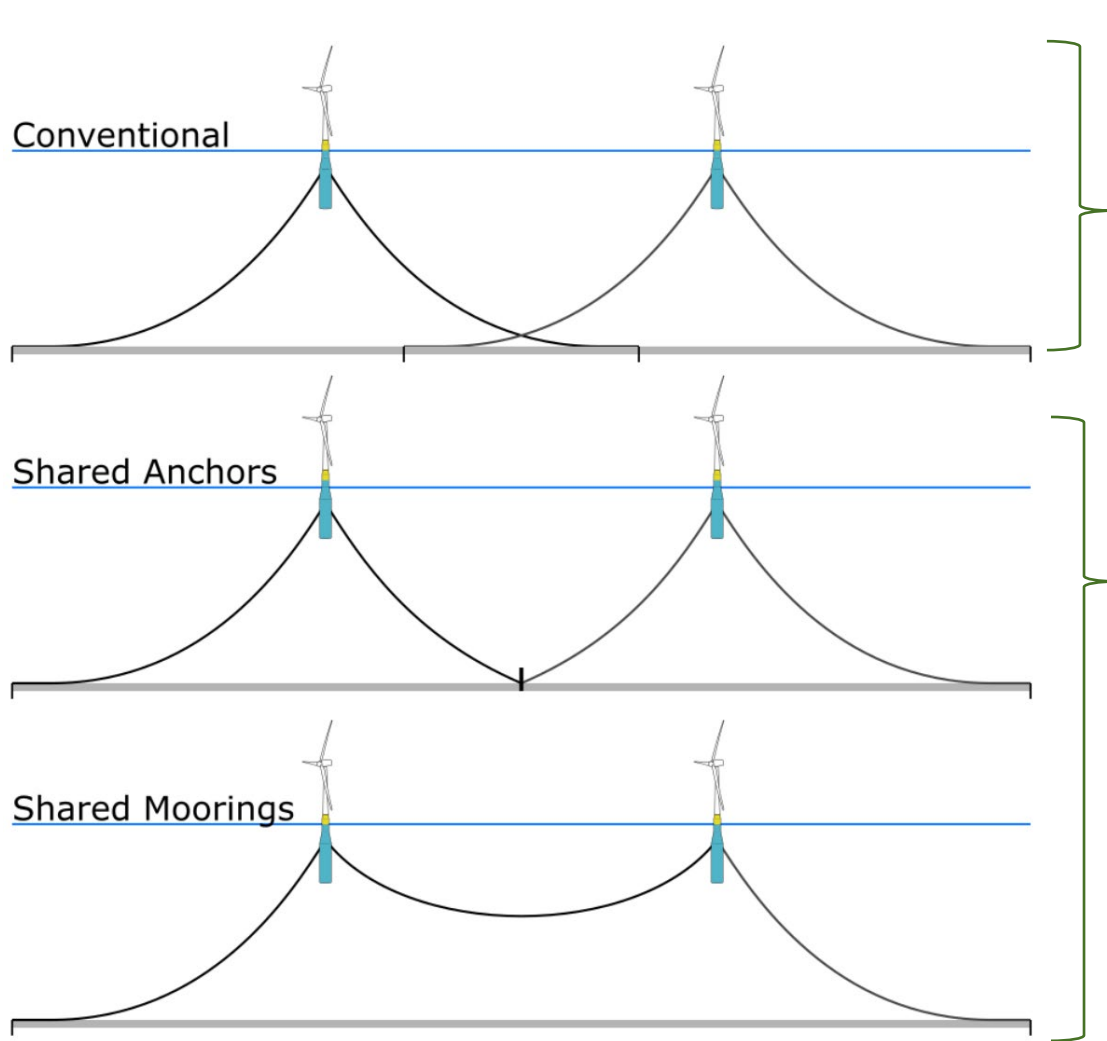


Challenges:

- Supply chain
- Water depth
- Depth variation
- Extreme events



The Concept of Shared Mooring Systems

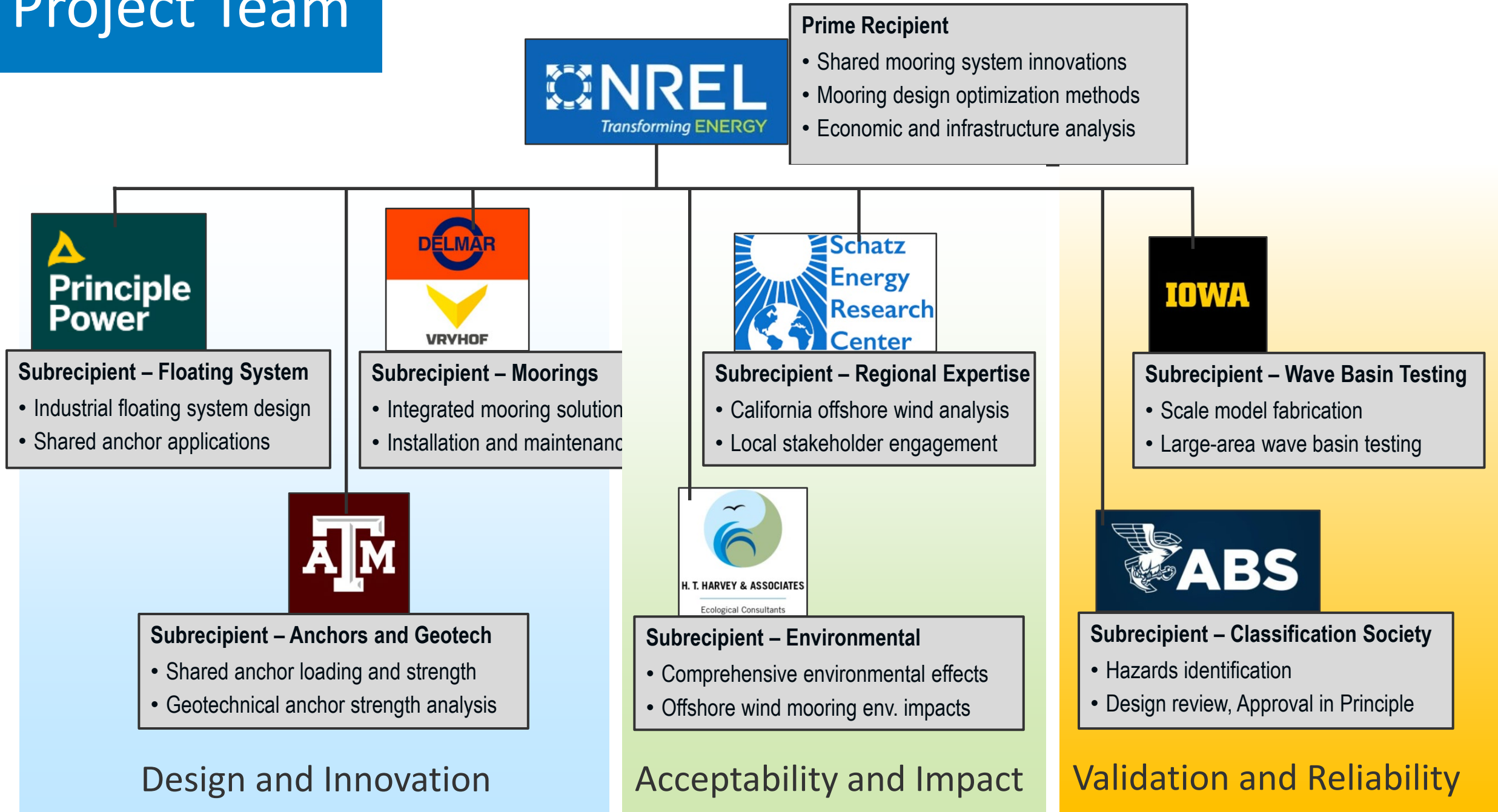


- Challenges: Complexity
- Benefits:
 - Reduce mooring component quantities
 - Reduce contact points with the seabed
 - Reduce sensitivity to failure

Our Project

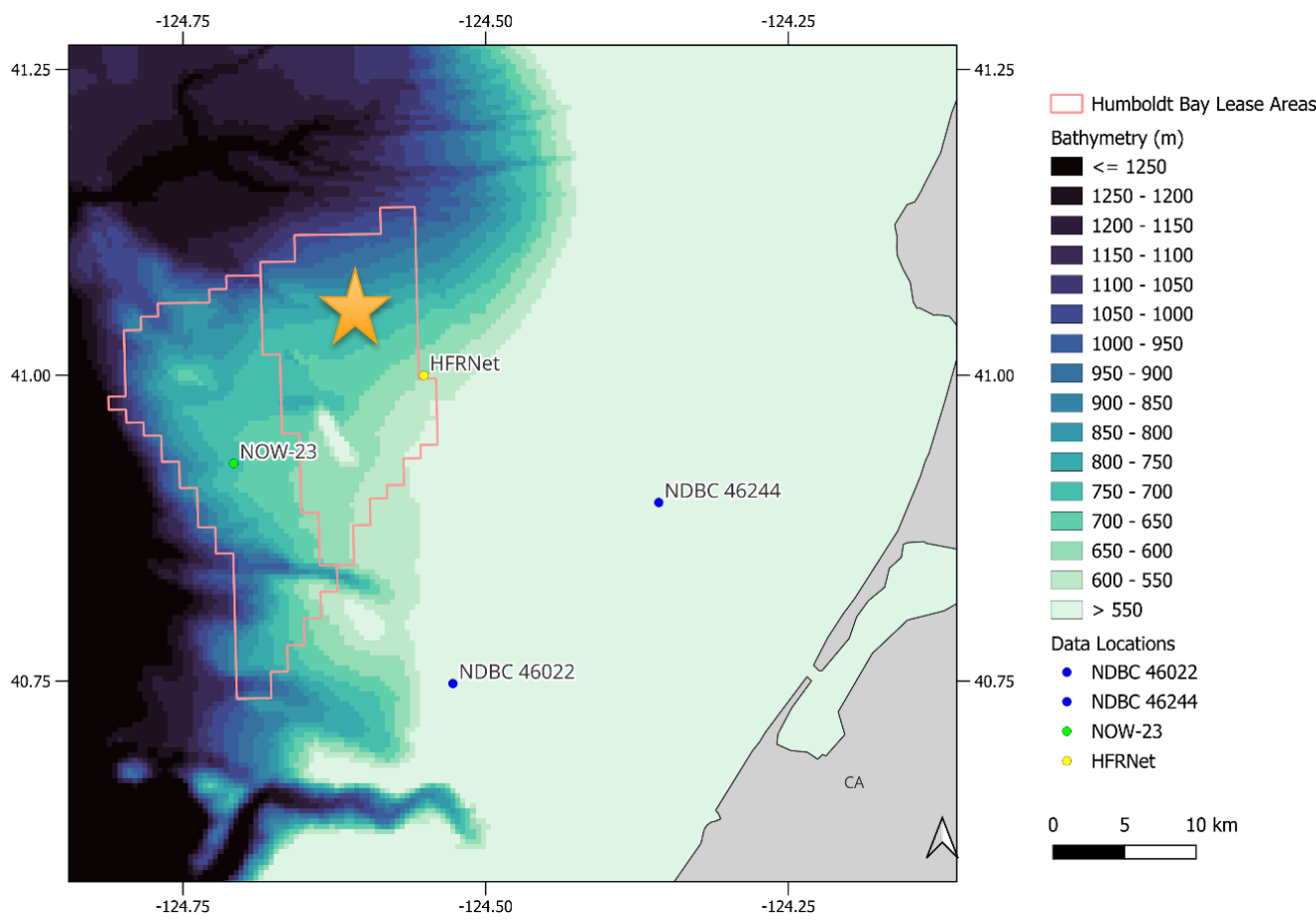
- Goal: develop comprehensive shared mooring system solutions that minimize the costs, failure risks, and environmental impacts of GW-scale floating wind farms in California site conditions
- Key elements of the approach:
 - State-of-the-art techniques for shared mooring lines and anchors
 - Installation and maintenance innovations that result in additional cost reductions and reliability improvements
 - Strategic use of shared mooring lines will make floating wind farms especially resilient to mooring system failures

Project Team



Project Design Basis

Location: Humboldt Bay lease area



Wind Turbine: 15-MW Platform: Semisubmersible (2 options)

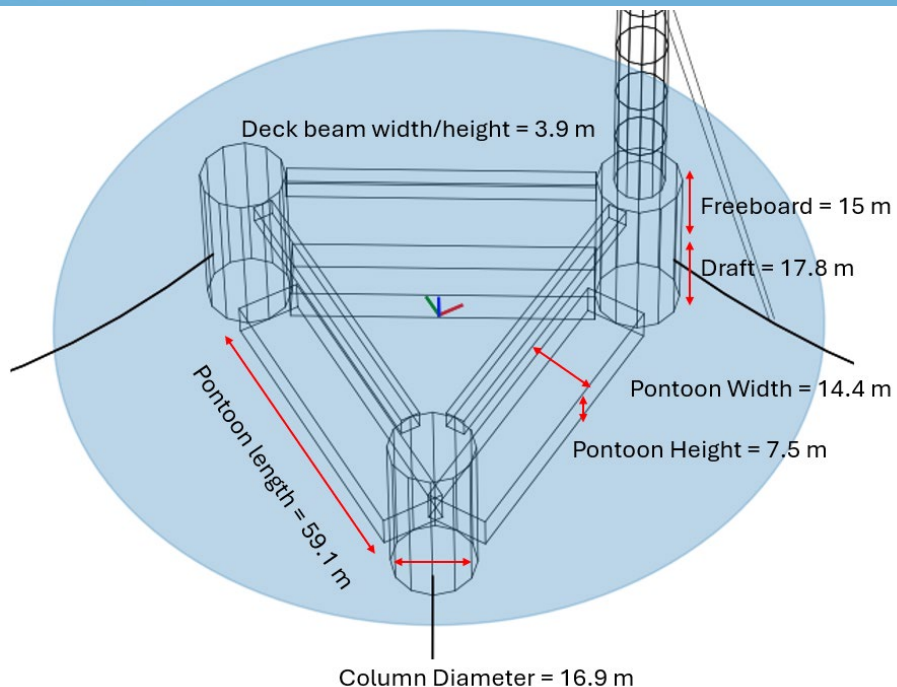


UMaine VoltturnUS-S

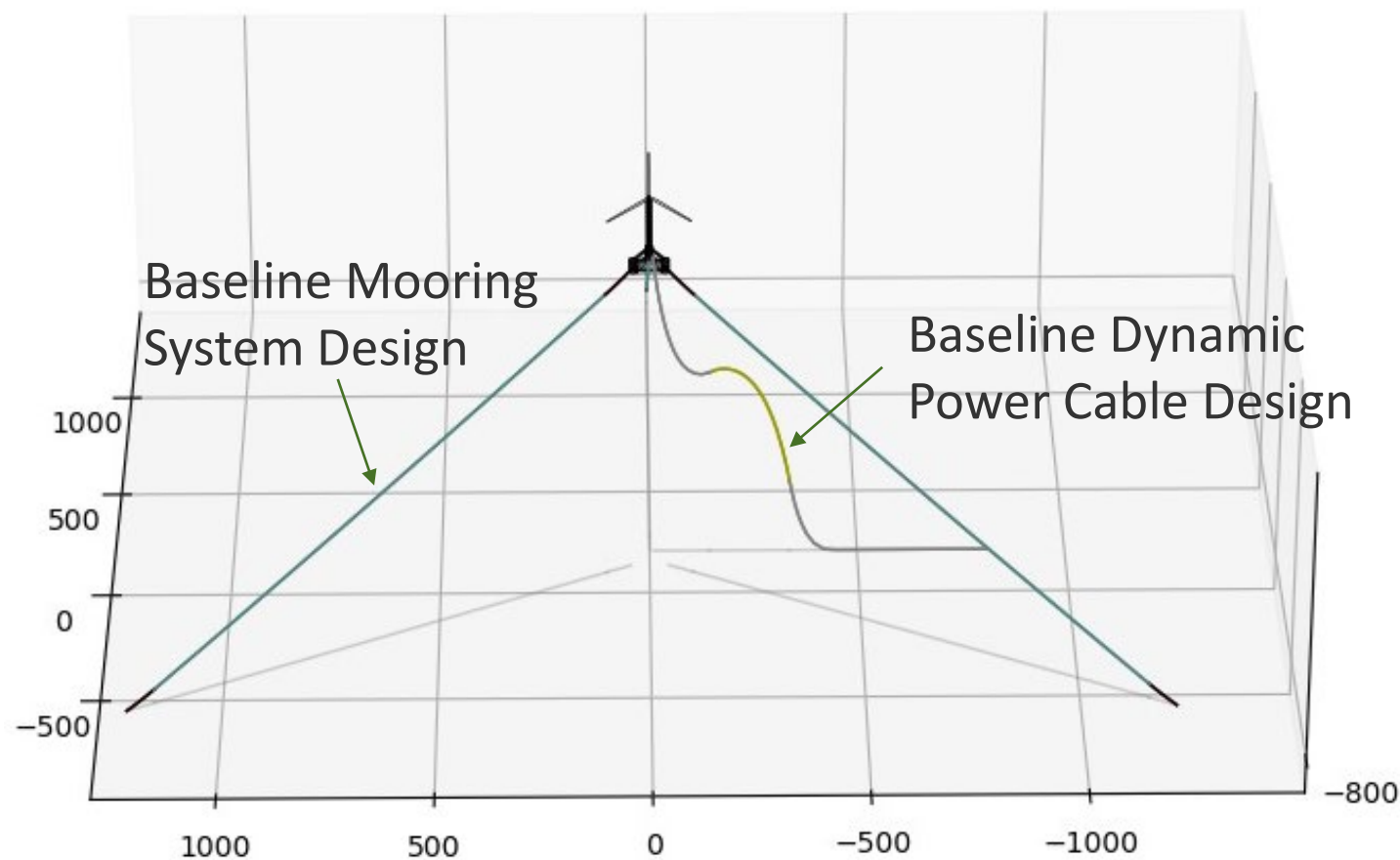


INO WindMoor

Recently Completed: Baseline Design



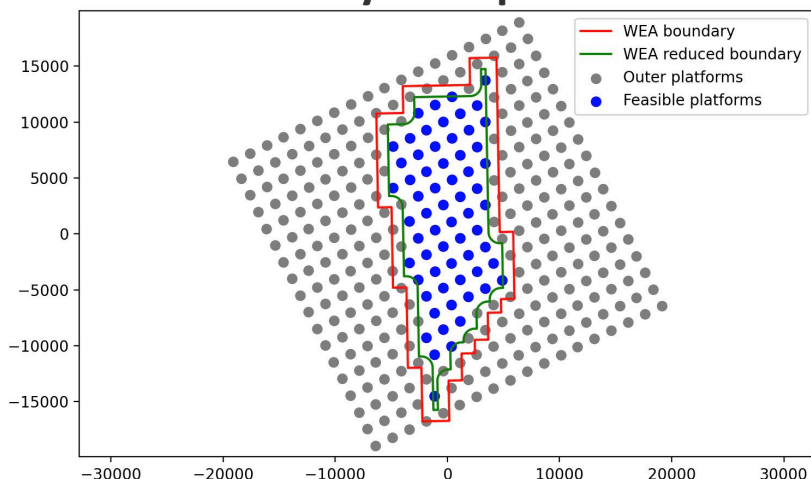
- Upscaled INO Windmoor platform for the IEA Wind 15-MW turbine
- Taut mooring system mainly using 200 mm polyester rope
- Lazy wave dynamic power cable



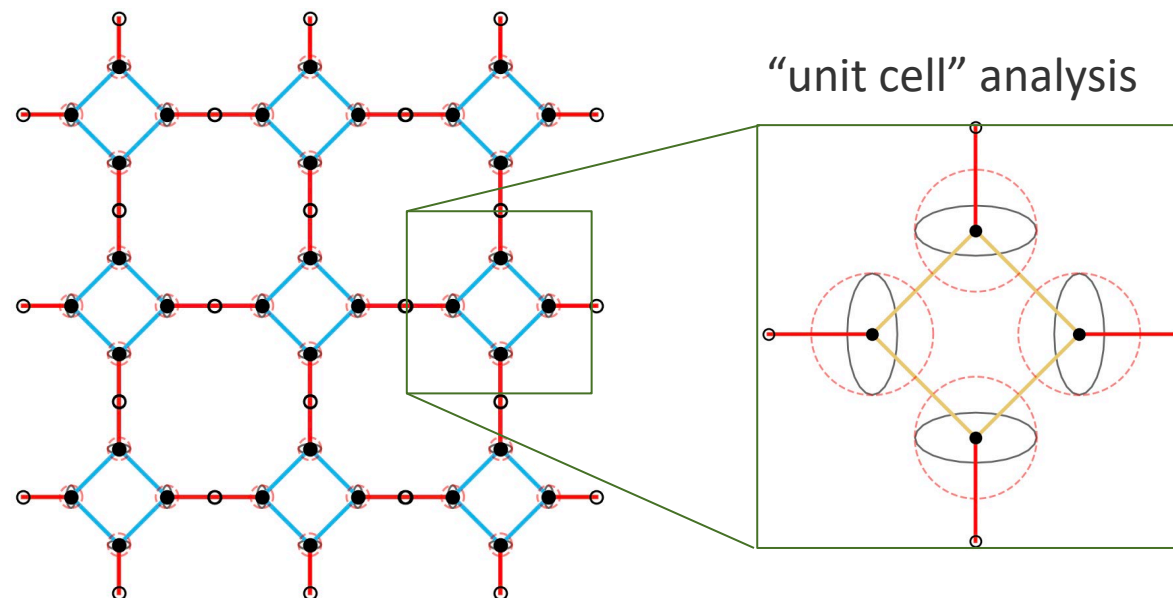
Baseline design OpenFAST input files are available on GitHub:
<https://github.com/FloatingArrayDesign/SharedMoorings/tree/main/IEA-15-240-RWT-INOSemiUpscaled>

Ongoing Work: Large-Scale Shared-Mooring Design

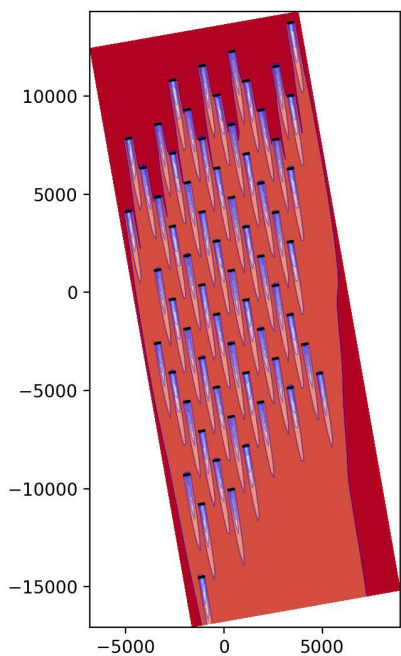
Turbine Layout Optimization



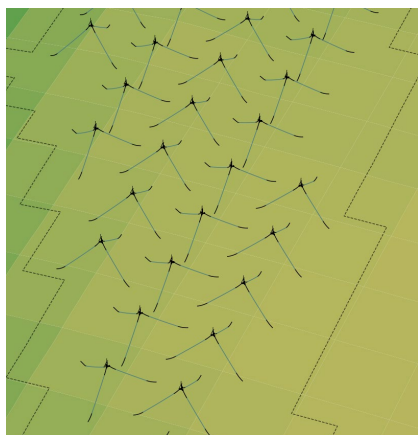
Methods for Modeling Large Shared Mooring Systems



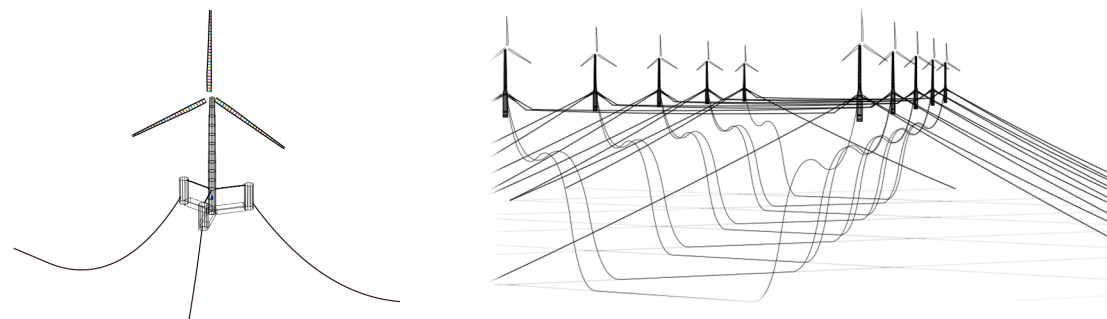
Wakes Analysis



Mooring System Arrangement/Fit



Ultimate Evaluation: Simulation of System Dynamic Response

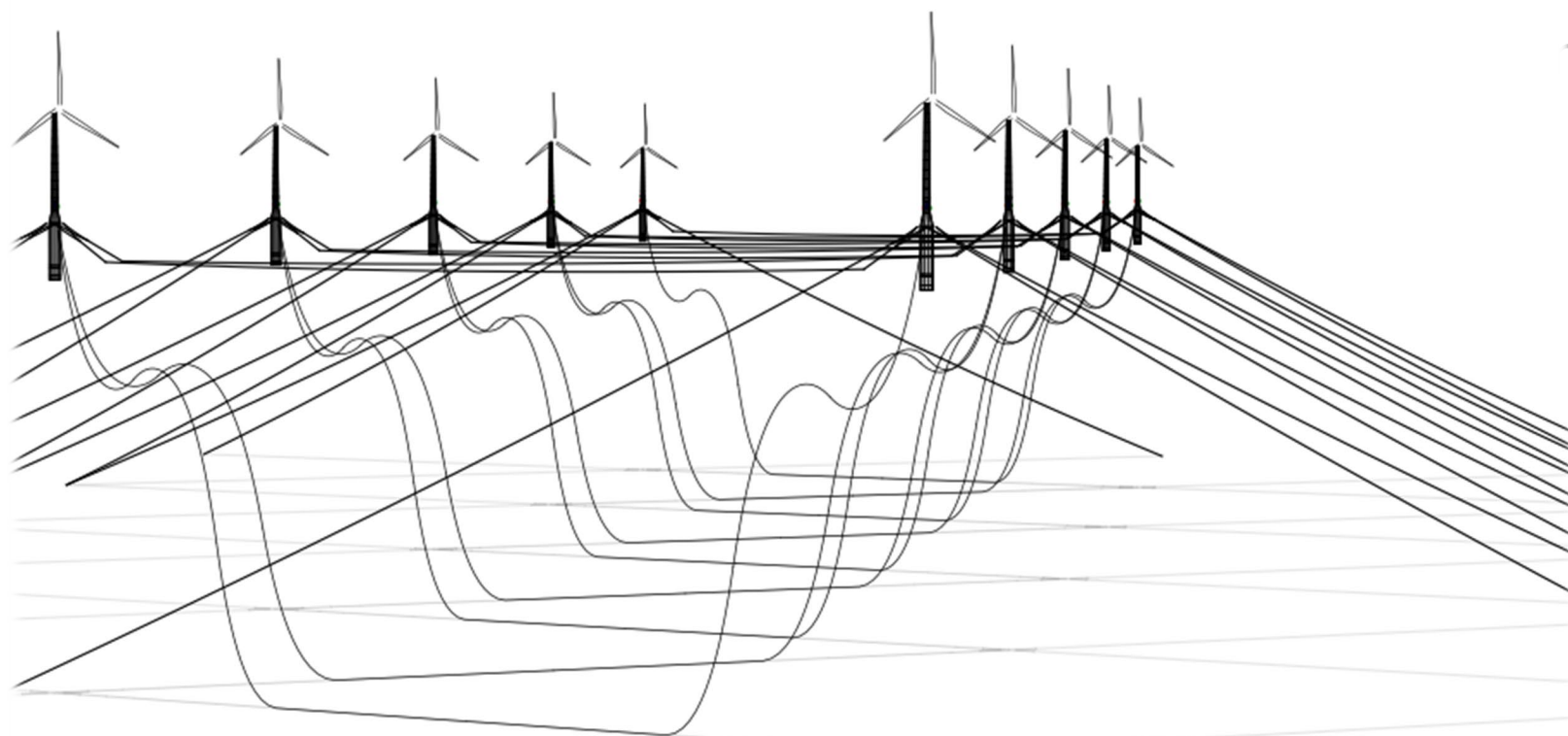


Expected Project Benefits

- Key findings to report on:
 - Shared mooring system innovations including installation and maintenance approaches
 - Assessment of array-level risks including extreme waves and earthquakes
 - Analysis of technical, reliability, economic, and environmental benefits/impacts compared to conventional mooring approaches
- Key outputs:
 - Baseline design definitions/files ✓
 - Installation and maintenance methods and assumptions
 - Design framework in open-source toolset
 - Final shared-mooring design definitions/files
 - Technical reports on design performance, cost, environmental impact

Thank You

Contact: matthew.hall@nrel.gov





Break

We will resume at 11:28am PT



Energize Innovation

1. <https://www.energizeinnovation.fund/projects/seabird-3d-distribution-and-relative-risk-california-offshore-wind-turbines>
2. <https://www.energizeinnovation.fund/projects/integrated-monitoring-cetacean-and-ocean-environmental-impacts-floating-offshore-wind>
3. <https://www.energizeinnovation.fund/projects/low-cost-environmentally-friendly-concrete-anchors-made-california>
4. <https://www.energizeinnovation.fund/projects/design-validation-and-certification-synthetic-mooring-line-system-15-mw-floating-wind>
5. <https://www.energizeinnovation.fund/projects/integrated-monitoring-approach-reduce-entanglement-hazards-floating-offshore-wind>
6. <https://www.energizeinnovation.fund/projects/advanced-anchoring-system-california-floating-offshore-wind>
7. <https://www.energizeinnovation.fund/projects/comprehensive-shared-mooring-solutions-minimize-cost-risk-and-footprint-gw-scale-floating>



Thank You!

<https://www.energy.ca.gov/event/webinar/2024-11/floating-offshore-wind-research-and-development-portfolio-showcase-webinar>

<https://www.energizeinnovation.fund/search?keywords=offshore+wind/>

<https://www.energy.ca.gov/funding-opportunities/solicitations>